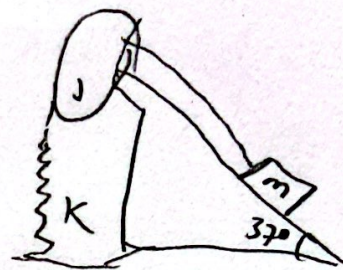


3.13

$$k=20\text{ N/m} \quad J=0.5\text{ kg}\cdot\text{m}^2 \quad \text{半径 } r=30\text{ cm} \\ m=2.0\text{ kg}$$



机械能守恒定律有

$$0 = \frac{1}{2} k x_m - m g x_m \sin \theta$$

得物体能沿斜面滑下的最大距离为

$$x_m = \frac{2 m g \sin \theta}{k} = 1.18\text{ m}$$

当沿斜面滑下 1.00 m

$$0 = \frac{1}{2} k x_0 - m g x_0 \sin \theta + \frac{1}{2} m v^2 + \frac{1}{2} J \omega^2$$

$$v = \sqrt{\frac{2 m g x_0 \sin \theta - k x_0}{m + \frac{1}{2} \frac{J}{r^2}}} = 0.69\text{ m/s}$$

$$\frac{2(2)(9.8) \sin(37^\circ) - 20}{2 + \frac{1}{0.3^2}} = 0.69\text{ m/s}$$

3.14

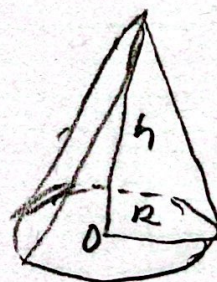
$$J \omega = (J + m R^2) \omega$$

$$m g h + \frac{1}{2} J \omega^2 = \frac{1}{2} m v^2 + \frac{1}{2} J \omega^2$$

$$\omega = \frac{J}{J + m R^2} \omega$$

$$v = \sqrt{\frac{J}{m} (\omega_0^2 - \omega^2) + 2 g h}$$

$$= \sqrt{\frac{(2 J + m R^2) J R^2 \omega^2}{(J + m R^2)^2} + 2 g h}$$



3,15

$$L = (J + mR^2) \omega \quad (\text{人站在盘边缘})$$

$$L' = J\omega' \quad \text{走到盘心}$$

角动量守恒 $(J + mR^2) \omega = J\omega'$

$$\omega' = \frac{J + mR^2}{J} \omega$$

角速度

$$\Delta \omega = \omega' - \omega = \frac{mR^2}{J} \omega$$

系. 转动动能

$$\Delta E_k = \frac{1}{2} J\omega'^2 - \frac{1}{2} (J + mR^2) \omega^2$$

$$\omega^2 = \frac{1}{2} \frac{J + mR^2}{J} mR^2 \omega^2$$



扫描全能王 创建

$$3.21 \quad m=60\text{kg} \quad l=10\text{m}$$

$$m'=500\text{kg} \quad 3\text{m/s}$$

$$0 = mv + m'v'$$

$$v = \frac{m}{m'} v' = -0.36\text{m/s}$$

$$\frac{60}{500} 3\text{m/s} \nearrow$$

运动方向与人跳离竹筏的方向相反

$$0 = mv \frac{1}{2} + J\omega$$

$$J_c = \frac{1}{12} ml^2 \quad \text{转动惯量}$$

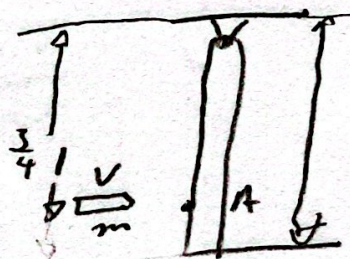
$$\text{角速度为 } \omega = \frac{6m}{m'l} v = -0.216\text{rad/s}$$

3.22

$$m'=1\text{kg} \quad v=200\text{m/s}$$

$$l=0.40\text{m}$$

$$m=3\text{g}$$



$$(1) \quad l_0 = \frac{3}{4} l m v \quad (\text{A点与O点的距离})$$

$$\text{角动量为 } L = J\omega = \left[m \left(\frac{3}{4} l \right)^2 + \frac{1}{3} m' l^2 \right] \omega$$

$$\text{角动量守恒 } \omega = \frac{3mv}{45} = 2.89\text{rad/s}$$

(2) 棒的最大偏转角

$$h_1 = \frac{1}{2} l - \frac{1}{2} l \cos \theta$$

$$\text{子弹上升的高度 } h_2 \text{ 为 } h_2 = \frac{3}{4} l - \frac{3}{4} l \cos \theta$$

到最大摆角时,重力做功而系统静止

$$-mgh_2 - m'gh_1 = 0 - \frac{1}{2} J\omega^2$$

$$\cos \theta = \frac{2m'gl + 3mgl - 2J\omega^2}{2m'gl + 3mgl} = -0.076$$

$$\theta = 94^\circ 21'$$

