## 1 K-NN and /decision Trees

$$\begin{array}{ll} \text{Distances, } d(x^{(i)}, x^{(q)}) = \\ \text{Manhattan} \quad \text{L1} \quad \sum_{k=1}^{K} |x_k^{(i)} - x_k^{(q)}| \\ \text{Euclidean} \quad \text{L2} \quad \sqrt{\sum_{k=1}^{K} (x_k^{(i)} - x_k^{(q)})^2} \\ \text{Chebyshev} \quad \text{L}\infty \quad \max_{k=1}^{K} |x_k^{(i)} - x_k^{(q)}| \end{array}$$

$$\text{Types} = \begin{array}{cc} \text{Inverse} & \frac{1}{d(x^{(i)}, x^{(q)})} \\ \text{Gaussian} & \frac{1}{\sqrt{2\pi}} \exp(-\frac{d(x^{(i)}, x^{(q)})^2}{2}) \end{array}$$

Entropy = 
$$H(X) = -\sum_{k=1}^{K} P(x_k) \log_2(P(x_k)) - \int_{k} f(x) \log_2(f(x))$$

$$\begin{split} \text{Information Gain} &= \text{IG}(\text{dataset}, \text{subsets}) \\ &= H(dataset) - \sum_{S \in \text{subsets}} \frac{|S|}{|\text{dataset}|H(S)} \\ &|\text{dataset}| = \sum_{S \in \text{subsets}} |S| \end{split}$$

#### **Neural Networks** 3

$$\begin{array}{lll} \text{Activation Functions:} & g(z) & g'(z) \\ \text{Sigmoid} & \frac{1}{1+e^{-x}} & g(z)(1-g(z)) \\ \text{Tanh} & \frac{e^x-e^{-x}}{e^x+e^{-x}} & 1-g(z)^2 \\ \text{ReLU} & 0 \text{ for } x \leq 0 & 0 \text{ for } x \leq 0 \\ x \text{ for } x>0 & 1 \text{ for } x>0 \\ \end{array}$$
 
$$\text{Softmax} & \frac{e^{Z_i}}{\sum_{t} e^{Z_k}} & \frac{\delta L}{\delta z} = \frac{1}{N}(\hat{y}-y) \end{array}$$

Back Propagation:  $\begin{array}{l} \frac{\delta \text{Loss}}{\delta W} = \frac{\delta \text{Loss}}{\delta W} \cdot \frac{\delta Z}{\delta W} \\ \frac{\delta \text{Loss}}{\delta b} = \frac{\delta \text{Loss}}{\delta Z} \cdot \frac{\delta Z}{\delta b} \\ \frac{\delta \text{Loss}}{\delta X} = \frac{\delta \text{Loss}}{\delta Z} \cdot \frac{\delta Z}{\delta X} \\ \frac{\delta \text{Loss}}{\delta X} = \frac{\delta \text{Loss}}{\delta Z} \cdot W^T \end{array}$  $\frac{\delta \text{Loss}}{\delta X} = \frac{\delta \text{Loss}}{\delta X} \cdot W^T$   $\frac{\delta \text{Loss}}{\delta W} = X^T \cdot \frac{\delta \text{Loss}}{\delta Z}$   $\frac{\delta \text{Loss}}{\delta b} = 1^T \cdot \frac{\delta \text{Loss}}{\delta Z}$   $\frac{\delta \text{Loss}}{\delta b} = \frac{\delta \text{Loss}}{\delta A} \circ g'(Z)$ where A = g(Z)

# Unsupervised Learning

### $\mathbf{2}$ **Evaluation** of Machine Learning Systems

Confusion Matrix

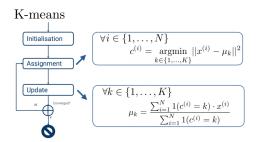
	Class 1 Predicted	Class 2 Predicted
Class 1 Actual	<b>TP</b> True Positive	FN False Negative
Class 2 Actual	FP False Positive	TN False Negative

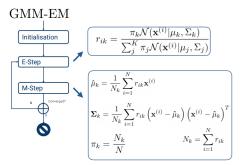
Accuracy = 
$$\frac{TP+TN}{TP+TN+FP+FN}$$
  
Precision =  $\frac{TP}{TP+FP}$   
Recall =  $\frac{TP}{TP+FP}$   
F-measure =  $F_1$  =  $2\frac{Precision*Recall}{Precision+Recall}$   
MSE =  $\frac{1}{N}\sum_{i=1}^{N}(Y_i - \hat{Y}_i)^2$   
Sample Error:  
 $error_s(h) = \frac{1}{N}\sum_{x \in S} \delta(f(x), h(x))$   
Confidence interval:  
 $error_s(h) \pm Z_N \sqrt{\frac{error_s(h)*(1-error_s(h))}{n}}$ 

$$Recall = \frac{TP}{TD+FN}$$

$$MSE = \frac{1}{N} \sum_{i=1}^{N} (Y_i - \hat{Y}_i)^2$$

$$error_s(h) \pm Z_N \sqrt{\frac{error_s(h)*(1-error_s(h))}{n}}$$





## 5 **Evolutionary Algorithms**

Fusce mauris. Vestibulum luctus nibh at lectus. Sed bibendum, nulla a faucibus semper, leo velit ultricies tellus, ac venenatis arcu wisi vel nisl. Vestibulum diam. Aliquam pellentesque, augue quis sagittis posuere, turpis lacus congue quam, in hendrerit risus eros eget felis. Maecenas eget erat in sapien mattis porttitor. Vestibulum porttitor. Nulla facilisi. Sed a turpis eu lacus commodo facilisis. Morbi fringilla, wisi in dignissim interdum, justo lectus sagittis dui, et vehicula libero dui cursus dui. Mauris tempor ligula sed lacus. Duis cursus enim ut augue. Cras ac magna. Cras nulla. Nulla egestas. Curabitur a leo. Quisque egestas wisi eget nunc. Nam feugiat lacus vel est. Curabitur consectetuer.