## The Porous Medium Equation

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18 June 2010

Flow of an ideal gas through a homogeneous porous medium can be described by

$$\begin{cases} \varepsilon \partial_t \rho + \operatorname{div}(\rho \mathbf{v}) &= 0 & \text{mass balance} \\ \mu \mathbf{v} &= -k \nabla \mathbf{p} & \text{Darcy's law} \\ \mathbf{p} &= \mathbf{p_0} \ \rho^{\gamma} & \text{state equation} \end{cases}$$

$$arepsilon \partial_t 
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ho: density

p : pressure

▶ **v** : velocity

 $\triangleright$   $\varepsilon$ , k,  $\mu$  > 0 : material constants

ho  $\gamma \geq$  1 : polytropic exponent

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#### **Definition**

The porous medium equation (PME) is

$$\partial_t u(t,x) = \Delta_x u^m(t,x), \ u \geq 0, \ m > 1 \quad (t,x) \in (0,\infty) \times \mathbb{R}^n$$

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#### Let

- ▶ *u* a classical solution of the PME in  $(0, \infty) \times \mathbb{R}^n$
- ▶  $\alpha, \beta > 0$  constants with  $\alpha(m-1) + 2\beta = 1$

#### Define for $\lambda > 0$

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#### Define for $\lambda > 0$

 $U_{\lambda}(t,x) := \lambda^{\alpha} u(\lambda t, \lambda^{\beta} x) \Rightarrow \partial_{t} u_{\lambda} - \Delta u_{\lambda}^{m} = 0$ 

#### Idea

Scaling  $u \to u_{\lambda}$  maps solutions of the PME to other solutions. Find a **scaling invariant** solution, that is  $u_{\lambda} = u$  for all  $\lambda > 0$ .

#### **Ansatz**

$$U(t,x) = t^{-\alpha}U(1,t^{-\beta}x) =: t^{-\alpha}V(t^{-\beta}x), \quad V: \mathbb{R}^n \to \mathbb{R}$$

### Reduction to one space variable

$$0 = -t^{\alpha+1}(\partial_t u - \Delta u^m) = \alpha v(t^{-\beta}x) + \beta Dv(t^{-\beta}x) \cdot t^{-\beta}x + \Delta v^m(t^{-\beta}x)$$

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ightharpoonup v is radial, *i.e.*  $v(y) = w(|y|) := w(r), \quad w : \mathbb{R} \to \mathbb{R}$ 

$$0 = r^{n-1} (\alpha v(y) + \beta D v(y) \cdot y + \Delta v^{m}(y))$$
  
=  $(\alpha r^{n-1} w + \beta r^{n} \partial_{r} w) + (r^{n-1} \partial_{r}^{2} w^{m} + (n-1)r^{n-2} \partial_{r} w^{m})$ 

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 $=\beta\partial_r(r^nw)$ 

#### **Ansatz**

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$$\partial_r w^{m-1} = -\frac{m-1}{m} \beta r \implies w^{m-1} = C - \frac{m-1}{2m} \beta r^2, \ C > 0$$

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$$u(t,x) = t^{-\alpha} \left( \left( C - \frac{\beta(m-1)}{2m} \frac{|x|^2}{t^{2\beta}} \right)^+ \right)^{\frac{1}{m-1}}$$

### Barenblatt's solution

#### **Definition**

Let  $\alpha = \frac{n}{n(m-1)+2}$ ,  $\beta = \frac{\alpha}{n}$ , C > 0. Barenblatt's solution to the PME is

$$U_m(t,x;C):=t^{-\alpha}\left(\left(C-\frac{\beta(m-1)}{2m}\frac{|x|^2}{t^{2\beta}}\right)^+\right)^{\frac{1}{m-1}}$$

It is also known as **ZKB solution** in literature.

- ▶  $U_m$  is a smooth solution where  $U_m > 0$
- Finite propagation speed
- Non-smoothness on  $|x| = t^{\beta} \left( \frac{C}{\beta} \frac{2m}{(m-1)} \right)^{\frac{1}{2}} =: r(t)$  for  $m \ge 2$
- Scaling invariance
- Which role does C play?

### Elimination of the free parameter

### Lemma (Mass conservation)

Fix C > 0. As a map  $(0, \infty) \to L^1(\mathbb{R}^n)$ ,  $U_m$  is mass preserving, i.e.  $M := \|U_m(t, \cdot; C)\|_{L^1(\mathbb{R}^n)}$  is independent of t and is called **mass** of  $U_m$ .

