

## Q&amp;A

Friday, July 12, 2024 4:58 PM

$$\begin{cases} x'' + tx' = 1 \\ x(0) = x'(0) = 0 \end{cases}$$

$$x'' + tx' = 1$$

second order linear non-homogeneous  
with non-constant coeff

$$x = x_h + x_p$$

$x_h \rightarrow$  the gen sol. of  $x'' + tx' = 0$

$x_p \rightarrow$  a partic. sol. of the given LN-1+DE

$$x'' + tx' = 0 \quad \text{LHDE}$$

$$x'' + tx' = 1 \quad y = x' \quad y(t) = x'(t) \Rightarrow y'(t) = x''(t)$$

$$y' + ty = 1 \quad \text{first order linear non-hom with non-const coeff.}$$

$$y = y_h + y_p \quad y_h: \quad y' + ty = 0 \quad \frac{dy}{dt} = -ty \quad y=0 \text{ sol.}$$

$$y \neq 0 \quad \frac{dy}{y} = -t dt$$

$$\ln|y| = -\frac{t^2}{2} + c$$

$$|y| = e^{-\frac{t^2}{2} + c}$$

$$y_h = \underbrace{c e^{-\frac{t^2}{2}}}, \quad c \in \mathbb{R}$$

$$y = \pm e^c \cdot e^{-\frac{t^2}{2}} \Rightarrow y=0$$

$$y_p = \varphi(t) e^{-\frac{t^2}{2}}$$

$$y' + ty = 1$$

$$\varphi' e^{-\frac{t^2}{2}} + \varphi \cdot e^{-\frac{t^2}{2}} \cdot (-t) + t \varphi e^{-\frac{t^2}{2}} = 1$$

$$\varphi'(t) = e^{\frac{t^2}{2}}$$

$$\varphi(t) = \int_0^t e^{\frac{s^2}{2}} ds$$

$$y_p = e^{-\frac{t^2}{2}} \int_0^t e^{\frac{s^2}{2}} ds$$

$$y = c \cdot e^{-\frac{t^2}{2}} + e^{-\frac{t^2}{2}} \int_0^t e^{\frac{s^2}{2}} ds, \quad c \in \mathbb{R}$$

$$\left. \begin{matrix} x'(0) = 0 \\ y = x' \end{matrix} \right\} \Rightarrow \underline{y(0) = 0} \Rightarrow c = 0$$

$$y(0) = c$$

$$y = e^{-\frac{t^2}{2}} \int_0^t e^{\frac{s^2}{2}} ds \Rightarrow x' = e^{-\frac{t^2}{2}} \int_0^t e^{\frac{s^2}{2}} ds \Rightarrow$$

$$\left. \begin{aligned} y &= e^{-\frac{z}{2}} \int_0^z e^{\frac{s}{2}} ds \\ y &= x' \end{aligned} \right\} \Rightarrow x' = e^{-\frac{z}{2}} \int_0^z e^{\frac{s}{2}} ds \Rightarrow$$

$$\Rightarrow x(t) = \int_0^t e^{-\frac{z^2}{2}} \int_0^z e^{\frac{s^2}{2}} ds dz + c, \quad c \in \mathbb{R}$$

$$x(0) = 0$$

$$\Rightarrow c = 0$$

The unique sol. of the IVP is

$$x(t) = \int_0^t e^{-\frac{z^2}{2}} \int_0^z e^{\frac{s^2}{2}} ds dz$$

Lecture 8.  $\rightarrow \ddot{\theta} + \omega^2 \sin \theta = 0 \quad \omega > 0$

$$x = \theta, \quad y = \dot{\theta}$$

we write it as the following planar system:

$$(2) \begin{cases} \dot{x} = y \\ \dot{y} = -\omega^2 \sin x \end{cases} \quad \text{the equil. points are } (k\pi, 0) : k \in \mathbb{Z}.$$

$$\theta(t) = 0, \quad \forall t \in \mathbb{R} \text{ is the unique sol. of the IVP } \begin{cases} \ddot{\theta} + \omega^2 \sin \theta = 0 \\ \theta(0) = 0 \\ \dot{\theta}(0) = 0 \end{cases}$$

Thus, it corresponds to the equilibrium  $(0, 0)$  of the planar system (2).

We have to justify that  $(0, 0)$  is stable but is not an attractor of the planar system (2).

if we linearize (2) around the equil. point  $(0, 0)$  we get

$$f(x, y) = \begin{pmatrix} y \\ -\omega^2 \sin x \end{pmatrix}$$

$$Jf(x, y) = \begin{pmatrix} 0 & 1 \\ -\omega^2 \cos x & 0 \end{pmatrix} \quad A := Jf(0, 0) = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix}$$

$$T^{-1} \dot{T} = \begin{pmatrix} -\omega^2 \sin x \\ 0 \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} -\omega \cos x & 0 \\ 0 & 0 \end{pmatrix} \quad \text{for } x=0$$

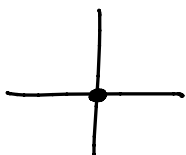
the eigenvalues of  $A$  are  $\lambda_1 = i\omega$ ,  $\lambda_2 = -i\omega$ .

$\operatorname{Re}(\lambda_1) = 0$  and  $\operatorname{Re}(\lambda_2) = 0 \Rightarrow$  the equl  $(0,0)$  is not hyperbolic

$\Rightarrow$  the LM (linearisation method) fails

$\leadsto$  look for a first integral

we find  $H: \mathbb{R}^2 \rightarrow \mathbb{R}$ ,  $H(x,y) = \frac{y^2}{2} + \omega^2(1 - \cos x)$



In particular, this first integral is well-defined in a neighborhood of the equl point  $(0,0)$ .

$\Rightarrow (0,0)$  is stable, but it is not an attractor.

the 2 theorems  
from Lecture 8