



| NMRA Standard | |
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| Layout Command Control™ (LCC) Datagram Transport | |
| Apr 25, 2021 | S-9.7.3.2 |

Adopted as a NMRA Standard

The OpenLCB Standard document appended to this cover sheet has been formally adopted as a NMRA Standard by the NMRA Board of Directors on the date shown in the *Adopted* column in the *Version History* table below.

Version History

| Date | Adopted | Summary of Changes |
|--------------|---------------------|---|
| Feb 17, 2015 | | Initial version submitted for public comment |
| Feb 6, 2016 | Feb 20, 2016 | Minor grammatical corrections and readability improvements as well as the following specific changes: <ul style="list-style-type: none"> • 4.3 Datagram Rejected • 4.3.1 Error Codes • 6.1 Normal Transmission • 6.2 Rejected Transmission • 7.1 CAN Message Formats • 7.2 CAN States • 7.3.1 Normal Transmission • 7.3.2 Rejected Transmission |
| Apr 25, 2021 | July 2, 2021 | Changed LCC logo to include the ® symbol Changed “Layout Command Control” to have the ™ symbol Added the NMRA Legal Disclaimer fine-print Changed the OpenLCB license to “Creative Commons Attribution-ShareAlike 4.0 International” |
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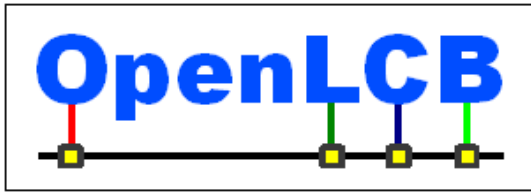
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OpenLCB Standard

Datagram Transport

Apr 25, 2021

Adopted

1 Introduction (Informative)

This standard defines the protocol for transporting OpenLCB datagrams.

2 Intended Use (Informative)

The datagram transport protocol is intended to efficiently transfer small amounts (0-72 bytes) of data reliably between two OpenLCB nodes. It allows for management of overlapping independent transmissions.

The datagram transport protocol relies on the underlying OpenLCB message transport protocol for reliable sequenced communications.

This document describes the required message formats for datagram transport. Section 4 gives an overview of the message types with an abstract numeric description intended as a normative guide to the construction of concrete message types over specific physical transport media. Section 7 describes, in concrete detail, the implementation of the datagram transport message formats for the specific physical transport media that have been adopted as normative standards.

3 References and Context (Normative)

This is in the context of the following OpenLCB Standards:

- The OpenLCB Message Network Standard, which defines the basic messages and how they interact. Higher-level protocols are based on this message network, but are defined elsewhere. The Message Network Standard defines the global error codes which are referenced here.
- The OpenLCB CAN Frame Transfer Standard, which specifies the use and format of CAN frames for OpenLCB communications.

4 Message Formats (Normative)

In the following, the “Common MTI” column specifies the the MTI value to be used when communicating in OpenLCB common format. The Common MTI is an abstract numeric description intended as a normative guide to the construction of concrete message formats over specific physical transport media.

4.1 Datagram Content

| Name | Simple Node | Dest ID | Event ID | Common MTI | Data Content |
|------------------|-------------|---------|----------|------------|--------------|
| Datagram Content | N | Y | N | 0x1C48 | 0-72 bytes |

The first byte of the data content defines the datagram type and is designated the Datagram Content ID. The values for that byte are documented in the Standard for the protocol that defines the type.

4.2 Datagram Received OK

| Name | Simple Node | Dest ID | Event ID | Common MTI | Data Content |
|----------------------|-------------|---------|----------|------------|----------------|
| Datagram Received OK | N | Y | N | 0x0A28 | Flags (1 byte) |

The flag bits are defined as:

- MSB 0x80 – Reply Pending – Use is defined by higher-level protocols.
 - Low four bits 0x0F – Timeout Value – Zero indicates no timeout value. A value N of 0x01 through 0x0F indicates that the pending reply will be transmitted before 2^N seconds have elapsed; if not, an error has occurred.
 - All others are reserved, shall be sent as zero and ignored upon receipt.
- Datagram Received OK messages without a Flags byte shall be treated as if they contained a byte with a zero value.

