



ROBERTTLANGE



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Visual-ML-Notes



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@SCIOI



@FORAI_ML

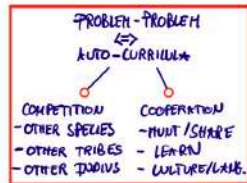


A Collection of Machine Learning Notes

a little bit of science - a little bit of art

T. Graepel (DeepMind): 'Automatic Curricula in Deep MARL'

HEIDER & SIMMEL [1958]



SOCIAL INTELLIGENCE HYPOTH.

SOCIAL COMPLEXITY = KEY SELECTION PRESSURE DUBBAR OF!



① ALPHA ZERO



→ POLICY NET: BREADTH ↓
→ VALUE NET: DEPTH ↓
P.V. / P.V. → SELF-PLAY DATA COLL.
REIN. LEARN. → LESS SEARCH

② CAPTURE-THE-FLAG



→ PBT + PROCEDURAL GEN.
DIVERSITY → META-OP. HYPERPARAMETERS
→ 2 TIME-SCALE RNN!
→ t-SNE → INTERNAL REPR.

③ SOCIAL DILEMMAS



→ SD = TIPPING POINT SELFISH.
→ STABLE COOPER. EMERGENCE
→ COMMON POOL RESOURCES
→ EMERGENT SOCIAL OUTCOMES!

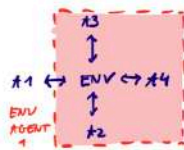
INTELLIGENCE $\Rightarrow Y(\pi) = \sum_{\pi \in \Pi} \sum_{k \in K} \gamma^k \pi^k$
MULTI-AGENT: IMPORTANCE APPLICATIONS ARCHITECTURES
① AUTO-CURRICULUM!

WHO IS REALLY INTELLIGENT? \Rightarrow CIVILISATION?
 \Rightarrow COMPANY AS NECESSARY INGREDIENT!

WHAT MAKES A RICH LEARNING ENV? \Rightarrow MARL

- 1) AGENT EXPERIENCES OTHER AGENTS AS PART OF ENV DYNAM.
- 2) DYNAMICS ARE NON-STAT. \Rightarrow OTHERS LEARN!
- 3) OTHER AGENT'S LEARNING = NEW TRAINING TASK

AUTO-CURRICULUM THROUGH MULTI-AGENT RL



- EXPLORE BY EXPLOIT \rightarrow PUSHED INTO
- DIVERSE POPULATION \rightarrow COVER SPACE
- SKILL-BASED MATCH MAKING \rightarrow BALANCE FOR ROBUSTNESS

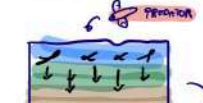
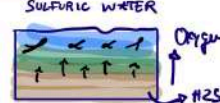
D. Bierbach (HU Berlin): Robofish - to Biomimetic fish-like robots for the study of collective behavior

WHY/HOW DO ANIMALS PERFORM COLLECTIVE BEHAVIOR?

FUNCTION: COPE W. PREDATOR

- ① DILUTION OF RISK
- ② ENHANCED VIGILANCE
- ③ PREDATOR DETERRENCE

Mexico System
Posidonia Sulphurina



EFFECT: WHY?!

ESCAPE SUCCESS ATTACK FREQ. ↓



SYNCHRONIZED DIVING BEHAVIOR AFTER BIRD ATTACK

TOP-VIEW!

COMBINE AL. 02! ZONE-BASED M.



OPEN LOOP

COLLECTIVES OF INDIVIDUALS \rightarrow PROBLEM OF HETEROGENEITY \rightarrow NOT EASY TO CONTROL!

OBSERV. IS NOT ENOUGH \rightarrow NEED MANIPULATION

CLOSED LOOP

HOW?!

ROBO-FISH

- 2D pool
- GLASS FLOOR

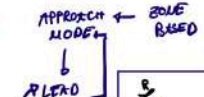
CRUCIAL FOR ACCEPTANCE

ADAPT INTERACTION RULES ON THE FLY



Path following \Rightarrow to Lukas et al. 2011

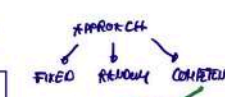
Indiv. Differences \rightarrow consistent over time \rightarrow Bierbach et al. 18!



APPROACH MODE

INDIV. DIFF. IN HOW OFTEN TO APPROACH

1 von 1



APPROACH

ADAPTION IS KEY

INTEGRATE REACTION EVIDENCE

SIGNIFICANTLY FASTER LEADERSHIP!

K. Saxe (UofOx): 'A Normative Theory of how Hippocampal-Neocortical Interactions Consolidate Memory'

MEMORY DEC. HERE! NON-DEC.



STUDENT-TEACHER + NOTEBOOK SETUP

TEACHER / ENV \rightarrow GEN. MODEL \rightarrow LUSHER NET \rightarrow S-D

STUDENT \rightarrow 'NEOCORTIX' \rightarrow SLOW \rightarrow LINEAR NET \rightarrow S-D

NOTEBOOK \rightarrow (HIPPOCAMPUS) \rightarrow FAST \Rightarrow HOPFIELD \rightarrow ONE-SHOT MEMS.