#### **Proof**

- Let  $t_1, t_2 > 0$  and  $\lambda = \frac{t_1}{t_2}$
- ▶ Scaling invariance:  $U_m(t_1, x; C) = \lambda^{\alpha} U_m(t_2, \lambda^{\beta} x; C)$
- $\|U_m(t_1,\cdot;C)\|_1 = \lambda^{\alpha}\lambda^{-n\beta} \|U_m(t_2,\cdot;C)\|_1 = \|U_m(t_2,\cdot;C)\|_1$

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### Definition (Mass as parameter)

Let  $\gamma = \frac{1}{m-1} + \frac{n}{2}$ . The mass M and the free parameter C are related by

$$M = a(m, n) \cdot C^{\gamma}$$

Write  $U_m(t, x; M)$  for Barenblatt's solution with mass M.

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$$M = a(m,n) \cdot C^{\gamma} = \pi^{\frac{n}{2}} \cdot \left(\frac{m\alpha - m}{2mn}\right)^{-\frac{n}{2}} \cdot \frac{\Gamma(\frac{m}{m-1})}{\Gamma(\frac{m}{m-1} + \frac{n}{2})} \cdot C^{\gamma}$$

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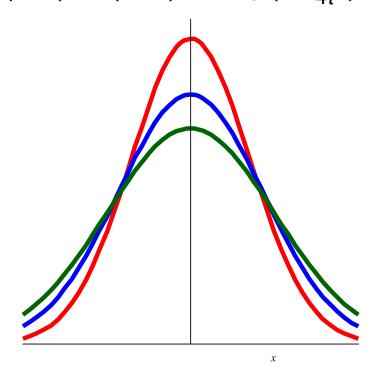
### Comparison to the heat equation

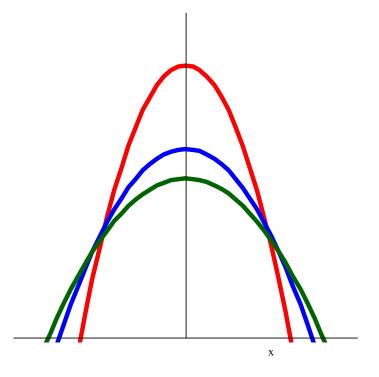
#### Note

For m = 1 the PME becomes the heat equation

$$\partial_t u - \Delta u = 0$$
 (HE)

Fundamental solution for the HE given by the Gaussian kernel  $G(t,x)=(4\pi t)^{-\frac{n}{2}}\exp(-\frac{|x|^2}{4t})$ 





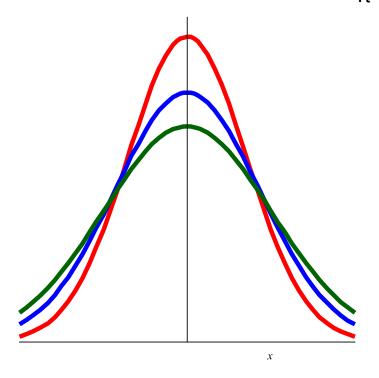
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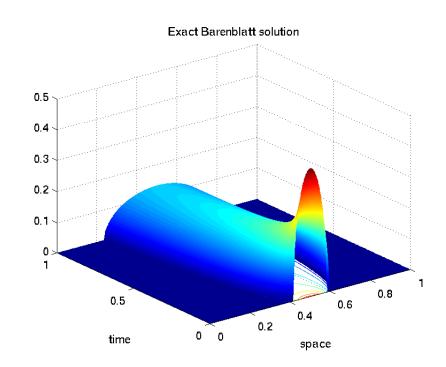
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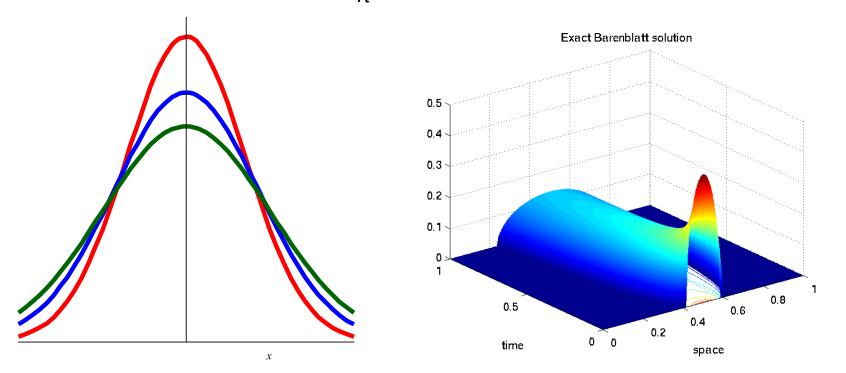
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What happens to Barenblatt's solution in the limit  $m \rightarrow 1$ ?

