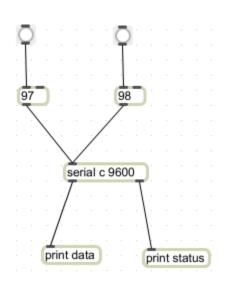
Simple Serial

MaxMSP → Arduino



```
int inByte = 0;  // incoming serial byte

void setup()
{
    Serial.begin(9600);
    pinMode(13, OUTPUT);  // connect an LED here
}

void loop()
{
    inByte = Serial.read();
    if (inByte == 97) digitalWrite(13, HIGH);  // letter 'a' turns LED on
    if (inByte == 98) digitalWrite(13, LOW);  // letter 'b' turns LED off
}
```

- Serial.read receives one byte at a time
- Click on MaxMSP "97" message: Arduino pin 13 goes high
- Click on MaxMSP "98" message: Arduino pin 13 goes low
- These numbers are single ASCII byte values, arbitrarily chosen

ASCII Code

each byte value corresponds to a character

```
Dec Hx Oct Html Chr Dec Hx Oct Html Chr
Dec Hx Oct Char
                                     Dec Hx Oct Html Chr
    0 000 NUL (null)
                                      32 20 040   Space
                                                            64 40 100 &#64: 0
                                                                               96 60 140 &#96:
                                      33 21 041 4#33;
                                                            65 41 101 @#65; A
                                                                               97 61 141 6#97;
    1 001 SOH (start of heading)
   2 002 STX (start of text)
                                      34 22 042 @#34; "
                                                            66 42 102 B B
                                                                              98 62 142 6#98;
                                      35 23 043 4#35; #
                                                            67 43 103 a#67; C
                                                                               99 63 143 6#99;
   3 003 ETX (end of text)
                                                            68 44 104 @#68; D
   4 004 EOT (end of transmission)
                                      36 24 044 $ 🕏
                                                                              |100 64 144 d d
                                      37 25 045 % 🕏
                                                            69 45 105 E E
                                                                              101 65 145 @#101; e
    5 005 ENQ (enquiry)
    6 006 ACK (acknowledge)
                                      38 26 046 @#38; @
                                                            70 46 106 @#70; F
                                                                              102 66 146 f f
                                      39 27 047 4#39;
                                                            71 47 107 @#71; G
                                                                              103 67 147 @#103; g
    7 007 BEL
              (bell)
                                                            72 48 110 @#72; H
                                                                              104 68 150 @#104; h
                                      40 28 050 4#40;
    8 010 BS
              (backspace)
    9 011 TAB
             (horizontal tab)
                                      41 29 051 )
                                                            73 49 111 a#73; I
                                                                              105 69 151 @#105; i
   A 012 LF
                                      42 2A 052 @#42;
                                                            74 4A 112 @#74; J
                                                                              106 6A 152 @#106; j
              (NL line feed, new line)
                                                                              |107 6B 153 k k
11 B 013 VT
              (vertical tab)
                                      43 2B 053 + +
                                                            75 4B 113 K K
   C 014 FF
                                                            76 4C 114 L L
                                                                              108 6C 154 @#108; 1
              (NP form feed, new page)
                                      44 2C 054 ,
                                                            77 4D 115 @#77; M
                                                                              109 6D 155 @#109; 10
   D 015 CR
                                      45 2D 055 -
              (carriage return)
14 E 016 50
              (shift out)
                                      46 2E 056 .
                                                            78 4E 116 @#78; N
                                                                              110 6E 156 n n
15 F 017 SI
              (shift in)
                                      47 2F 057 /
                                                            79 4F 117 @#79; 0
                                                                             |111 6F 157 o º
16 10 020 DLE (data link escape)
                                      48 30 060 4#48; 0
                                                            80 50 120 P P
                                                                              112 70 160 @#112; p
                                                            81 51 121 @#81; 0
17 11 021 DC1 (device control 1)
                                      49 31 061 4#49; 1
                                                                              |113 71 161 q q
18 12 022 DC2 (device control 2)
                                      50 32 062 4#50; 2
                                                            82 52 122 R R
                                                                             |114 72 162 r r
19 13 023 DC3 (device control 3)
                                      51 33 063 3 3
                                                            83 53 123 4#83; 💲
                                                                             |115 73 163 s 3
20 14 024 DC4 (device control 4)
                                      52 34 064 @#52; 4
                                                            84 54 124 @#84; T
                                                                              116 74 164 @#116; t
                                                           85 55 125 U U
21 15 025 NAK (negative acknowledge)
                                      53 35 065 4#53; 5
                                                                              117 75 165 u u
                                                            86 56 126 @#86; V
                                                                              118 76 166 @#118; V
22 16 026 SYN (synchronous idle)
                                      54 36 066 @#54; 6
                                      55 37 067 4#55: 7
23 17 027 ETB (end of trans. block)
                                                            87 57 127 W W
                                                                              |119 77 167 &#ll9; ₩
                                                            88 58 130 X X
                                                                              120 78 170 @#120; X
24 18 030 CAN (cancel)
                                      56 38 070 4#56; 8
25 19 031 EM (end of medium)
                                      57 39 071 4#57; 9
                                                            89 59 131 Y Y
                                                                             121 79 171 @#121; Y
26 1A 032 SUB (substitute)
                                      58 3A 072 4#58; :
                                                            90 5A 132 Z Z
                                                                              |122 7A 172 @#122; Z
27 1B 033 ESC (escape)
                                      59 3B 073 &#59; ;
                                                            91 5B 133 [ [
                                                                              123 7B 173 {
28 1C 034 FS
              (file separator)
                                      60 3C 074 < <
                                                            92 5C 134 \ \
                                                                              124 7C 174 |
29 1D 035 GS
                                      61 3D 075 = =
                                                            93 5D 135 ] ]
                                                                             125 7D 175 @#125;
              (group separator)
30 1E 036 RS
              (record separator)
                                      62 3E 076 > >
                                                           94 5E 136 ^ ^
                                                                             |126 7E 176 ~ ~
                                                           95 5F 137 6#95; _ | 127 7F 177 6#127; DEL
31 1F 037 US
              (unit separator)
                                      63 3F 077 ? ?
```

