MA283: Linear Algebra

 $\begin{array}{c} 70\% \ {\rm Exam} \\ 30\% \ {\rm Continuous \ Assessment \ (Homework)} \\ 10\% \ {\rm Optional \ Project \ (Bonus)} \end{array}$

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1 Systems of linear equations

1.1 Linear equations and Solution Sets

A linear equation in the variables x and y is an equation of the form

$$2x + y = 3$$

If we replace x and y with some numbers, the statement **becomes true or false**.

Definition 1.1: Solution to a linear equation

A pair, $(x_0, y_0) \in \mathbb{R}$, is a solution to an linear equation if setting $x = x_0$ and $y = y_0$ makes the equation true.

Definition 1.2: Solution set

The **solution set** is the set of all solutions to a linear equation.

$$a_1X_1 + a_2X_2 + \ldots + a_nX_n = b$$
 where $a_i, b \in \mathbb{R}$

is an **affine hyperplane** in \mathbb{R}^n ; geometrically resembles a copy of \mathbb{R}^{n-1} inside \mathbb{R}^n .

1.2 Elementary Row Operations

To solve a system of linear equations we associate an **augmented matrix** to the system of equations. For example:

To solve, we can perform the following Elementary Row Operations (EROs):

- 1. Multiply a row by a non-zero constant.
- 2. Add a multiple of one row to another row.
- 3. Swap two rows.

The goal of these operations is to transform the augmented matrix into **row echelon form** (REF) or **reduced row echelon form** (RREF).

1.2.1 REF and Strategy

We say a matrix is in **row echelon form** (REF) if:

- The first non zero entry in each row is a 1 (called the **leading 1**).
- If a column has a leading 1, then all entries below it are 0.
- $\bullet\,$ The leading 1 in each row is to the right of the leading 1 in the previous row.
- All rows of 0s are at the bottom of the matrix.

$$\begin{bmatrix} 1 & 2 & -1 & | & 3 \\ 0 & 1 & 2 & | & -1 \\ 0 & 0 & 1 & | & -1 \end{bmatrix}$$

Example of REF

We have produced a new system of equations. This is easily solved by back substitution.

Concept 1.1: Stategy for Obtaining REF

- \bullet Get a 1 as the top left entry
- Use this 1 to clear the entries below it
- Move to the next column and repeat
- Continue until all leading 1s are in place
- Use back substitution to solve the system

1.2.2 Row Reduced Echelon Form

A matrix is in reduced row echelon form (RREF) if:

- It is in REF
- $\bullet\,$ The leading 1 in each row is the only non-zero entry in its column.

$$\begin{bmatrix} 1 & 0 & 0 & | & 2 \\ 0 & 1 & 0 & | & -1 \\ 0 & 0 & 1 & | & -1 \end{bmatrix}$$

 $Example\ of\ RREF$

1.3 Leading variables and free variables

We'll start by an example:

Solving this system of equations, we get:

RREF:
$$\begin{bmatrix} 1 & 0 & 0 & 2 & | & 4 \\ 0 & 1 & 0 & -1 & | & 2 \\ 0 & 0 & 0 & 1 & | & 2 \end{bmatrix} \Rightarrow \begin{array}{c} x_1 & + & 2x_4 & = & 4 \\ x_2 & - & x_4 & = & 2 \\ x_3 & + & x_4 & = & 2 \end{array} \Rightarrow \begin{array}{c} x_1 & = & 4 - 2x_4 \\ x_2 & = & 2 + x_4 \\ x_3 & = & 2 - x_4 \end{array}$$

This RREF tells us how the **leading variables** (x_1, x_2, x_3) depend on the **free variable** (x_4) . The free variable can take any value in \mathbb{R} . We write the solution set as:

$$x_1 = 4 - 2t$$
, $x_2 = 2 + t$, $x_3 = 2 - t$, $x_4 = t$ where $t \in \mathbb{R}$
$$(x_1, x_2, x_3, x_4) = (4 - 2t, 2 + t, 2 - t, t); \quad t \in \mathbb{R}$$

Definition 1.3: Leading and Free Variables

- Leading variable : A variable whose columns in the RREF contain a leading 1
- Free variable: A variable whose columns in the RREF do not contain a leading 1

1.4 Consistent and Inconsistent Systems

Consider the following system of equations:

We can see the last row of the REF is:

$$0x + 0y + 0z = 1$$

This equation clearly has no solution, and hence the system has no solutions. We say the system is **inconsistent**. Alternatively, we say the system is **consistent** if it has at least one solution.

