Chapter 1 Computer System Overview

(based on original slides by Pearson)

WHAT IS AN OPERATING SYSTEM?

What is an OS

- Informally: Something that helps you use the available hardware
 - Expensive Hardware, Cheap People
 Goal: maximize hardware utilization
 - Now: Cheap Hardware, Expensive People
 Goal: make it easy for people to use.
- How to make it easier to use? Abstractions

Operating System

- An OS is a standardized abstraction, a VM, that is implemented on the underlying machine.
 - Manages resources: processor, memory, I/O
 - Provides a set of services to system users
 - Consumes resources (complexity vs cost)

WHAT DO WE NEED TO RUN AN OPERATING SYSTEM?

Basic Elements

- What do you need in a computer?
 - A processing unit (CPU)
 - Memory
 - I/O modules

Note, these are already abstractions of more complicated hardware systems.

- System bus connecting them
- Question is: What do we need from these modules?

Basic Elements

- Processing unit
 - Some registers/buffers
 - Memory address resister (MAR)
 - Specifies the address for the next read or write
 - Memory buffer register (MBR)
 - Contains data written into memory or receives data read from memory
 - I/O address register
 - I/O buffer register

Basic Elements

- Main Memory
 - Volatile, referred to as real memory or primary memory
- I/O Modules
 - Secondary Memory Devices, communications equipment, terminals
- System bus
 - Communication among processors, main memory, and I/O modules

Computer Components

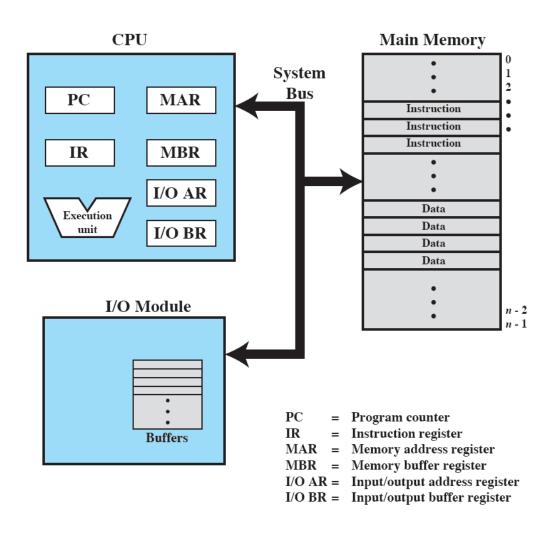


Figure 1.1 Computer Components: Top-Level View

User-Visible Registers

- Enable programmer to minimize main memory references by optimizing register use
- Available to all programs application programs and system programs
- Depend on computer architecture (E.g. r1-r15; r0 might be hard coded to 0)
- May be referenced by machine language
- Usually the compiler controls them
- Can be user controlled
 - Register keyword in C
 - Volatile keyword in C

User-Visible Registers

- Two categories of visible registers:
- 1. <u>Data registers:</u> store data (e.g., results from calculations; math data section in the PIC18)
- 2. Address register: point to memory
 - Indexed addressing (Adding an index to a base value to get the effective address)
 - Segment pointer (When memory is divided into segments, memory is referenced by a segment and an offset)
 - Stack pointer (Points to top of stack for pop&push)

Control and Status Registers

- Invisible to the user (on most architectures)
- Used by processor to control operating of the processor
- Used by privileged OS routines to control the execution of programs

Examples of Invis. Registers

- Program counter (PC)
 - Contains the address of an instruction to be fetched
- Instruction register (IR)
 - Contains the instruction most recently fetched
- Program status word (PSW)
 - Contains status information and condition codes (e.g, Interrupts enabled, errors, supervisor mode bit)

Condition Codes or Flags

- Part of the PSW
- Bits set by processor hardware as a result of operations
 - Example: Positive, negative, zero, or overflow result of arithmetic operation
- Used for conditional branching
- Only implicitly accessible on most architectures
- Architecture specific ones include reset status (brownout, watchdog, power button).

SO HOW DO WE EXECUTE PROGRAMS ON THIS?

