

Clown Cannon 2 Assignment - Robert P.

Test Outputs:

```
ares.harpercollege.edu - PuTTY

e_prevost@ares:~/homeworkAssignments$ ./clownCannon2
Please Input Max Velocity Followed by Min and Max Angle: 100 20 45

Velocity(mph):          4.000
Angle (degrees):        39.000
Distance:                1.052
e_prevost@ares:~/homeworkAssignments$ ./clownCannon2
Please Input Max Velocity Followed by Min and Max Angle: 300 20 70

Velocity(mph):          158.000
Angle (degrees):        57.000
Distance:                1533.053
e_prevost@ares:~/homeworkAssignments$ ./clownCannon2
Please Input Max Velocity Followed by Min and Max Angle: 50 10 40

Velocity(mph):           19.000
Angle (degrees):         13.000
Distance:                 10.638
```

Source Code:

```
File Edit Search Preferences Shell Macro Windows Help

/* Clown Cannon 2
 * Code Made By Robert Prevost
 * Code takes in Max Velocity (mph) Min and Max angle (degrees & degrees)
 * Code outputs random velocity and angle and distance travelled according to those values
 * Code Written On: 9/3/2023
 */

#include <iostream>
#include <cstdlib>
#include <ctime>
#include <cmath>

using namespace std;
const double g = 32.0; //ft/sec

int main()
{
    srand(static_cast<unsigned>(time(nullptr)));
    int maxVelocity = 0; //mph
    int minAngle = 0; //degrees
    int maxAngle = 0;
    cout << "Please Input Max Velocity Followed by Min and Max Angle: ";
    cin >> maxVelocity >> minAngle >> maxAngle;
    cout << endl;
    int minVelocity = 0;
    double velocity = (rand() % (maxVelocity - minVelocity + 1)) + minVelocity;
    double angle = (rand() % (maxAngle - minAngle + 1)) + minAngle;

    double angleR = angle * M_PI / 180.0;
    double velocityFPS = (velocity * 5280.0) / 3600.0;
    double distanceTravelled = (pow(velocityFPS, 2.0) / g) * (sin(2.0 * angleR));

    cout.precision(3); //sets the output to be no more than 2 digits
    cout.setf(ios::fixed); //non-scientific notation
    cout.setf(ios::showpoint); //show the decimal point no matter what

    cout.width(20);
    cout.setf(ios::left); //left-justify the number
    cout << "Velocity(mph): ";
    cout.width(10);
    cout.setf(ios::right); //right-justify the number
    cout << velocity << endl;

    cout.width(20);
    cout << left;
    cout << "Angle (degrees): ";
    cout.width(10);
    cout.setf(ios::right); //right-justify the number
    cout << angle << endl;

    cout.setf(ios::right); //right-justify the number
    cout << angle << endl;

    cout.width(20);
    cout << left;
    cout << "Distance: ";
    cout.width(10);
    cout.setf(ios::right); //right-justify the number
    cout << distanceTravelled << endl;

    return 0;
}
```

Source Code Text:

/* Clown Cannon 2

* Code Made By Robert Prevost

* Code takes in Max Velocity (mph) Min and Max angle (degrees & degrees)

```
* Code outputs random velocity and angle and distance travelled according to those values
* Code Written On: 9/9/2023
*/
```

```
#include <iostream>
#include <cstdlib>
#include <ctime>
#include <cmath>
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```
using namespace std;
const double g = 32.0; //ft/sec
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int main()
{
    srand(static_cast<unsigned>(time(nullptr)));
    int maxVelocity = 0;//mph
    int minAngle = 0;//degrees
    int maxAngle = 0;
    cout << "Please Input Max Velocity Followed by Min and Max Angle: ";
    cin >> maxVelocity >> minAngle >> maxAngle;
    cout << endl;
    int minVelocity = 0;
    double velocity = (rand() % (maxVelocity - minVelocity + 1)) + minVelocity;
    double angle = (rand() % (maxAngle - minAngle + 1)) + minAngle;

    double angleR = angle*M_PI/180.0;
    double velocityFPS = (velocity * 5280.0) / 3600.0;
    double distanceTravelled = (pow(velocityFPS,2.0)/g) * (sin(2.0*angleR));

    cout.precision(3); //sets the output to be no more than 2 digits
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    cout.setf(ios::left); //left-justify the number
    cout << "Velocity(mph): ";
    cout.width(10);
    cout.setf(ios::right); //right-justify the number
    cout << velocity << endl;

    cout.width(20);
    cout << left;
    cout << "Angle (degrees): ";
    cout.width(10);
```

```
cout.setf(ios::right); //right-justify the number
cout << angle << endl;

cout.width(20);
cout << left;
cout << "Distance: ";
cout.width(10);
cout.setf(ios::right); //right-justify the number
cout << distanceTravelled << endl;

return 0;
}
```