4.3 Datagram Rejected

| Name | Simple Node | Dest ID | Event ID | Common MTI | Data Content |
|-------------------|-------------|---------|----------|------------|---------------------------|
| Datagram Rejected | N | Y | N | 0x0A48 | Error Code, optional info |

The data contents are, in order:

- Two bytes of error code.
- Any extra bytes that the node wishes to include. There can be zero or more of these, to a maximum of 64 bytes. These shall be described in the node documentation.

Nodes shall accept and process Datagram Rejected messages that do not contain the full error code. Missing error code bits are to be interpreted as zero.

4.3.1 Error Code

- The Error Code field shall be in accordance with the Message Network Standard.

5 States (Normative)

The common OpenLCB datagram protocol has no formal states.

6 Interactions (Normative)

- 55 A node that receives a valid Datagram Content message shall send either a Datagram Received OK or Datagram Rejected message in reply. A node that receives a Datagram Content message that does not comply with this Standard may, but is not required to, reply with a Datagram Rejected message.

6.1 Normal Transmission

- 60 Normal transmission consists of the transmitting node sending a Datagram Content message to the receiving node, followed by the receiving node sending a Datagram Received OK message to the transmitting node. A node shall not send a second Datagram to the same receiving node before receiving a reply from the receiving node or a timeout occurs.

6.2 Rejected Transmission

- 65 After the transmitting node sends a Datagram Content message to the receiving node, the receiving node may send a Datagram Rejected message to the transmitting node.

Upon receipt of a Datagram Rejected message with a Temporary Error, the original transmitting node may resend the same Datagram Content message, or may abandon the transmission attempt.

- 70 Upon receipt of a Datagram Rejected message with a Permanent Error, the original transmitting node shall abandon the transmission attempt and not resend the original Datagram Content message.

7 Adaptation to CAN Transport (Normative)

This section describes the CAN implementation of the datagram transport message formats.

7.1 CAN Message Formats

- 75 The OpenLCB CAN Frame Transport Standard and OpenLCB Message Network Standard define how OpenLCB messages are carried across CAN networks. Following those standards, the Datagram Transport messages used on CAN are as defined in the following table.

| Name | CAN-MTI | Can Header | Data Content |
|----------------------|-------------------|---|--|
| Datagram Content | 0xdd ¹ | 0x1Add,dsss ² – Single ³ 0x1Bdd,dsss – First 0x1Cdd,dsss – Middle 0x1Ddd,dsss – Last | 0–8 bytes 0–8 bytes 1–8 bytes 0–8 bytes |
| Datagram Received OK | 0xA28 | 0x19A2,8sss | 0xfddd ⁴ , Flags |
| Datagram Rejected | 0xA48 | 0x19A4,8sss | 0xfddd, Error Code |

7.2 CAN States

80 A node implementing the OpenLCB-CAN datagram protocol shall maintain a Datagram-started state for each datagram that it is receiving as a sequence of frames. If the node receives multiple overlapping datagrams from different source nodes, the states shall be independent.

7.3 CAN Interactions

7.3.1 Normal Transmission

85 Normal transmission of a datagram over CAN consists of the transmitting node sending the Datagram Content message using one of two sequences of Datagram frames:

- One Datagram Content Single Frame
- One Datagram Content First Frame, followed by zero or more Datagram Content Middle Frame, followed by one Datagram Content Last Frame

90 A node shall not transmit frames with lower CAN priority between the frames making up a datagram. A node may, but is not required to, transmit frames with higher CAN priority between the frames making up a datagram.

A receiving node receiving either of the above sequences shall send either a Datagram Received OK or Datagram Rejected message in reply.

7.3.2 Rejected Transmission

95 If a receiving node receives a sequence of Datagram frames other than one of

- One Datagram Content Single Frame
- One Datagram Content First Frame, followed by zero or more Datagram Content Middle Frame, followed by one Datagram Content Last Frame⁵

¹ddd – The 12-bit destination alias field

²sss – The 12-bit source alias field

³Because CAN frames are limited to 8 bytes, datagrams larger than 8 bytes must be broken up among multiple messages. Thus, four distinct message types are defined to aid in flow control.

⁴fddd — First two bytes of the data-part, representing the 4-bit flag field and 12-bit destination Alias. See the OpenLCB-CAN Frame Transport Standard.

⁵The total payload bytes sent, including any First, Middle, and Last Frames, cannot exceed 72 bytes.

100 the receiving node shall send a Datagram Rejected message with a Temporary Error, indicating a resend is allowed.

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