

$$1. \quad \overline{x(t)} = m_x \quad \overline{x(t+\tau)x(t)} = R_x(\tau)$$

时间平均 = 集平均.

P71.

2. 积分系统. P104. 均值  $\rightarrow$   $ct$

3. ①. 证互不相关  $x(t)$ .  $y(t) = \dot{x}(t)$

$$\begin{aligned} \text{证 } E[x(t)\dot{x}(t)] &= E\left[x(t) \lim_{\epsilon \rightarrow 0} \frac{x(t+\epsilon) - x(t)}{\epsilon}\right] = \lim_{\epsilon \rightarrow 0} E\left[x(t) \frac{x(t+\epsilon) - x(t)}{\epsilon}\right] \\ &= R'(0) = 0 \end{aligned}$$

高斯: 互不相关 = 独立.

$$4. \quad \Delta\omega_e \cdot \tau_0 = \frac{2\pi}{4}$$

$$\begin{aligned} \Delta\omega_e &= \frac{\int_0^\infty S_Y(\omega) d\omega}{S_Y(\omega_0)} \quad \text{等效通频带} \quad P119 \\ &= \frac{\int_0^\infty |H(j\omega)|^2 d\omega}{|H(0)|^2} \end{aligned}$$

$$\text{相关时间: } r_x(\tau) = \frac{C_x(\tau)}{C_x(0)} = \frac{R_x(\tau) - m_x^2}{\sigma_x^2}$$

P64

$$\tau_0 = \int_0^\infty r(\tau) d\tau$$

$$\text{关系: } \Delta\omega_e \cdot \tau_0 = \frac{2\pi}{4}$$

$$\Delta f \cdot \tau_0 = \frac{1}{4}$$



5.  $\tilde{x}(t) = x(t) + j\hat{x}(t)$

$$G_{\tilde{x}}(\omega) = 2[G_x(\omega) + j\hat{G}_x(\omega)]$$

$$= \begin{cases} 0 & , \omega < 0 \\ 2G_x(\omega) & , \omega = 0 \\ 4G_x(\omega) & , \omega > 0 \end{cases}$$

6. 题 6.3.

7. 对于马尔科夫链,  $k$  步转移概率满足:

$$P_{ij}^{(m+r)}(n) = \sum_{k \in S} P_{ik}^{(m)}(n) \cdot P_{kj}^{(r)}(n+m)$$

对于马尔可夫链, 如果知道其初始分布及转移概率, 则它的有限维分布可完全确定。

二. (1).  $m_z(t) = E[z(t)] = E\left[\sum_{k=1}^m A_k e^{j\omega_k t}\right] = 0$

$$C(t_1, t_2) = E\{[z(t_1) - m_z][z(t_2) - m_z]^*\} = E[z(t_1) z^*(t_2)]$$

$$= E\left[\sum_{i=1}^m A_i e^{j\omega_i t_1} \cdot \sum_{j=1}^m A_j e^{-j\omega_j t_2}\right]$$

$$= E\left[\sum_{i=1}^m A_i^2 e^{j\omega_i(t_1 - t_2)}\right]$$

$$= \sum_{i=1}^m e^{j\omega_i \tau}$$

(2).  $\psi^2 = E[z^2(t)] = \sum_{i=1}^m e^{j\omega_i \tau} \Big|_{\tau=0} = m$

(3).  $R_{\tilde{x}}(t, t-\tau) = \sum_{i=1}^m e^{j\omega_i \tau} \quad m_{\tilde{x}} = 0$

是平稳随机过程



题 2.18

$$\begin{aligned} \text{三. 1. } R_x(t, t-\tau) &= E\{[U\cos\omega_0 t + V\sin\omega_0 t][U\cos\omega_0(t-\tau) + V\sin\omega_0(t-\tau)]\} \\ &= E[U^2\cos\omega_0 t\cos\omega_0(t-\tau) + UV\sin\omega_0(t-\tau)\cos\omega_0 t \\ &\quad + UV\sin\omega_0 t\cos\omega_0(t-\tau) + V^2\sin\omega_0 t\sin\omega_0(t-\tau)] \\ &= \cos\omega_0 \tau \end{aligned}$$

同理  $R_Y(\tau) = \cos\omega_0 \tau$

$$\begin{aligned} \text{2. } R_{XY}(t_1, t_2) &= E[(U\cos\omega_0 t_1 + V\sin\omega_0 t_1)(U\sin\omega_0 t_2 + V\cos\omega_0 t_2)] \\ &= E[\cancel{U^2\cos\omega_0 t_1\sin\omega_0 t_2} + \cancel{UV\cos\omega_0 t_1\sin\omega_0 t_2} + \cancel{UV\sin\omega_0 t_1\cos\omega_0 t_2} \\ &\quad + \cancel{V^2\sin^2\omega_0 t_1}] \\ &= E[U^2\cos\omega_0 t_1\sin\omega_0 t_2 + UV\cos\omega_0 t_1\cos\omega_0 t_2 + UV\sin\omega_0 t_1\sin\omega_0 t_2 \\ &\quad + V^2\sin\omega_0 t_1\cos\omega_0 t_2] \\ &= \sin\omega_0(t_1 + t_2) \end{aligned}$$

