



# Expectation Maximization

## Chapter 5

### *Gaussian Mixture Models II*

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# Supervised versus Unsupervised

- Supervised Learning:
  - Chapter 4
  - Class label comes with observations
- Unsupervised Learning:
  - Chapter 5
  - Class label inferred from observations

# Expectation Maximization

- Expectation:
  - Chapter 5
  - Current estimate of parameters
  - Estimate class labels
- Maximization (MLE):
  - Chapter 4
  - Current estimate of class labels
  - Estimate parameters
- Alternate E and M step till convergence

# Introduction

- Single Gaussian pdf
  - Useful analytic properties
  - Not always practical
  - Multi-modal data set
  - Mixture of  $k$  Gaussians

# A Gaussian Mixture

$$p(\mathbf{x}|\theta) = \sum_{j=1}^k \pi_j \mathcal{N}(\mathbf{x}|\mathbf{u}_j, \Sigma_j)$$

- $\mathcal{N}$  – Gaussian distribution
- $\mathbf{u}, \Sigma$  – Mean and Covariance
- $\pi$  – Mixture coefficients (class probabilities)
- $\sum \pi = 1$
- $\theta$  – Mixture Parameters ( $\mathbf{u}, \Sigma, \pi$ )

# Problem

- Estimate  $\theta$  from  $\mathbf{x}$ 
  - Contribution to mixture components unknown
- Similar to  $k$ -means
  - Cluster label unknown

# A General Mixture Model

$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z}) \leftarrow \text{Marginalization}$$

$$= \sum_{\mathbf{z}} p(\mathbf{x}|\mathbf{z}) P(\mathbf{z}) \leftarrow \text{Chain-Rule}$$

Enumeration

$$= \sum_{j=1}^k p(\mathbf{x}|z_j = 1) P(z_j = 1)$$

$\mathcal{N}$

$\pi_j$

Gaussian Ass.

$$\mathbf{z} = [z_1, \dots, z_n]^T \text{ where } z_j \in \{0, 1\} \text{ and } \sum_j z_j = 1$$

Latent-variable

# Mixture Component Prob $\gamma_j$

Bayes-law

$$\begin{aligned}\gamma(z_j) &= P(z_j = 1|\mathbf{x}) \\ &= \frac{P(z_j = 1)p(\mathbf{x}|z_j = 1)}{\sum_{i=1}^k P(z_i = 1)p(\mathbf{x}|z_i = 1)} \\ &= \frac{\pi_j \mathcal{N}(\mathbf{x}|\mathbf{u}_j, \Sigma_j)}{\sum_{i=1}^k \pi_i \mathcal{N}(\mathbf{x}|\mathbf{u}_i, \Sigma_i)}\end{aligned}$$

Gaussian Ass.



Matrix  $N \times d$

# Log-likelihood

Chain-Rule

$$p(\mathbf{X}, \boldsymbol{\pi}, \mathbf{u}, \Sigma) = p(\mathbf{X} | \boldsymbol{\pi}, \mathbf{u}, \Sigma) p(\boldsymbol{\pi}, \mathbf{u}, \Sigma)$$

Independence

$$= p(\boldsymbol{\pi}, \mathbf{u}, \Sigma) \prod_{n=1}^N p(\mathbf{x}_n | \boldsymbol{\pi}, \mathbf{u}, \Sigma)$$

Substitution

$$= p(\boldsymbol{\pi}, \mathbf{u}, \Sigma) \prod_{n=1}^N \sum_{i=1}^k \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i, \Sigma_i)$$

Discard

$$\ln p(\mathbf{X} | \boldsymbol{\pi}, \mathbf{u}, \Sigma) = \sum_{n=1}^N \ln \left\{ \sum_{i=1}^k \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i, \Sigma_i) \right\}$$

# ML Estimation - mean

$$0 = - \sum_{n=1}^N \frac{\pi_j \mathcal{N}(\mathbf{x}_n | \mathbf{u}_j, \Sigma_j)}{\sum_i \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i, \Sigma_i)} \Sigma_j^{-1} (\mathbf{x}_n - \mathbf{u}_j)$$
$$= - \sum_{n=1}^N \gamma(z_{nj}) \Sigma_j^{-1} (\mathbf{x}_n - \mathbf{u}_j)$$

Chain Rule

$$\mathbf{u}_j = \frac{1}{N_j} \sum_{n=1}^N \gamma(z_{nj}) \mathbf{x}_n$$

$$\frac{d \ln x}{dx} = x^{-1}; \quad \frac{de^{x^2}}{dx} = 2xe^{x^2}$$

$$N_j = \sum_{n=1}^N \gamma(z_{nj})$$

# ML Estimation - covariance

$$\Sigma_j = \frac{1}{N_j} = \sum_{n=1}^N \gamma(z_{nj}) (\mathbf{x}_n - \mathbf{u}_j)(\mathbf{x}_n - \mathbf{u}_j)^T$$

# ML Estimation – mixture coeff

Lagrange

$$\sum \ln \left\{ \sum_{i=1}^k \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i, \Sigma_i) \right\} + \lambda \left( \sum_{i=1}^k \pi_i - 1 \right)$$

max

$$0 = - \sum_{n=1}^N \frac{\mathcal{N}(\mathbf{x}_n | \mathbf{u}_j, \Sigma_j)}{\sum_i \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i, \Sigma_i)} + \lambda \quad \sum_{i=1}^k \pi_i = 1$$

