

## Course 4

### Generated subspace, linear maps



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# Chapter 2. Vector Spaces

- 1 Basic properties
- 2 Subspaces
- 3 Generated subspace
- 4 Linear maps

# Application: image crossfade

Following [Klein], we describe a way to achieve an image crossfade effect.



# Intersection of subspaces

For a vector space  $V$  over  $K$ , we denote by  $S(V)$  the set of all subspaces of  $V$ . Sometimes, this set is denoted by  $S_K(V)$  if we like to emphasize the field  $K$ .

## Theorem

*Let  $V$  be a vector space over  $K$  and let  $(S_i)_{i \in I}$  be a family of subspaces of  $V$ . Then  $\bigcap_{i \in I} S_i \in S(V)$ .*

*Proof.* [...]

In general, the union of two subspaces of a vector space is not a subspace. For instance,  $S = \{(x, 0) \mid x \in \mathbb{R}\}$  and  $T = \{(0, y) \mid y \in \mathbb{R}\}$  are subspaces of the canonical real vector space  $\mathbb{R}^2$ , but  $S \cup T$  is not a subspace of  $\mathbb{R}^2$ . Indeed, for instance, we have  $(1, 0), (0, 1) \in S \cup T$ , but  $(1, 0) + (0, 1) = (1, 1) \notin S \cup T$ .

Now we are interested in how to “complete” a given subset of a vector space to a subspace in a minimal way.

## Definition

Let  $V$  be a vector space and let  $X \subseteq V$ . Then we denote

$$\langle X \rangle = \bigcap \{S \leq V \mid X \subseteq S\}$$

and we call it the *subspace generated by  $X$*  or the *subspace spanned by  $X$* . Here  $X$  is called the *generating set* of  $\langle X \rangle$ . If  $X = \{v_1, \dots, v_n\}$ , we denote  $\langle v_1, \dots, v_n \rangle = \langle \{v_1, \dots, v_n\} \rangle$ .

- (1)  $\langle X \rangle$  is the “smallest” (with respect to inclusion) subspace of  $V$  containing  $X$ .
- (2)  $\langle \emptyset \rangle = \{0\}$ .
- (3) If  $S \leq V$ , then  $\langle S \rangle = S$ .

## Definition

A vector space  $V$  over  $K$  is called *finitely generated* if  $\exists v_1, \dots, v_n \in V$  ( $n \in \mathbb{N}$ ) such that

$$V = \langle v_1, \dots, v_n \rangle.$$

Then the set  $\{v_1, \dots, v_n\}$  is called a *system of generators* for  $V$ .

## Definition

Let  $V$  be a vector space over  $K$  and  $v_1, \dots, v_n \in V$  ( $n \in \mathbb{N}$ ). A finite sum of the form

$$k_1 v_1 + \dots + k_n v_n,$$

where  $k_i \in K$  ( $i = 1, \dots, n$ ), is called a (finite) *linear combination* of the vectors  $v_1, \dots, v_n$ .

# Characterization of the generated subspace

## Theorem

*Let  $V$  be a vector space over  $K$  and let  $\emptyset \neq X \subseteq V$ . Then*

$$\langle X \rangle = \{k_1 v_1 + \cdots + k_n v_n \mid k_i \in K, v_i \in X, i = 1, \dots, n, n \in \mathbb{N}^*\},$$

*that is, the set of all finite linear combinations of vectors of  $X$ .*

*Proof.* We prove the result in 3 steps, by showing that

$$L = \{k_1 v_1 + \cdots + k_n v_n \mid k_i \in K, v_i \in X, i = 1, \dots, n, n \in \mathbb{N}^*\}$$

is the smallest subspace of  $V$  containing  $X$  [...].

## Corollary

*Let  $V$  be a vector space over  $K$  and let  $x_1, \dots, x_n \in V$ . Then*

$$\langle x_1, \dots, x_n \rangle = \{k_1 x_1 + \cdots + k_n x_n \mid k_i \in K, x_i \in X, i = 1, \dots, n\}.$$

(a) Consider the canonical real vector space  $\mathbb{R}^3$ . Then

$$\begin{aligned} & \langle (1, 0, 0), (0, 1, 0), (0, 0, 1) \rangle \\ &= \{k_1(1, 0, 0) + k_2(0, 1, 0) + k_3(0, 0, 1) \mid k_1, k_2, k_3 \in \mathbb{R}\} \\ &= \{(k_1, 0, 0) + (0, k_2, 0) + (0, 0, k_3) \mid k_1, k_2, k_3 \in \mathbb{R}\} \\ &= \{(k_1, k_2, k_3) \mid k_1, k_2, k_3 \in \mathbb{R}\} = \mathbb{R}^3. \end{aligned}$$

Hence  $\mathbb{R}^3$  is generated by the three vectors  $(1, 0, 0)$ ,  $(0, 1, 0)$  and  $(0, 0, 1)$ , and thus it is finitely generated.

