### **Robot Vision**

- Automation and control -

Project Report Group 832

Aalborg University Electronics and IT





Electronics and IT Aalborg University http://www.aau.dk

STUDENT REPORT

Title:

Lego Brickszzz

Theme:

Robot Vision

**Project Period:** 

Spring Semester 2016

**Project Group:** 

Group: 832

Participant(s):

Alvaro Perez Ortega Kenny Lund Lafon Kelvin Kjærvik Pagels Robert-Octavian Popescu

Orlando Vaz

**Supervisor(s):** 

Anders La Cour Harbo

Copies: 1

Page Numbers: 20

**Date of Completion:** 

April 2, 2016

**Abstract:** 

Here is the abstract

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Elektronik og IT Aalborg Universitet http://www.aau.dk

#### **AALBORG UNIVERSITET**

STUDENTERRAPPORT

Titel:	Abstract
LEgo Brickszzz	

Her er resuméet
Tema:

**Projektperiode:** Spring 2016

Robot Vision

**Projektgruppe:** Group: 832

Deltager(e):

Alvaro Perez Ortega Kenny Lund Lafon Kelvin Kjærvik Pagels Robert-Octavian Popescu Orlando Vaz

**Vejleder(e):**No supervisors

Oplagstal: 1

Sidetal: 20

**Afleveringsdato:** 2. april 2016

Rapportens indhold er frit tilgængeligt, men offentliggørelse (med kildeangivelse) må kun ske efter aftale med forfatterne.

#### **Contents**

Pr	eface		хi
1	Intr	oduction	1
2	Scer	nario	3
	2.1	Communication	3
	2.2	Rescue missions	3
		2.2.1 What do they do today?	3
		2.2.2 Compare the rescue missions	3
	2.3	Pipeline survey	3
3	Har	dware setup	5
	3.1	Drone (eBee)	5
	3.2	Basestation	6
		3.2.1 Laptop	6
		3.2.2 Antennas	6
		3.2.3 Gimbals (Camera)	6
4	Tele	communication	7
	4.1	Telemetry	7
	4.2	MavLink (protocal)	7
	4.3	Link Budget	7
5	Veri	fication	9
6	Sim	ulation	11
	6.1	Drone model	11
	6.2	Controller	11
	6.3		11
	6.4	1	11
7	Disc	russion	13

viii	Contents
111	Contents

8	Conclusion	15
Bi	bliography	17
A	Appendix LaTeX Tips	19
	A.1 Example 1	19
	A.2 How Does Sections, Subsections, and Subsections Look?	19
	A.2.1 This is a Subsection	19
	A.3 Example 2	20

# **Todo list**

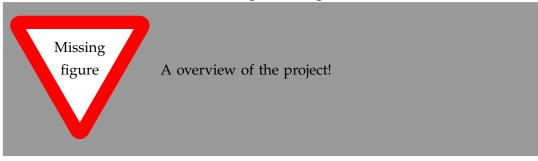
Fi٤	gure: A overview of the project!	1
	Is it possible to add a subsubparagraph?	20
	I think that a summary of this exciting chapter should be added	20
	I think this word is mispelled	20
Fig	gure: We need a figure right here!	20

### **Preface**

Here is the preface. You should put your signatures at the end of the preface.		
Aalborg University, April 2,		
Alvaro Perez Ortega	Kelvin Kjærvik Pagels	
<aperez15@student.aau.dk></aperez15@student.aau.dk>	<pre><kpagel15@student.aau.dk></kpagel15@student.aau.dk></pre>	
Kenny Lund Lafon	Orlando Vaz	
<klafon15@student.aau.dk></klafon15@student.aau.dk>	<obasto16@student.aau.dk></obasto16@student.aau.dk>	
Robert-Octavian	Popescu	
<rpopes15@student< td=""><td>.aau.dk&gt;</td></rpopes15@student<>	.aau.dk>	

#### Introduction

Here is the introduction. The next chapter is chapter 2.



#### Scenario

- 2.1 Communication
- 2.2 Rescue missions
- 2.2.1 What do they do today?
- 2.2.2 Compare the rescue missions

#### 2.3 Pipeline survey

The pipeline survey could be to transport oil from a factory to another facility. To ensure that there is no thiefs that want to steal the oil, they have to hire people to patrol. Instead they could use a drone to search the area. Potential danger

Figure 2.1: Pipeline survey

- Terrorist
- Thiefs

## Hardware setup

Our hardware setup.

#### 3.1 Drone (eBee)



**Figure 3.1:** The professional mapping drone *eBee* (www.sensefly.com). Fully autonomous drone to capture high-resolution aerial photos that can transform into accurate 2D orthomosaics & 3D models.

- 3.2 Basestation
- **3.2.1** Laptop
- 3.2.2 Antennas
- 3.2.3 Gimbals (Camera)

#### **Telecommunication**

Our telecommunication.

- 4.1 Telemetry
- 4.2 MavLink (protocal)
- 4.3 Link Budget

### Verification

Our verification.

#### **Simulation**

Our simulations.

- 6.1 Drone model
- 6.2 Controller
- 6.3 V-Rep
- 6.4 Drone in real life (real data)

#### Discussion

Our discussion.

### Conclusion

Our conclusion.

## **Bibliography**

- [1] Lars Madsen. *Introduktion til LaTeX*. http://www.imf.au.dk/system/latex/bog/. 2010.
- [2] Frank Mittelbach. The LATEX companion. 2. ed. Addison-Wesley, 2005.
- [3] Tobias Oetiker. The Not So Short A Introduction to LaTeX2e. http://tobi.oetiker.ch/lshort/lshort.pdf. 2010.

#### Appendix A

#### Appendix LaTeX Tips

#### A.1 Example 1

You can also have examples in your document such as in example A.1.

#### Example A.1 (An Example of an Example)

Here is an example with some math

$$0 = \exp(i\pi) + 1. \tag{A.1}$$

You can adjust the colour and the line width in the macros.tex file.

#### A.2 How Does Sections, Subsections, and Subsections Look?

Well, like this

#### A.2.1 This is a Subsection

and this

#### This is a Subsubsection

and this.

A Paragraph You can also use paragraph titles which look like this.

**A Subparagraph** Moreover, you can also use subparagraph titles which look like this. They have a small indentation as opposed to the paragraph titles.

I think that a summary of this exciting chapter should be added.

Is it possible to ac subsubparagraph?

#### A.3 Example 2

I think this word is mispelled

Here is chapter 2. If you want to leearn more about  $\LaTeX$  2 $\varepsilon$ , have a look at [1], [3] and [2].