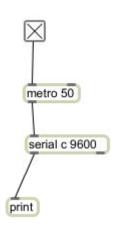
Simple Serial

Arduino → MaxMSP

```
int sensorValue = 0;

void setup()
{
    Serial.begin(9600);
}

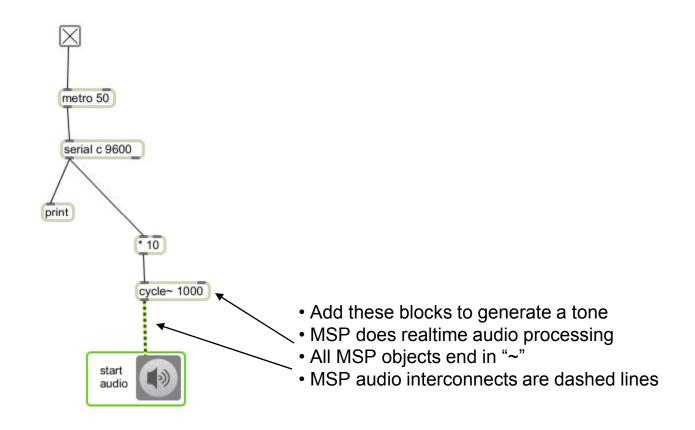
void loop()
{
    sensorValue = analogRead(0);
    sensorValue = map(sensorValue, 0, 1023, 0, 255);
    Serial.write(sensorValue);
    delay(100);
}
```



- Sends one byte at a time
- Only a single stream of numbers (i.e. data from one sensor) can be sent
- Values are limited to the range 0-255
- "map" command takes 0-1023 sensor range and reduces it to a range of 0-255

Simple Serial

Arduino sensor controls sound in MaxMSP



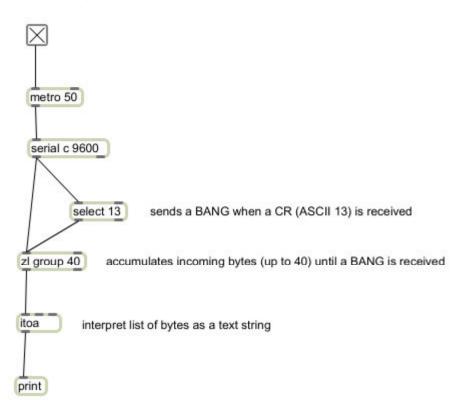
Using Formatted Data

Arduino → MaxMSP

```
int sensorValue = 0;

void setup()
{
    Serial.begin(9600);
}

void loop()
{
    sensorValue = analogRead(0);
    //sensorValue = map(sensorValue, 0, 1023, 0, 255);
    Serial.println(sensorValue);
    delay(100);
}
```