(b) Consider the canonical vector space  $\mathbb{Z}_2^3$  over  $\mathbb{Z}_2$ . Similarly as above, we have:

$$\langle (\hat{1}, \hat{0}, \hat{0}), (\hat{0}, \hat{1}, \hat{0}) \rangle = \{(k_1, k_2, \hat{0}) \mid k_1, k_2 \in \mathbb{Z}_2\} \neq \mathbb{Z}_2^3.$$



## Examples II

Hence  $\mathbb{Z}_2^3$  is not generated by the two vectors  $(\hat{1}, \hat{0}, \hat{0})$  and  $(\hat{0}, \hat{1}, \hat{0})$ . But it is generated by  $(\hat{1}, \hat{0}, \hat{0})$ ,  $(\hat{0}, \hat{1}, \hat{0})$  and  $(\hat{0}, \hat{0}, \hat{1})$ , hence it is finitely generated.

(c) Consider the subspace

$$S = \{(x, y, z) \in \mathbb{R}^3 \mid x - y - z = 0\}$$

of the canonical real vector space  $\mathbb{R}^3$ . Let us write it as a generated subspace. Expressing  $x = y + z$ , we have:

$$\begin{aligned} S &= \{(y + z, y, z) \mid y, z \in \mathbb{R}\} = \{(y, y, 0) + (z, 0, z) \mid y, z \in \mathbb{R}\} \\ &= \{y(1, 1, 0) + z(1, 0, 1) \mid y, z \in \mathbb{R}\} = \langle (1, 1, 0), (1, 0, 1) \rangle. \end{aligned}$$

Alternatively, one may express  $y$  or  $z$  by using the other two components and get other writings of  $S$  as a generated subspace, namely  $S = \langle (1, 1, 0), (0, -1, 1) \rangle = \langle (1, 0, 1), (0, 1, -1) \rangle$ . We see that  $S$  is finitely generated.

# Sum of subspaces

In what follows we shall be interested in “decomposing” a vector space into subspaces.

## Definition

Let  $V$  be a vector space over  $K$  and let  $S, T \leq V$ .

We define the *sum* of the subspaces  $S$  and  $T$  as the set

$$S + T = \{s + t \mid s \in S, t \in T\}.$$

## Theorem

*Let  $V$  be a vector space over  $K$  and  $S, T \leq V$ . Then  $S + T = \langle S \cup T \rangle$ , hence  $S + T \leq V$ .*

*Proof.* We prove the equality by double inclusion [...].

# Direct sum of subspaces

## Definition

Let  $V$  be a vector space over  $K$  and let  $S, T \leq V$ .

If  $S \cap T = \{0\}$ , then  $S + T$  is denoted by  $S \oplus T$  and is called the *direct sum* of the subspaces  $S$  and  $T$ .

## Theorem

Let  $V$  be a vector space over  $K$  and let  $S, T \leq V$ . Then

$$V = S \oplus T \iff \forall v \in V, \exists! s \in S, t \in T : v = s + t.$$

*Proof.* [...]

## Example

Consider the canonical real vector space  $\mathbb{R}^2$ . Then  $\mathbb{R}^2 = S \oplus T$ , where  $S = \{(x, 0) \mid x \in \mathbb{R}\}$  and  $T = \{(0, y) \mid y \in \mathbb{R}\}$ .

## Definition

Let  $V$  and  $V'$  be vector spaces over the same field  $K$ . A function  $f : V \rightarrow V'$  is called:

(1) *( $K$ -)linear map* (or *(vector space) homomorphism* or *linear transformation*) if

$$\begin{aligned}f(v_1 + v_2) &= f(v_1) + f(v_2), \quad \forall v_1, v_2 \in V, \\f(kv) &= kf(v), \quad \forall k \in K, \forall v \in V.\end{aligned}$$

(2) *isomorphism* if it is a bijective  $K$ -linear map.

