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A review: GPU parallelism and CUDA architecture

Beginning CUDA C

Skeleton program Simple program Vector addition Pairwise summation Respecting the SIMI paradism

Introduction to programming in CUDA C

Will Landau

Iowa State University

September 30, 2013

Outline

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SIMD: apply the same command to multiple places in a dataset.

```
1 for(i = 0; i < 1e6; ++i)
2 a[i] = b[i] + c[i];
```

- On CPUs, the iterations of the loop run sequentially.
- With GPUs, we can easily run all 1,000,000 iterations simultaneously.

```
1 | i = threadIdx.x;
2 | a[i] = b[i] + c[i];
```

▶ We can similarly *parallelize* a lot more than just loops.

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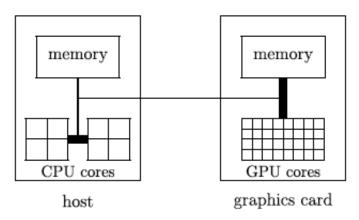
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CPU / GPU cooperation

- ► The CPU ("host") is in charge.
- The CPU sends computationally intensive instruction sets to the GPU ("device") just like a human uses a pocket calculator.



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- 2. The GPU executes several duplicate realizations of this command, called **threads**.
 - ► These threads are grouped into bunches called **blocks**.
 - The sum total of all threads in a kernel is called a grid.
- Toy example:
 - ► CPU says: "Hey, GPU. Sum pairs of adjacent numbers. Use the array, (1, 2, 3, 4, 5, 6, 7, 8)."
 - GPU thinks: "Sum pairs of adjacent numbers" is a kernel.
 - ▶ The GPU spawns 2 blocks, each with 2 threads:

| Block | 0 | | 1 | |
|--------|-------|-------|-------|-------|
| Thread | 0 | 1 | 0 | 1 |
| Action | 1 + 2 | 3 + 4 | 5 + 6 | 7 + 8 |

▶ I could have also used 1 block with 4 threads and given the threads different pairs of numbers.

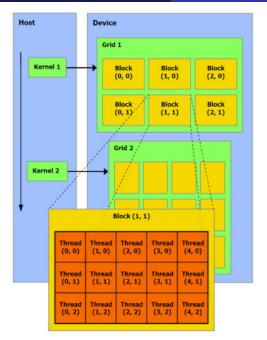
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CUDA: making a gaming toy do science

- **CUDA**: Compute Unified Device Architecture.
- Before CUDA, programmers could only do GPU programming in graphics languages, which are appropriate for video games but clumsy for science.
- CUDA devices support CUDA C, an extension of C for programs that use GPUs.
- CUDA-enabled servers at Iowa State:
 - impact1.stat.iastate.edu
 - ▶ impact2.stat.iastate.edu
 - ▶ impact3.stat.iastate.edu
 - impact4.stat.iastate.edu (in the works...)

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Hello world

Hello world

A beginner C program:

```
#include <stdio.h>
2
  int main(){
4
    printf("Hello, World!\n");
5
    return 0:
```

A beginner CUDA C program:

```
#include <stdio.h>
1
2
3
4
5
   __global__ void myKernel(){
 6
   int main(){
     mvKernel <<<1, 1>>>():
 8
     printf("Hello, World!\n");
9
     return 0:
10 }
```

Beginning CUDA

Hello world

Hello world

```
#include <stdio.h>
2
3
4
   __global__ void myKernel(){
5
  int main(){
     myKernel <<<2, 4>>>();
8
     printf("Hello, World!\n");
     return 0:
10 }
```

- __global__ says that the function is a kernel, which
 - will be executed on the GPU by one or more simultaneous threads when called.
 - must return void
- <<<2, 4>>> specifies
 - number of blocks (first number)
 - number of threads per block (second number).

- __host__
 - Runs once per call on the CPU.
 - Only callable from the CPU (i.e., from another host function).
 - ▶ All functions without explicit prefixes are host functions.
- __global__
 - Used to specify a kernel.
 - Runs multiple times per call on the GPU (that's what <<<#, #>>> is for).
 - ▶ Only callable from the CPU (i.e., from a host function).
- __device__
 - ▶ Runs once per call on the GPU.
 - ▶ Only callable from the GPU (i.e., from either a kernel or another device function).

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```
#include <stdio.h>
2
   __device__ int dev1(){
4
5
   __device__ int dev2(){
7
8
9
   __global__ void pleaseRunThis10Times(){
10
     dev1();
11
     dev2();
12
13
14
  int main(){
15
     pleaseRunThis10Times <<<2, 5>>>():
16
     printf("Hello, World!\n");
17
     return 0;
18 }
```

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```
#include < stdio.h>
 2 #include < stdlib . h>
 3 #include <cuda.h>
  #include <cuda_runtime.h>
   __global__ void some_kernel(...) {...}
   int main (void){
     // Declare all variables.
10
11
     // Allocate host memory.
12
13
     // Dynamically allocate device memory for GPU results.
14
15
     // Write to host memory.
16
17
     // Copy host memory to device memory.
18
19
20
     // Execute kernel on the device.
21
     some_kernel <<< num_blocks, num_theads_per_block >>>(...);
22
23
     // Write GPU results in device memory back to host memory.
24
25
     // Free dynamically-allocated host memory
26
27
     // Free dynamically-allocated device memory
28
29
```