Instruction Execution

- Simple version:
 - 1. Processor fetches instruction from memory
 - 2. Processor executes the instruction
 - 3. Goto 1
- Reality:
 - Pipeline
 - VLIW Very Long Instruction Word
 - Superscalar architectures
 - ... (see your computer architecture class)

Basic Instruction Cycle

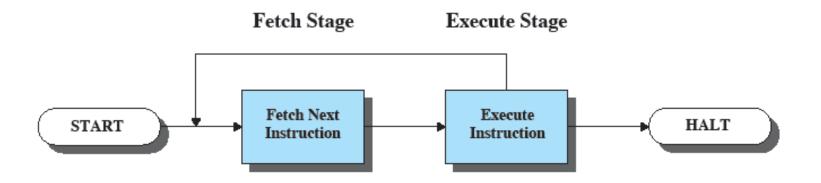


Figure 1.2 Basic Instruction Cycle

Instruction Fetch and Execute

- The processor fetches the instruction from memory
- Program counter (PC) holds address of the instruction to be fetched next
- PC is incremented after each fetch

Instruction Register

- Fetched instruction loaded into instruction register (IR)
- Categories of actions dictated by the instruction
 - Processor-memory, processor-I/O, data processing, control (e.g., branching)
 - No clear boundaries; an instruction may include several of these actions

A Hypothetical Machine

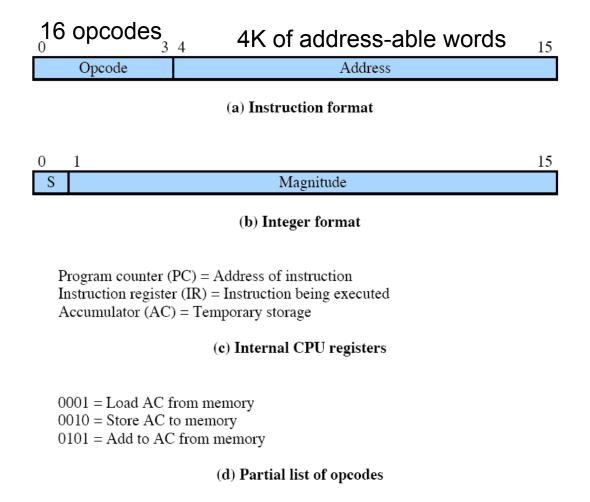


Figure 1.3 Characteristics of a Hypothetical Machine

Example of Program Execution

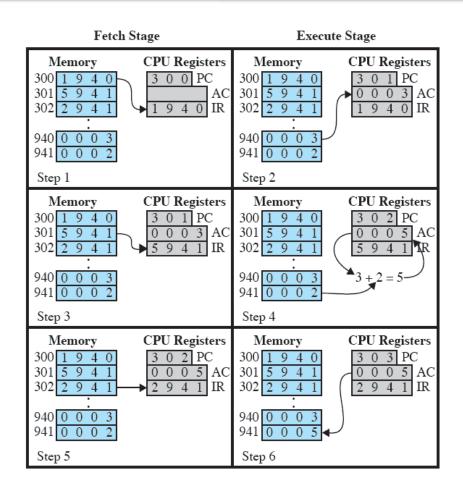


Figure 1.4 Example of Program Execution (contents of memory and registers in hexadecimal)

HOW TO DEAL WITH PERIPHERALS?

Interrupts

- Most I/O devices are slower than the processor
 - Processor must pause to wait for device
- Interrupts help to improve the processor utilization.
- The change the normal sequencing of the processor

Classes of Interrupts

Table 1.1 Classes of Interrupts

Program	Generated by some condition that occurs as a result of an instruction execution, such as arithmetic overflow, division by zero, attempt to execute an illegal machine instruction, and reference outside a user's allowed memory space.
Timer	Generated by a timer within the processor. This allows the operating system to perform certain functions on a regular basis.
I/O	Generated by an I/O controller, to signal normal completion of an operation or to signal a variety of error conditions.
Hardware failure	Generated by a failure, such as power failure or memory parity error.

Example: Watchdog

Program Flow of Control

I/O

Program

I/O

4

(5)

Command WRITE END 2

User

Program

WRITE

3

WRITE

1

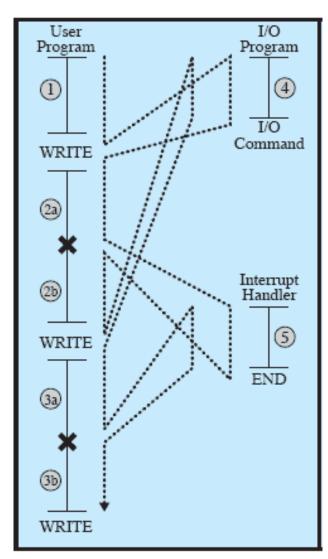
Wait until completion Here.

No interrupts.

(a) No interrupts

Program Flow of Control

Interrupt with short I/O wait.