(3) *endomorphism* if it is a  $K$ -linear map and  $V = V'$ .

(4) *automorphism* if it is a bijective  $K$ -linear map and  $V = V'$ .

# Properties of linear maps

If  $f : V \rightarrow V'$  is a  $K$ -linear map, then the first condition from its definition tells us that  $f$  is a group homomorphism between the groups  $(V, +)$  and  $(V', +)$ . Then we have  $f(0) = 0'$  and  $f(-v) = -f(v)$ ,  $\forall v \in V$ .

We denote by  $V \simeq V'$  the fact that two vector spaces  $V$  and  $V'$  are isomorphic. We also denote

$$\text{Hom}_K(V, V') = \{f : V \rightarrow V' \mid f \text{ is } K\text{-linear}\},$$

$$\text{End}_K(V) = \{f : V \rightarrow V \mid f \text{ is } K\text{-linear}\},$$

$$\text{Aut}_K(V) = \{f : V \rightarrow V \mid f \text{ is bijective } K\text{-linear}\}.$$

## Theorem

*Let  $V$  and  $V'$  be vector spaces over  $K$  and  $f : V \rightarrow V'$ . Then  $f$  is a  $K$ -linear map  $\iff f(k_1v_1 + k_2v_2) = k_1f(v_1) + k_2f(v_2), \forall k_1, k_2 \in K, \forall v_1, v_2 \in V$ .*

*Proof. [...]*

(a) Let  $V$  and  $V'$  be vector spaces over  $K$  and let  $f : V \rightarrow V'$  be defined by  $f(v) = 0'$ ,  $\forall v \in V$ . Then  $f$  is a  $K$ -linear map, called the *trivial linear map*.

(b) Let  $V$  be a vector space over  $K$ . Then the identity map  $1_V : V \rightarrow V$  is an automorphism of  $V$ .

(c) Let  $V$  be a vector space and  $S \leq V$ . Define  $i : S \rightarrow V$  by  $i(v) = v$ ,  $\forall v \in S$ . Then  $i$  is a  $K$ -linear map, called the *inclusion linear map*.

(d) Let  $V$  be a vector space over  $K$  and  $a \in K$ . Define  $t_a : V \rightarrow V$  by  $t_a(v) = av$ ,  $\forall v \in V$ . Then  $t_a$  is an endomorphism of  $V$ .

## Examples II

(e) Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be defined by  $f(x, y) = x + y$ . Then  $f$  is an  $\mathbb{R}$ -linear map, because we have

$$\begin{aligned} f(k_1(x_1, y_1) + k_2(x_2, y_2)) &= f(k_1x_1 + k_2x_2, k_1y_1 + k_2y_2) \\ &= (k_1x_1 + k_2x_2) + (k_1y_1 + k_2y_2) \\ &= k_1(x_1 + y_1) + k_2(x_2 + y_2) \\ &= k_1f(x_1, y_1) + k_2f(x_2, y_2) \end{aligned}$$

for every  $k_1, k_2 \in K$  and for every  $(x_1, y_1), (x_2, y_2) \in \mathbb{R}^2$ .

On the other hand,  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $f(x, y) = xy$  is not an  $\mathbb{R}$ -linear map, because, for instance, we have

$$f((1, 0) + (0, 1)) = f(1, 1) = 1 \neq 0 = f(1, 0) + f(0, 1).$$

(f) Let  $\theta \in \mathbb{R}$  and let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by

$$f(x, y) = (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta),$$



## Examples III

which is the counterclockwise rotation of angle  $\theta$  about the origin in the plane. Then  $f$  is an  $\mathbb{R}$ -linear map. In particular, for  $\theta = \frac{\pi}{2}$ , we have  $f(x, y) = (-y, x)$ .

(g) For an interval  $I = [a, b] \subseteq \mathbb{R}$  we considered the real vector space

$$\mathbb{R}^I = \{f \mid f : I \rightarrow \mathbb{R}\}$$

and its subspaces

$$C(I, \mathbb{R}) = \{f \in \mathbb{R}^I \mid f \text{ continuous on } I\},$$

$$D(I, \mathbb{R}) = \{f \in \mathbb{R}^I \mid f \text{ derivable on } I\}.$$

Then

$$F : D(I, \mathbb{R}) \rightarrow \mathbb{R}^I, \quad F(f) = f',$$

$$G : C(I, \mathbb{R}) \rightarrow \mathbb{R}, \quad G(f) = \int_a^b f(t)dt,$$

are  $\mathbb{R}$ -linear maps.