# Asymptotics of Barenblatt's solution

#### **Theorem**

Let  $U_m(t, x; M)$  Barenblatt's solution with mass M. We have the limits

$$\lim_{\substack{t\to 0\\ m\to 1}} U_m(t,\cdot M) = M\delta_0 \quad \text{in the sense of distributions}$$

#### **Proof**

- ▶ supp  $U_m(t, \cdot; M) \subseteq B(0, t^{\beta} \left(\frac{C}{\beta} \frac{2m}{(m-1)}\right)^{\frac{1}{2}})$
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$$\lim_{\substack{t\to 0\\ m\to 1}} U_m(t,x;M) = MG(t,x) \quad \text{pointwise on } (0,\infty)\times\mathbb{R}^n$$

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- ▶ By mass preservation:  $\lim_{t\to 0} U_m(t,\cdot M) = M\delta_0$
- Limit for  $m \rightarrow 1$  is a truly marvelous calculation but this margin is to narrow to contain it

# The Cauchy Dirichlet problem (CDP)

#### Let

- $\Omega \subseteq \mathbb{R}^n$  bounded with  $\partial \Omega$  smooth,  $T \in (0, \infty]$
- $ightharpoonup Q := \mathbb{R}_+ imes \Omega, \ Q_T := (0, T) imes \Omega$
- $u_0 \in L^1(\Omega), f \in L^1(Q)$
- $\Phi \in C(\mathbb{R})$  strictly increasing with  $\Phi(\pm \infty) = \pm \infty$ ,  $\Phi(0) = 0$

#### Consider

$$(CDP) \begin{cases} \partial_t u - \Delta(\Phi(u)) &= f & \text{in } Q_T \\ u(0,x) &= u_0(x) & \text{in } \Omega \\ u(t,x) &= 0 & \text{on } [0,T) \times \partial \Omega \end{cases}$$

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- $ightharpoonup Q := \mathbb{R}_+ imes \Omega, \ Q_T := (0, T) imes \Omega$
- $u_0 \in L^1(\Omega), f \in L^1(Q)$
- ullet  $\Phi \in C(\mathbb{R})$  strictly increasing with  $\Phi(\pm \infty) = \pm \infty$ ,  $\Phi(0) = 0$

#### Consider

$$(CDP) \begin{cases} \partial_t u - \Delta(\Phi(u)) &= f & \text{in } Q_T \\ u(0,x) &= u_0(x) & \text{in } \Omega \\ u(t,x) &= 0 & \text{on } [0,T) \times \partial \Omega \end{cases}$$

▶ Choose  $\Phi(u) = |u|^{m-1}u$  and f = 0 for the PME

#### **Definition**

A weak solution of CDP in  $Q_T$  is a function  $u \in L^1(Q_T)$  s.t.

- **1**  $w := \Phi(u) \in L^1(0, T; W_0^{1,1}(\Omega))$

holds for any  $\eta \in C^1(\overline{Q_T})$  which vanishes on  $[0, T) \times \partial \Omega$  and for t = T

- Integration by parts shows: smooth solutions are weak solutions
- What about initial data...?

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- Integration by parts shows: smooth solutions are weak solutions
- What about initial data...?
- ▶ satisfied in the sense that for any  $\varphi \in C^1(\overline{\Omega})$  with  $\varphi = 0$  on  $\partial\Omega$

$$\lim_{t\to 0}\int\limits_{\Omega}u(t)\varphi\,dx=\int\limits_{\Omega}u_0\varphi\,dx$$

### A well-known weak solution

### Modify Barenblatt's solution

- ▶ Take  $x_0 \in \Omega$ ,  $\tau > 0$
- ► Set  $v(t,x) := U_m(t + \tau, x x_0; M)$
- ▶ Let T > 0 be small enough so that v = 0 on  $[0, T) \times \partial \Omega$

#### **Theorem**

Define v(t,x) as above. Then v is a weak solution of the CDP for the PME in  $Q_T$ . If  $m \ge 2$ , then v is not a classical solution of that problem.

#### **Proof**

- v has the stated regularity
- ▶ Let  $P := \{(t, x) \in Q_T \mid v(t, x) > 0\}$
- ightharpoonup v is smooth solution within P and  $v^m$  is  $C^1$  up to |x| = r(t)
- Integration by parts yields the integral equality (2)