① REPLAY W. LEARNING [BATCH 50]

$\epsilon = \frac{\# \text{ SAMPLES}}{\# \text{ HIDDEN}} \rightarrow$

DYNAMICS

FORGET INIT

OVERFIT NOISE

DEPENDS ON 2 DISK. \Rightarrow GAUSSIAN W

MARCHENKO - PACHUR



WORST CASE: $\alpha = 0$

② ONLINE LEARNING DYNAMICS

FORGET INIT

WANDER NEAR MIN.

CAN'T OVERFIT to each point new! \Rightarrow break 'wiggle'!

PREDICTABILITY OF ENV

GEN. ENV. HIGH- α

LOW- α

PRED. UNPRED.

RETRICAL

③ LEARNING VIA MEMORIZATION

NEAREST NEIGHB.

\rightarrow FALLS IN HIGH-D.

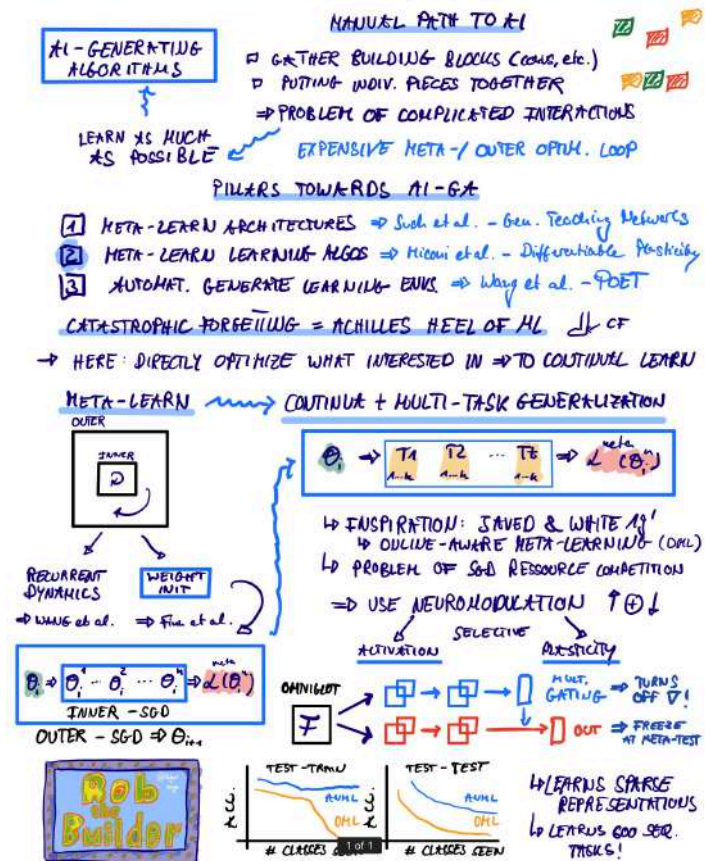
HEBBIAN L. INTERFERENCE

\Rightarrow REPLAY ONLY WHEN IT NEEDS TO GENERALIZE



The Emergence of a Sketch Note

Jeff Clune (OpenAI): 'Learning to continually learn'



iPad Pro 12.9'

Notability/GoodNotes

One theme color

Put your name on it

Iterate & find your style

A Timeline of how I got started...

10/2019

My 1st note.

12/2019

NeurIPS euphoria.

12/2019

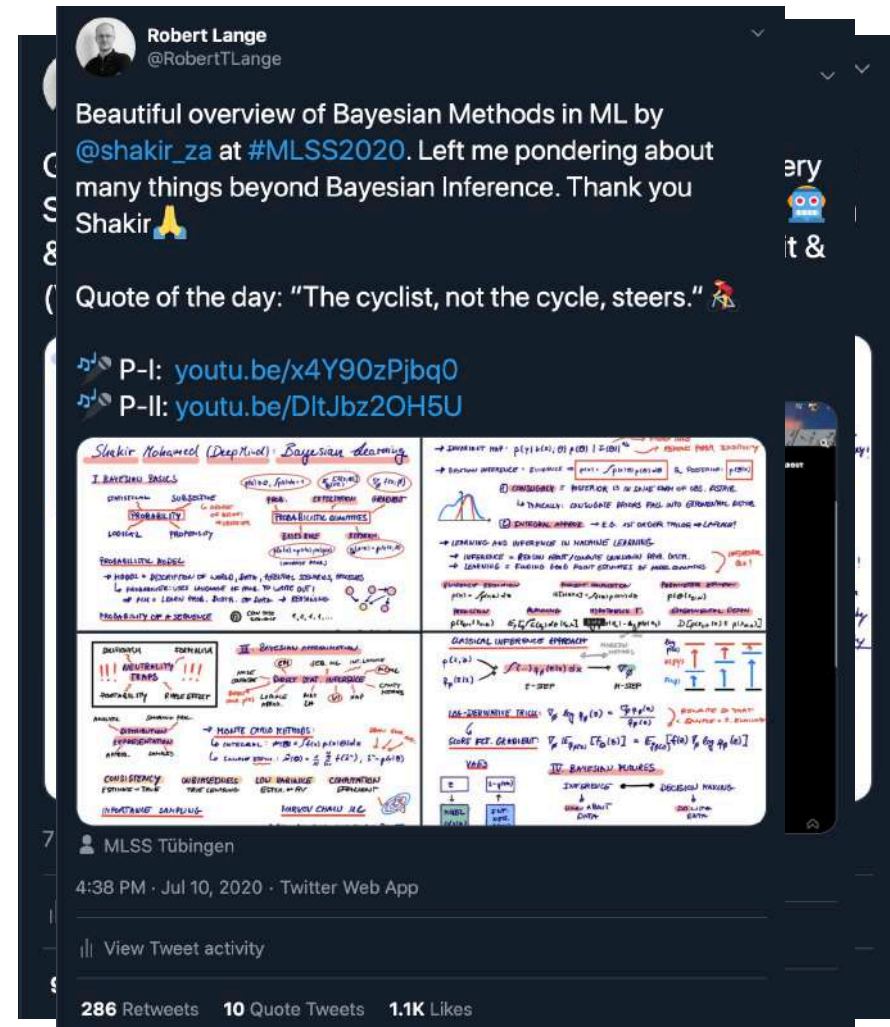
GitHub repository.