## Theorem

- (i) Let  $f : V \rightarrow V'$  be an isomorphism of vector spaces over  $K$ . Then  $f^{-1} : V' \rightarrow V$  is again an isomorphism of vector spaces over  $K$ .
- (ii) Let  $f : V \rightarrow V'$  and  $g : V' \rightarrow V''$  be  $K$ -linear maps. Then  $g \circ f : V \rightarrow V''$  is a  $K$ -linear map.

*Proof.* Homework.

## Definition

Let  $f : V \rightarrow V'$  be a  $K$ -linear map. Then the set

$$\text{Ker } f = \{v \in V \mid f(v) = 0'\}$$

is called the *kernel* (or the *null space*) of the  $K$ -linear map  $f$  and the set

$$\text{Im } f = \{f(v) \mid v \in V\}$$

is called the *image* (or the *range space*) of the  $K$ -linear map  $f$ .

## Theorem

*Let  $f : V \rightarrow V'$  be a  $K$ -linear map. Then*

$$\text{Ker } f \leq V \text{ and } \text{Im } f \leq V'.$$

*Proof. [...]*

## Theorem

*Let  $f : V \rightarrow V'$  be a  $K$ -linear map. Then*

$$\text{Ker } f = \{0\} \iff f \text{ is injective.}$$

*Proof. [...]*

## Theorem

*Let  $f : V \rightarrow V'$  be a  $K$ -linear map and let  $X \subseteq V$ . Then*

$$f(\langle X \rangle) = \langle f(X) \rangle.$$

*Proof.* If  $X = \emptyset$ , then we have:

$$f(\langle \emptyset \rangle) = f(\{0\}) = \{f(0)\} = \{0'\} = \langle \emptyset \rangle = \langle f(\emptyset) \rangle.$$

If  $X \neq \emptyset$ , use

$$\langle X \rangle = \{k_1 v_1 + \cdots + k_n v_n \mid k_i \in K, v_i \in X, i = 1, \dots, n, n \in \mathbb{N}^*\} [\dots].$$

# The vector space of linear maps

## Theorem

Let  $V$  and  $V'$  be vector spaces over  $K$ . Consider on  $\text{Hom}_K(V, V')$  the operations:  $\forall f, g \in \text{Hom}_K(V, V')$  and  $\forall k \in K$ ,  $f + g, k \cdot f \in \text{Hom}_K(V, V')$ , where

$$\begin{aligned}(f + g)(v) &= f(v) + g(v), \\ (kf)(v) &= kf(v)\end{aligned}$$

$\forall v \in V$ . Then  $\text{Hom}_K(V, V')$  is a vector space over  $K$ .

## Corollary

Let  $V$  be a vector space over  $K$ . Then  $\text{End}_K(V)$  is a vector space over  $K$ .

## Extra: Image crossfade I

A black-and-white image of (say)

$$n = 1024 \times 768$$

pixels can be viewed as a vector in the real canonical vector space  $\mathbb{R}^n$ , where each component of the vector is the intensity of the corresponding pixel.

Let us consider two vectors representing images:

$$v_1 = \text{img}_1, \quad v_2 = \text{img}_2.$$

Now consider the following intermediate images:

## Extra: Image crossfade II



The vectors corresponding to the above images are the following linear combinations of the vectors  $v_1$  and  $v_2$ :

$$\begin{array}{ccccccccc} v_1, & \frac{8}{9}v_1 + \frac{1}{9}v_2, & \frac{7}{9}v_1 + \frac{2}{9}v_2, & \frac{6}{9}v_1 + \frac{3}{9}v_2, & \frac{5}{9}v_1 + \frac{4}{9}v_2, & & & & \\ \frac{4}{9}v_1 + \frac{5}{9}v_2, & \frac{3}{9}v_1 + \frac{6}{9}v_2, & \frac{2}{9}v_1 + \frac{7}{9}v_2, & \frac{1}{9}v_1 + \frac{8}{9}v_2, & v_2. & & & & \end{array}$$

One may use these images as frames in a video in order to get a crossfade effect.