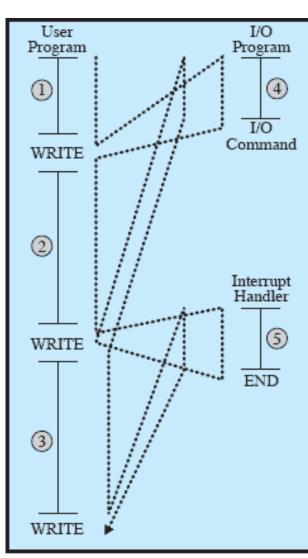


(b) Interrupts; short I/O wait

Program Flow of Control

Interupt with long I/O wait.

Need to wait for first I/O here.



(e) Interrupts; long I/O wait

Interrupt Stage

- Processor checks for interrupts
- If interrupt
 - Suspend execution of program (store snapshot!!)
 - Execute interrupt-handler routine
 - Resume execution of program
- This is a simplified version:
 - Nested interrupts?
 - Interrupt priorities?
 - Counting interrupts?

Transfer of Control via Interrupts

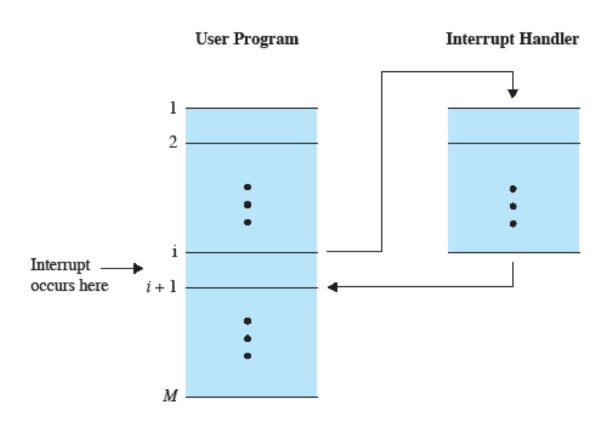


Figure 1.6 Transfer of Control via Interrupts

Instruction Cycle with Interrupts

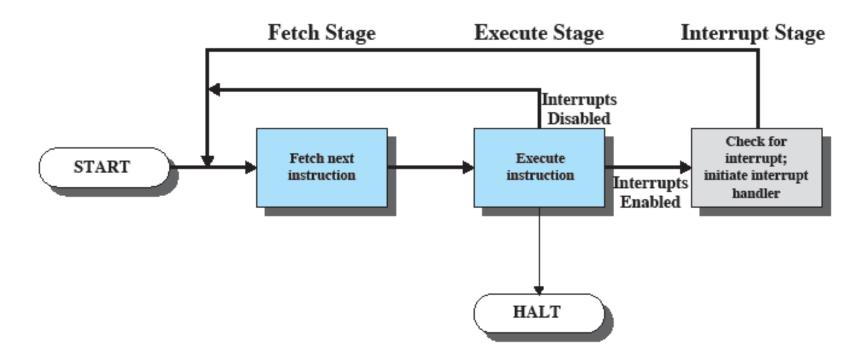


Figure 1.7 Instruction Cycle with Interrupts

Big advantage: no special code or programmer attention required. Everything happens in hardware.