1.5 Possible Outcomes when solving a system of equations

• The system may be inconsistent (no solutions) - i.e:

$$[0\ 0\ \dots\ 0\ |\ a] \quad a \neq 0$$

- The system may be **consistent** which occurs if:
 - Unique Solutions each column (aside from the rightmost) contains a single leading 1. i.e:

$$\begin{bmatrix} 1 & 0 & 0 & | & 4 \\ 0 & 1 & 0 & | & 3 \\ 0 & 0 & 1 & | & -2 \end{bmatrix}$$

- **Infinitely many solutions** at least one variable does not appear as a leading 1 in any row, making it a free variable - i.e:

$$\begin{bmatrix} 1 & 2 & -1 & | & 3 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

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1.6 Elementary Row Operations as Matrix Transformations

Elementary row operations may be interpreted as **matrix multiplication**. To see this, first we introduce the **Identity matrix**:

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The I_m Identity matrix is an $m \times m$ matrix with 1s on the diagonal and 0s elsewhere. We also introduce the $E_{i,j}$ matrix which has 1 in the (i,j) position and 0s elsewhere. For example:

$$E_{1,2} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Then:

$$I_3 + 4E_{1,2} = \begin{bmatrix} 1 & 4 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing a row operation on A is the same as multiplying A by an appropriate matrix E on the left.

1.6.1 Multiplying a Row by a Non-Zero Scalar

When multiplying row i of matrix A by a scalar $\alpha \neq 0$, we can use the matrix:

$$I_m + (\alpha - 1)E_{i,i}$$

This works because it modifies only the (i, i) entry of the identity matrix to be α while keeping all other entries unchanged. When multiplied with A, it scales row i by α and leaves all other rows intact.

Example: If $\alpha = 5$ and i = 2, then:

$$I_3 + 4E_{2,2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \qquad (I_3 + 4E_{2,2})A = \begin{bmatrix} 1 & 2 & 3 \\ 20 & 25 & 30 \\ 7 & 8 & 9 \end{bmatrix}$$

1.6.2 Switching Two Rows

To swap rows i and k, we use:

$$S = I_m + E_{i,k} + E_{k,i} - E_{i,i} - E_{k,k}$$

This works by:

- Removing the 1's at positions (i, i) and (k, k) from the identity matrix
- Adding 1's at positions (i, k) and (k, i)

Example: Swapping rows 1 and 3:

$$S = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \qquad SA = \begin{bmatrix} 7 & 8 & 9 \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{bmatrix}$$

1.6.3 Adding a Multiple of One Row to Another

To replace row k with row $k + \alpha \times$ row i, use:

$$I_m + \alpha E_{k,i}$$

This adds α times row i to row k while leaving all other rows unchanged because:

- For any row $j \neq k$, the corresponding row in this matrix is just the standard basis row
- Row k becomes the sum of the standard basis row k plus α times the standard basis row i

Example: Adding 3 times row 1 to row 2:

$$I_3 + 3E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \qquad (I_3 + 3E_{2,1})A = \begin{bmatrix} 1 & 2 & 3 \\ 7 & 11 & 15 \\ 7 & 8 & 9 \end{bmatrix}$$

Below we describe the three types of elementary matrices and derive their inverses. In each case, the inverse is obtained by performing the *reverse* row operation, and it is itself an elementary matrix.

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1. Multiplying a Row by a Nonzero Scalar

Operation: Multiply row i by $\alpha \neq 0$.

Elementary Matrix:

$$E = I_m + (\alpha - 1)E_{i,i},$$

where $E_{i,i}$ is the matrix with a 1 in the (i,i) entry and 0 elsewhere.

Inverse: To reverse the operation, multiply row i by $1/\alpha$. Hence, the inverse is

$$E^{-1} = I_m + \left(\frac{1}{\alpha} - 1\right) E_{i,i} = I_m + \frac{1 - \alpha}{\alpha} E_{i,i}.$$

This matrix is of the same elementary form.

2. Swapping Two Rows

Operation: Swap rows i and k.

Elementary Matrix:

$$S = I_m - E_{i,i} - E_{k,k} + E_{i,k} + E_{k,i}.$$

This matrix interchanges row i with row k.

Inverse: Since swapping the same two rows twice returns them to their original positions,

$$S^{-1} = S.$$

Thus, the inverse is also an elementary matrix.

3. Adding a Multiple of One Row to Another

Operation: Add α times row i to row k.

Elementary Matrix:

$$E = I_m + \alpha E_{k,i}.$$

Inverse: To undo the operation, subtract α times row i from row k. Therefore,

$$E^{-1} = I_m - \alpha E_{k,i}.$$

This is again an elementary matrix.

Conclusion

Each elementary matrix is invertible by performing the reverse row operation. Hence, every elementary matrix E has an inverse E^{-1} that is itself an elementary matrix.

Example 1.1: Write the inverse of an elementary matrix and show it is an elementary matrix