- Formatting allows multi-byte packets to be sent
- "Real world" language can be used
- Data from multiple sensors can be sent
- Numbers can take any format or range of values (no need to use "map")
- Serial.printIn automatically adds ASCII 13 to the end of every packet sent

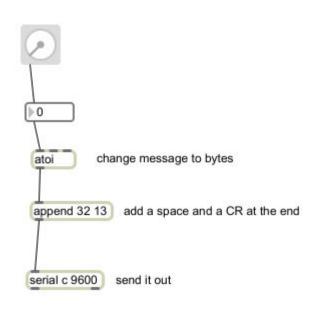
Multiple Messages

Arduino → MaxMSP

```
int sensorValue = 0;
                                                                metro 50
int count:
                                                                 serial c 9600
void setup()
 Serial.begin(9600);
                                                                                    sends a BANG when a CR (ASCII 13) is received
                                                                       select 13
                                                                             accumulates incoming bytes (up to 40) until a BANG is received
                                                               zl group 40
void loop()
 sensorValue = analogRead(0);
 count = count + 1;
                                                                                     interpret stream of bytes as a string of ASCII characters
 Serial.print(sensorValue);
 Serial.write(32);
                                                              unpack 1 1
                                                                           separate messages in the string
 Serial.println(count);
 delay(100);
                                                        916
                                                                        4881
                                       sensorValue
                                                                               count
```

Formatted Serial

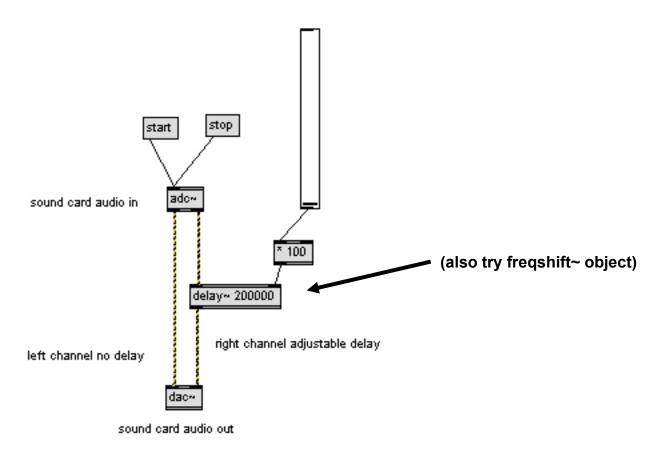
MaxMSP → Arduino



```
int inByte = 0;
                   // incoming serial byte
char buffer[40];
int index = 0:
int value;
void setup()
 Serial.begin(9600);
 pinMode(11, OUTPUT);
void loop()
   index = 0:
   do
     buffer[index] = Serial.read();
                                               // get a byte from the serial port
     if (buffer[index]!=-1) index = index+1; // -1 if no byte is present
   } while (buffer[index-1] != 32);
   //keep collecting bytes until a space is received
   value = atoi(buffer);
                            // interpret buffer string as an integer
   analogWrite(11,value); // set brightness of an LED on pin 11
```

Audio Processing

External Sound Input



Assignment for Thursday 8 April 2010:

One page proposal for Final Project

This proposal is due in class on Thursday April 8th. The project will be presented in class on May 6th

Final Project

For this project, you will connect multiple sensors (such as switches, potentiometers, flex sensors, light sensors, thermistors, ping distance sensors, IR distance sensors, accelerometers, etc...) to the Arduino. and use them to control audio and/or video in MaxMSP.

In your proposal please include a description of what you want your project to do and how it will react and interact with its environment. Make a list of specifically which sensors you intend to use and provide a breakdown of the system's intended behavior describing how the hardware and software will function in a range of situations, for example:

- ping distance sensor controls speed of video playback based upon viewer location
- video track is selected by buttons on keyboard
- -- audio is pitch shifted by potentiometer setting
- -- tilting the keyboard triggers new audio track...

Try to make the system as engaging/interesting as possible. It may help to first choose a category for the device you want to make such as "toy", "game", "sculpture", "fashion accessory", or "musical instrument". It is also a good idea to decide first whether this is primarily a sound or video based system such as a musical instrument, effects box, or interactive video installation.

The primary focus over the remaining weeks of the class will be working together to make sure each of you can realize your projects as planned. The grade for this project will be based upon a combination of technical proficiency (in terms of software, hardware, and mechanical/visual design) and conceptual development.