Program Timing: Short I/O Wait

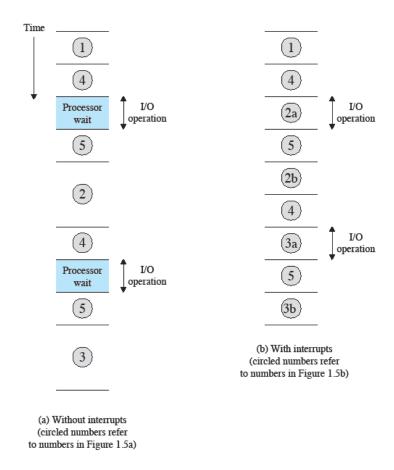


Figure 1.8 Program Timing: Short I/O Wait

Program Timing: Long I/O Wait

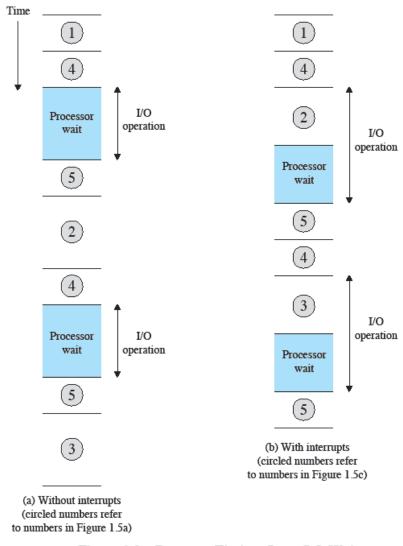


Figure 1.9 Program Timing: Long I/O Wait

Simple Interrupt Processing

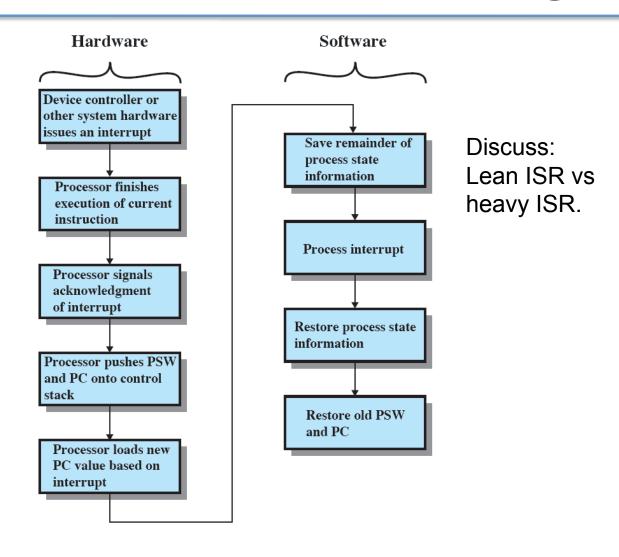
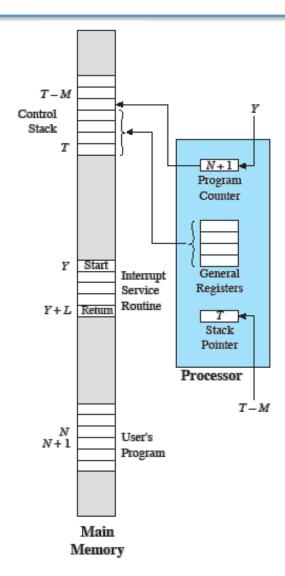


Figure 1.10 Simple Interrupt Processing

An Interrupt Occurs

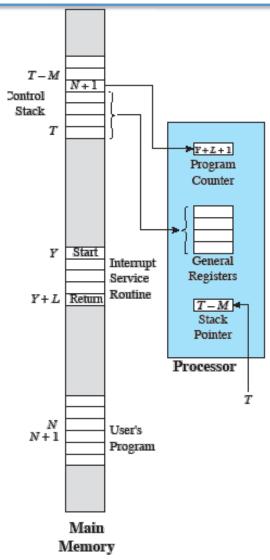
Storing a snapshot.



(a) Interrupt occurs after instruction at location N

Returning from an Interrupt

Restoring from a snapshot.

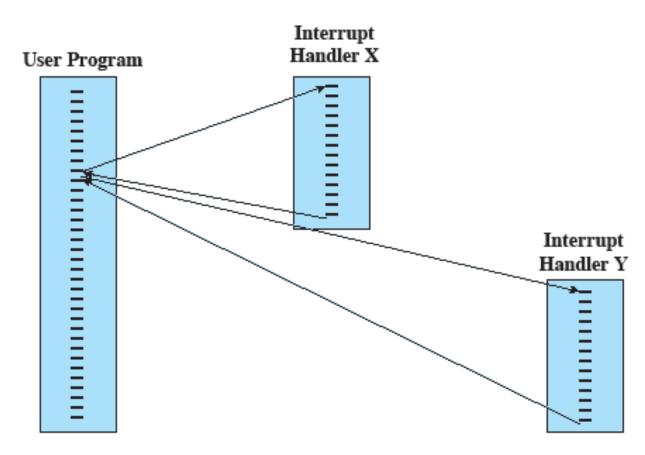


(b) Return from interrupt

Multiple Interrupts?

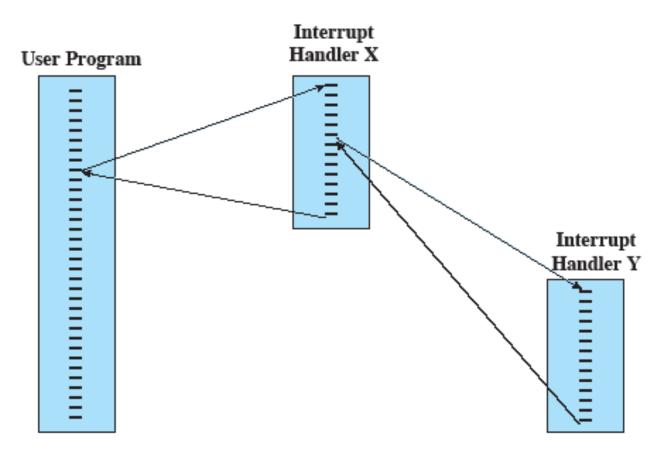
- Multiple I/O, timers, ADC, PWM settings, RS232, CAN, EEPROM, I2C, etc.
- Approach 1:
 - Disable interrupts in ISR
 - No priority information
 - Not useful for time critical elements
- Approach 2:
 - Priorities for ISR
 - How to assign priorities
 - finite number of priority levels

