

Assumptions:

$h(s)$  is an admissible heuristic  $\Rightarrow 0 \leq h(s) \leq \text{length}(\text{path}(s, s_g))$

All actions have a positive cost

Let  $\text{path}(s_i, s_g)$  be the path returned by A\*.

Assume for the sake of contradiction that there exists a second path,  $\text{path}(s_i, s_g)'$  such that

$$\text{cost}(\text{path}(s_i, s_g)') < \text{cost}(\text{path}(s_i, s_g))$$

Note that if we do not exclude the case where  $s_g = s_g'$ , in which case  $\text{path}(s_i, s_g)'$  would be a shorter path to the same goal.

We first observe that the path length from a node to itself is 0.

$$\text{length}(\text{path}(s, s)) = 0$$

and thus the length of the shortest path from a goal state to a goal state must be 0.

$$\text{path}(s_g, s_g) = 0$$

And because  $h$  is an admissible heuristic

$$h(s_g) = 0$$

Therefore

$$g(s_g) = \text{cost}(\text{path}(s_i, s_g)) + h(s_g) = \text{cost}(\text{path}(s_i, s_g))$$

Because  $\text{cost}(\text{path}(s_i, s_g)') < \text{cost}(\text{path}(s_i, s_g))$  we know that  $g(s_g') < g(s_g)$

Let  $s_j$  be the first node on  $\text{path}(s_i, s_g)'$  that was not expanded by A\*. Because  $s_j$ 's predecessor on path  $\text{path}(s_i, s_g)'$  has been expanded we know that  $s_j$  must be on the priority queue when the A\* algorithm returns. We next observe that

$$g(s_j) = \text{path}(s_i, s_j) + h(s_j)$$

Because  $h$  is admissible we know that  $h(s_j) \leq \text{path}(s_i, s_j)$  which means that

$$g(s_j) = \text{path}(s_i, s_j) + h(s_j) \leq \text{path}(s_i, s_j) + \text{path}(s_i, s_j)$$

and  $\text{path}(s_i, s_j) + \text{path}(s_i, s_j) = \text{path}(s_i, s_g)'$ , so

$$g(s_j) \leq \text{path}(s_i, s_g)'$$

We also know that

$$g(s_g) = \text{cost}(\text{path}(s_i, s_g)) \text{ and}$$

$$\text{cost}(\text{path}(s_i, s_g)') < \text{cost}(\text{path}(s_i, s_g)), \text{ so}$$

$$g(s_j) \leq g(s_g)$$

Because A\* selects nodes from a priority queue ordered by  $g(s)$ , we know that  $s_j$  cannot be on the priority queue when A\* returns  $s_g$  because A\* would have selected  $s_j$  instead of  $s_g$ . By contradiction  $\text{path}(s_i, s_g)'$  cannot exist. Thus the path returned by A\* must be the shortest path