$\times \pi_j$  and  $\sum_j$

$$\lambda = -N$$

$\times \pi_j$  only

+substitution of  $\lambda$

$$0 = \sum_{n=1}^N \gamma(z_{nj}) - \pi_j N$$

$$\pi_j = \frac{N_j}{N}$$

# EM Algorithm for GMMs

- 1) Initialize parameters  $\pi, \mathbf{u}, \Sigma$  ( $k$ -means).
- 2) **E-step**: Estimate responsibilities  $\lambda$
- 3) **M-step**: Re-estimate parameters  $\pi, \mathbf{u}, \Sigma$
- 4) Check for convergence of parameters or log-likelihood (increase monotonically)
- 5) Iterate from (2) until convergence

# E-step

$$\gamma(z_{nj}) = \frac{\pi_j \mathcal{N}(\mathbf{x}_n | \mathbf{u}_j \mathbf{\Sigma}_j)}{\sum_{i=1}^k \pi_i \mathcal{N}(\mathbf{x}_n | \mathbf{u}_i \mathbf{\Sigma}_i)}$$

# M-step

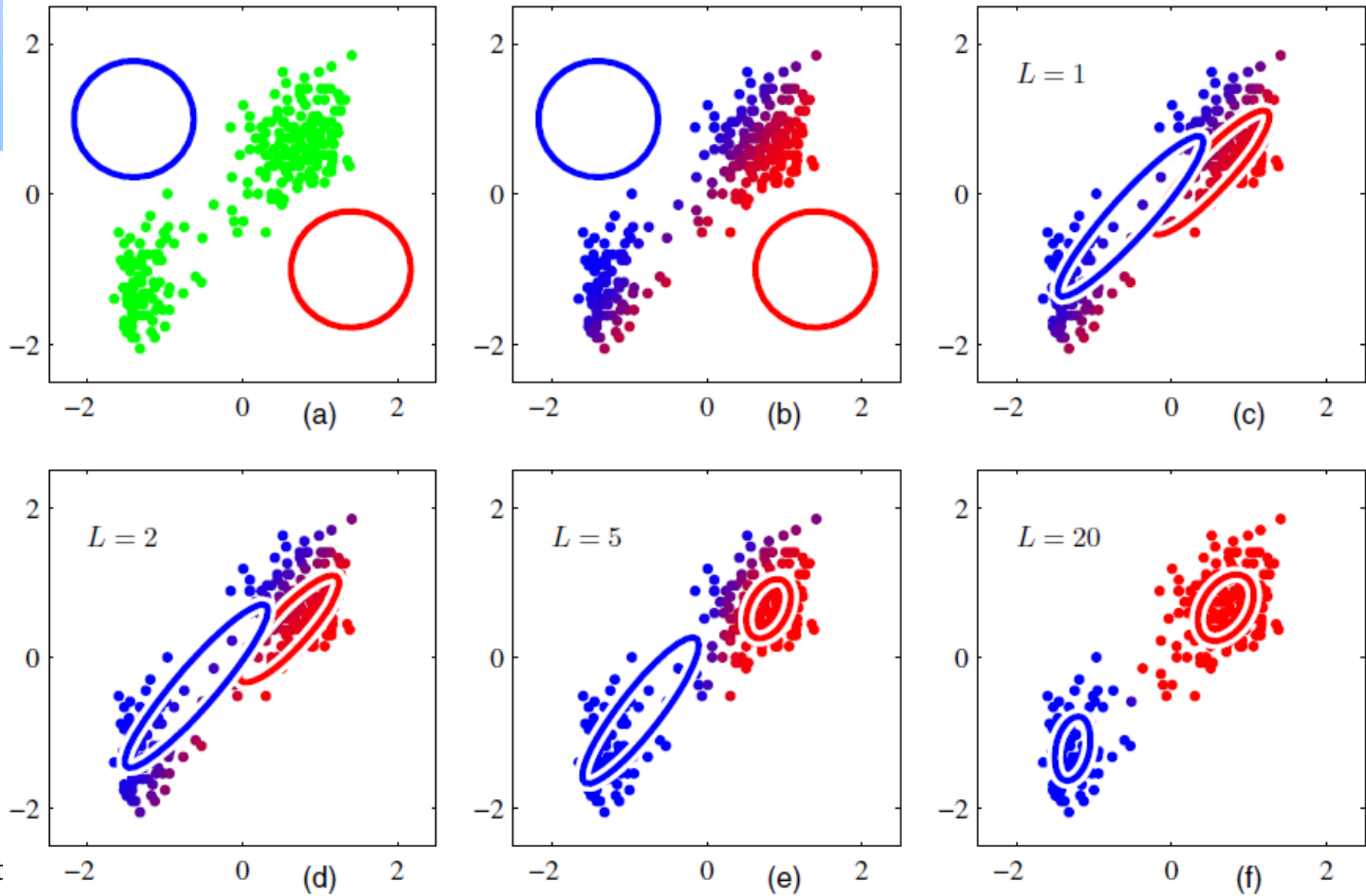
$$\mathbf{u}_j = \frac{1}{N_j} \sum_{n=1}^N \gamma(z_{nj}) \mathbf{x}_n$$

$$\mathbf{\Sigma}_j = \frac{1}{N_j} \sum_{n=1}^N \gamma(z_{nj}) (\mathbf{x}_n - \mathbf{u}_j)(\mathbf{x}_n - \mathbf{u}_j)^T$$

$$\pi_j = \frac{N_j}{N}$$

$$N_j = \sum_{n=1}^N \gamma(z_{nj})$$

# EM for GMMs





# Example

- (a) – initialization
- (b) – 1st E-step
- (c) – 1st M-step
- (d) to (f) 2nd, 5th and 20th EM step