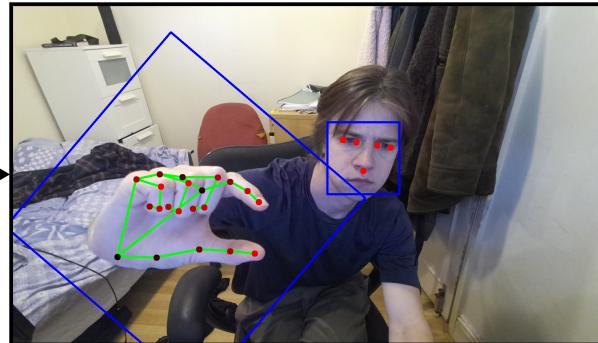


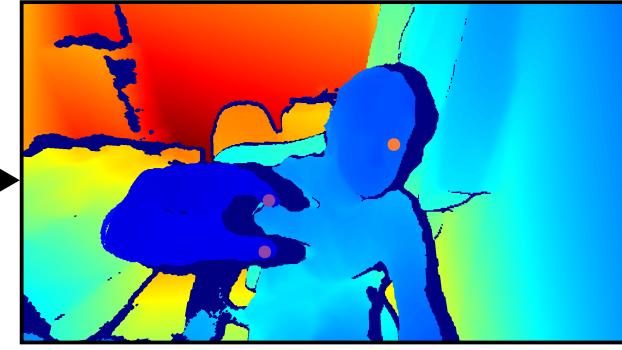
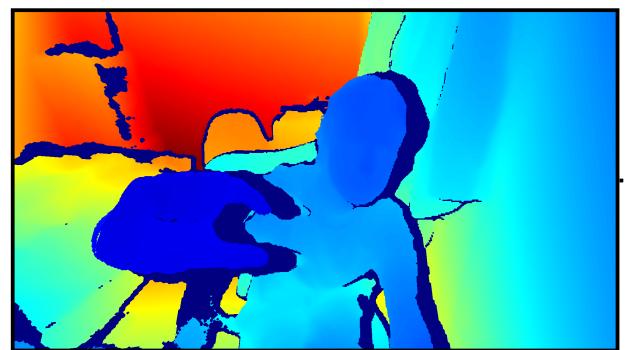
Capture



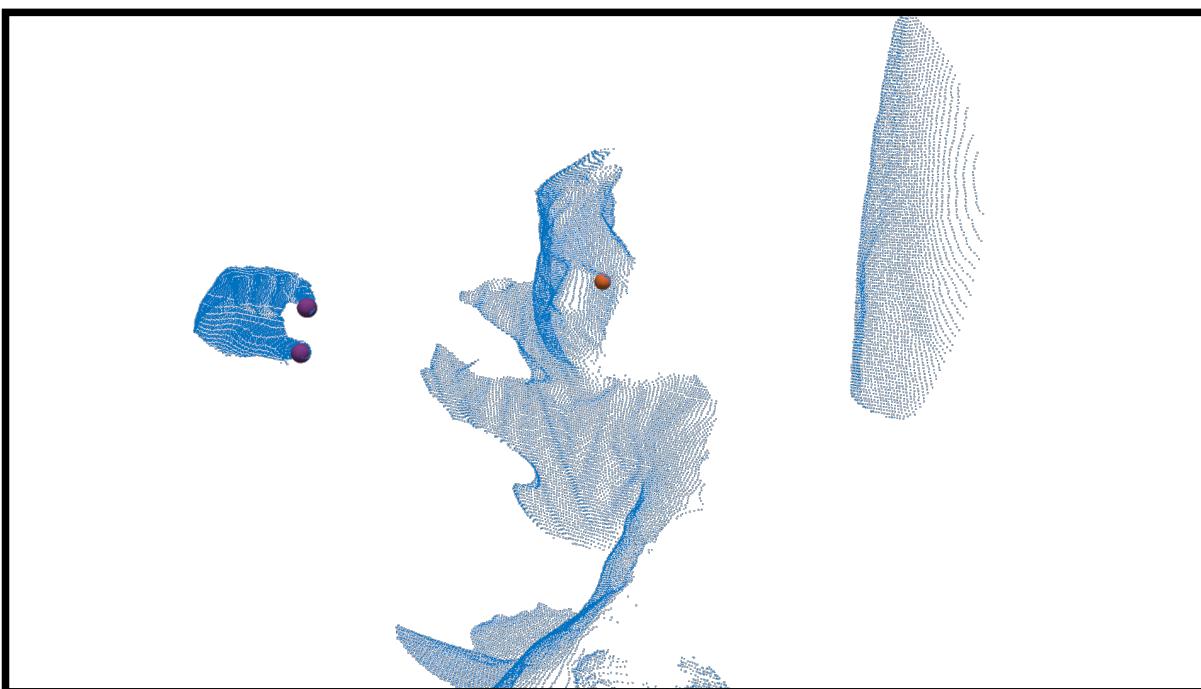
Run Tracking



Extract Key
points



Tracking Frame



Combine &
convert to 3D