Sequential Interrupt Processing



(a) Sequential interrupt processing

Nested Interrupt Processing



(b) Nested interrupt processing

Multiprogramming

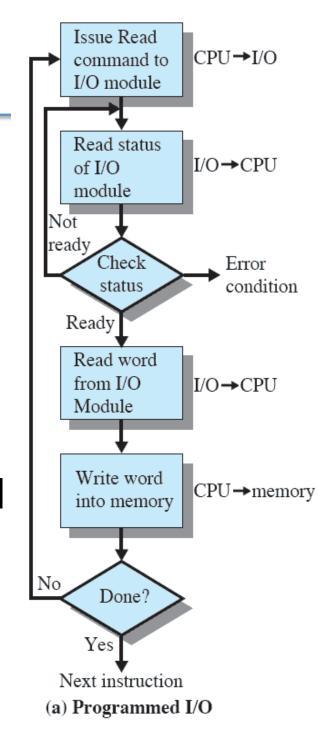
- Long I/O requests still leave the processor idle
 → run multiple programs
- Processor has more than one program to execute
- The sequence the programs are executed depend on their relative priority and whether they are waiting for I/O
- After an interrupt handler completes, control may not return to the program that was executing at the time of the interrupt

Memory Hierarchy

Self study

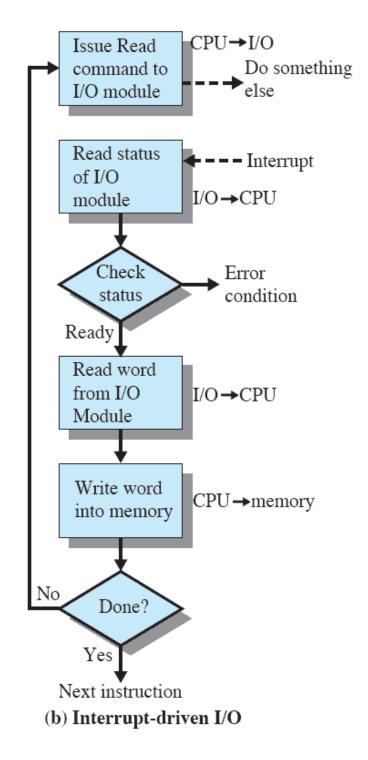
Programmed I/O

- I/O module performs the action, not the processor
- Sets the appropriate bits in the I/O status register
- No interrupts occur
- Processor checks status until operation is complete
- Called busy waiting, has benefits



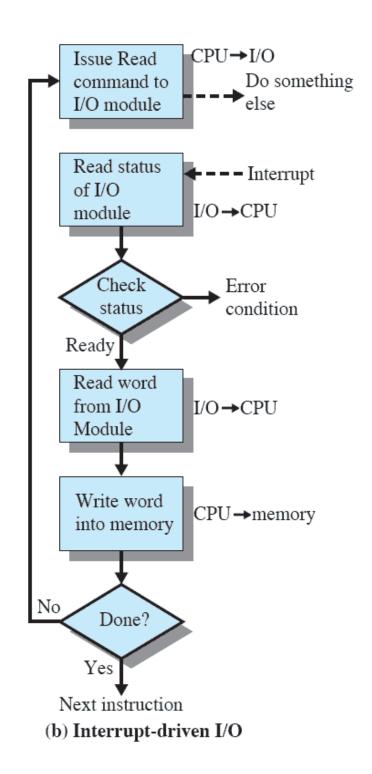
Interrupt-Driven I/O

- Processor is interrupted when I/O module ready to exchange data
- Processor saves context or program executing and begins executing interrupt-handler



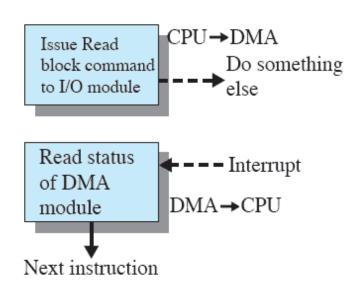
Interrupt-Driven I/O

- No needless waiting
- Consumes a lot of processor time compared to DMA, because every word read or written passes through the processor



Direct Memory Access

- Transfers a block of data directly to or from memory
- An interrupt is sent when the transfer is complete
- More efficient
- Not always available (e.g., external peripherals)



(c) Direct memory access