不是广义平稳联合平稳.. 无法求互功率谱密度

3.  $m_X = m_Y = 0$

$$C = \begin{bmatrix} E[X^2(t)] & E[X(t)Y(t)] \\ E[Y(t)X(t)] & E[Y^2(t)] \end{bmatrix} = \begin{bmatrix} 1 & \sin\omega_0 2t \\ \sin\omega_0 2t & 1 \end{bmatrix}$$

$$P_{XY}(x, y) = \frac{1}{2\pi |C|^{\frac{1}{2}}} \cdot \exp\left\{-\frac{1}{2} [x, y] C^{-1} \begin{bmatrix} x \\ y \end{bmatrix}\right\}$$





四. 1.  $R_{Y_1 Y_2}(\tau) = R_X(\tau) * h_1(\tau) * h_2(-\tau)$

$$S_{Y_1 Y_2}(\omega) = S_X(\omega) \cdot H_1(j\omega) \cdot H_2^*(j\omega)$$

2.  $H_1(j\omega) \cdot H_2^*(j\omega) = 0$ . 通频带不重叠.

$$\begin{cases} \omega_1 + \frac{B}{2} < \omega_2 - \frac{B}{2} \\ \omega_1 - \frac{B}{2} > \omega_2 + \frac{B}{2} \end{cases} \rightarrow \begin{cases} \omega_2 - \omega_1 < -B \\ \omega_2 - \omega_1 > B \end{cases} \rightarrow |\omega_2 - \omega_1| > B$$

3.  $r_{Y_1 Y_2} = \frac{R_{Y_1 Y_2}(0)}{\sqrt{\sigma_{Y_1}^2 \sigma_{Y_2}^2}}$

$R_X(\tau) = \delta(\tau)$ .  $S_X(\omega) = 1$

$$S_{Y_1}(\omega) = \begin{cases} 1 & |\omega \pm \omega_1| < \frac{B}{2} \\ 0 & \text{else} \end{cases}$$

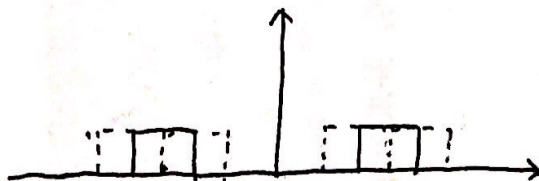
$$\sigma_{Y_1}^2 = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S_{Y_1}(\omega) d\omega = \frac{1}{2\pi} \cdot 2B = \frac{B}{\pi}$$

同理  $\sigma_{Y_2}^2 = \frac{B}{\pi}$

$$r_{Y_1 Y_2} = \frac{R_{Y_1 Y_2}(0)}{\frac{B}{\pi}} = \frac{1}{2}$$

$$\frac{1}{2\pi} \int_{-\infty}^{+\infty} H_1(j\omega) H_2^*(j\omega) d\omega = \frac{B}{2\pi}$$

$$\int_{-\infty}^{+\infty} H_1(j\omega) H_2^*(j\omega) d\omega = B$$



$$\omega_1 + \frac{B}{2} = \omega_2$$

$$|\omega_2 - \omega_1| = \frac{B}{2}$$

$$\omega_1 - \frac{B}{2} = \omega_2$$



五. 1.  $m_w = E[W(t)] = \int_0^t m_x(s) ds = 0$

2.  $R_w(t_1, t_2) = E\left[\int_0^{t_1} \int_0^{t_2} X(s)X(\lambda) ds d\lambda\right] = \int_0^{t_1} \int_0^{t_2} E[X(s)X(\lambda)] ds d\lambda$

$= \int_0^{t_1} \int_0^{t_2} R_x(s, \lambda) ds d\lambda$

$R_x(\tau) = \delta(\tau)$

①  $t_1 < t_2$   $R_r(t_1, t_2) = t_1$

②  $t_1 > t_2$   $R_r(t_1, t_2) = t_2$

$R_r(t_1, t_2) = \min(t_1, t_2)$

③.  $W(t_1) - W(t_2)$

$E[W(t_1) - W(t_2)] = 0$

$E\{[W(t_1) - W(t_2)]^2\} = E[W^2(t_1) - 2W(t_2)W(t_1) + W^2(t_2)]$

$= t_1 + t_2 - 2\min(t_2, t_1)$