05/2020

Website Launch.

07/2020

Cracking 1000 Likes.



You can combine sketching with anything...

Blogposts

Poems



Sketch Notes



Notability

Thumbnails



Procreate

Blogs/Mini-Projects



Raspberry Pi 4B

Remote Jupyter



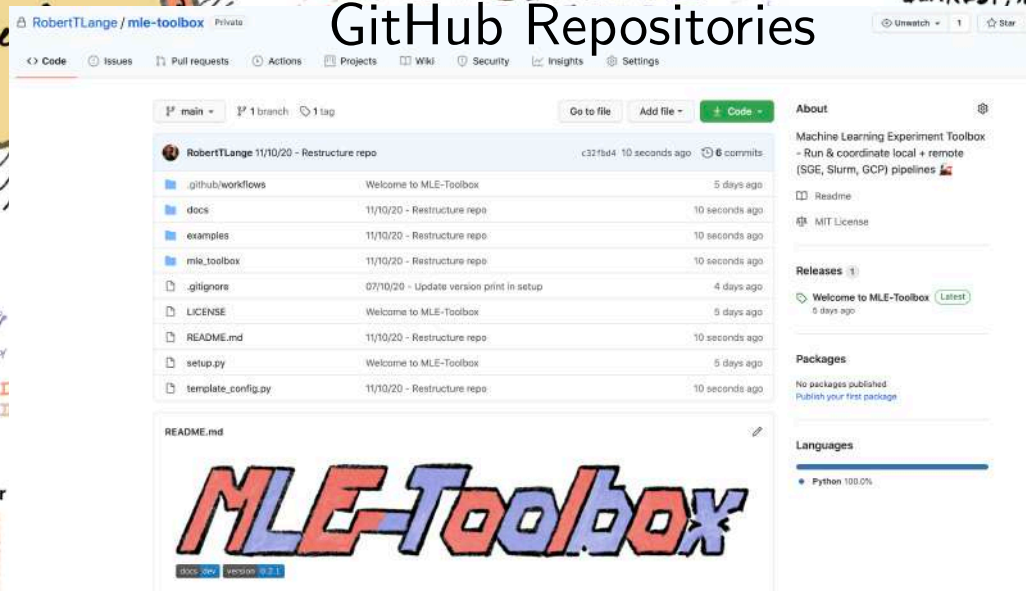
Juno Connect



Working Copy



GitHub Repositories



- MACHINES -

BY MICHAEL DONAGHY (2000)

DEAREST, NOTE HOW THESE TWO ARE ALIKE:
ORD PAVANE BY PURCELL
LER'S TWELVE-SPEED BIKE.

OF GRACE IS ALWAYS SIMPLE.

RAPEZOID, ONE WHEEL CONNECTED
= CONCENTRIC GEARS,
I DREAMT OF 2 SCHWINN PERFECTED,
CYCLIST, NOT THE CYCLE, STEERS.
LYING, PURCELL'S CHORUS ARE PLAYED

K, OR TONK IF I WERE THERE,
ITS EFFORTLESS GADGETRY OF LOVE,
HEAVEN, AND HELT INTO THE AIR.

OF COURSE, I'VE FALLN. SO MUCH IS

RY, DESIRE, AND FEVERISH CARE,
AND HARPSICHORDISTS PROVE

MOVING CAN BALANCE,
ONLY BY BALANCING MOVE.

A Couple of Personal Takeaways

- ① Use your PhD to build your brand.
- ② You need a Twitter account.
- ③ The iPad is an awesome investment.
- ④ Positive energy attracts positivity.
- ⑤ Be individual and consistent.