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```
#include <stdio.h>
  #include < stdlib.h>
  #include <cuda.h>
  #include < cuda_runtime.h>
   __global__ void colonel(int *a_d){
7
8
     *a d = 2:
   int main(){
     int a = 0, *a_d:
10
11
12
     cudaMalloc((void**) &a_d, sizeof(int));
13
     cudaMemcpy(a_d, &a, sizeof(int), cudaMemcpyHostToDevice);
14
15
     colonel <<<1.1>>>(a_d):
16
17
     cudaMemcpy(&a, a_d, sizeof(int), cudaMemcpyDeviceToHost);
18
     printf("a = %d n", a);
19
20
     cudaFree(a_d);
21
22
```

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```
nvcc simple.cu -o simple
> ./simple
```

Notes:

- nvcc is the NVIDIA CUDA C compiler.
- CUDA C source files usually have the *.cu extension. though they sometimes have have *.c and *.cpp extensions.
- ► This code is available at http://will-landau.com/ gpu/Code/CUDA_C/simple/simple.cu.
- Most of the example code I present will be linked from pages at will-landau.com/gpu/talks.

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Simple program

- maxThreadsPerBlock: exactly that: 1024 on impact1.
- For a kernel call with B blocks and T threads per block,
 - ▶ blockIdx.x
 - ▶ ID of the current block (in the *x* direction).
 - ▶ Integer from 0 to B-1 inclusive.
 - threadIdx.x
 - within the current block, ID of the current thread (in the x direction).
 - ▶ Integer from 0 to T-1 inclusive.
 - gridDim.x: number of blocks in the current grid (in the x direction).
 - blockDim.x: number of threads per block (in the x direction).
- ▶ With some modifications that I will describe in later lectures, you can use the y and z directions with variables like threadIdx.y, threadIdx.z etc.

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```
1 #include < stdio.h>
 2 #include < stdlib.h>
  #include <cuda.h>
  #include <cuda_runtime.h>
  #define N 10
7
   __global__ void add(int *a, int *b, int *c){
9
     int bid = blockldx.x:
     if(bid < N)
10
11
       c[bid] = a[bid] + b[bid];
12
13
14
   int main(void) {
15
     int i, a[N], b[N], c[N];
16
     int *dev_a. *dev_b. *dev_c:
17
18
     cudaMalloc((void**) &dev_a, N*sizeof(int));
19
     cudaMalloc((void**) &dev_b, N*sizeof(int));
20
     cudaMalloc((void**) &dev_c. N*sizeof(int)):
21
22
     for (i=0; i<N; i++)
23
       a[i] = -i:
24
       b[i] = i*i:
25
26
27
     cudaMemcpy(dev_a, a, N*sizeof(int), cudaMemcpyHostToDevice);
28
     cudaMemcpy(dev_b, b, N*sizeof(int), cudaMemcpyHostToDevice);
```

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Vector addition

```
29
30
     add \ll N,1 >> (dev_a, dev_b, dev_c);
31
32
     cudaMemcpy(c, dev_c, N*sizeof(int), cudaMemcpyDeviceToHost);
33
34
      printf("\na + b = c\n"):
35
     for (i = 0; i < N; i++)
36
        printf("\%5d + \%5d = \%5d \setminus n", a[i], b[i], c[i]);
37
38
39
     cudaFree(dev_a);
40
     cudaFree (dev_b);
41
     cudaFree(dev_c):
42 }
```

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Vector addition

```
nvcc vectorsums.cu -o vectorsums
     ./vectorsums
3
    + b = c
4
5
      -1 +
6
      -2 +
7
      -3 +
8
           16 =
                      12
9
      -5 +
           25 =
                      20
10
              36 =
                      30
11
      -7 +
              49 =
                      42
12
      -8 +
              64 =
                      56
13
      -9 +
              81 =
                      72
```

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Pairwise summation

Synchronizing threads within blocks: the pairwise sum revisited

Example: pairwise sum of the vector (5, 2, -3, 1, 1, 8, 2, 6)



Thread 0

Thread 1

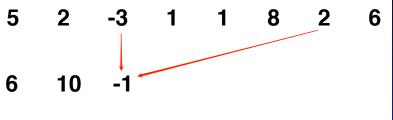
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Thread 2

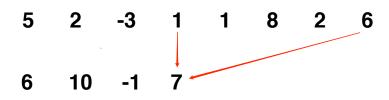
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Thread 3

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5 2 -3 1 1 8 2 6 6 10 -1 7

Synchronize threads

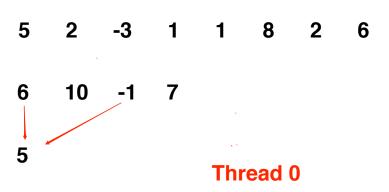
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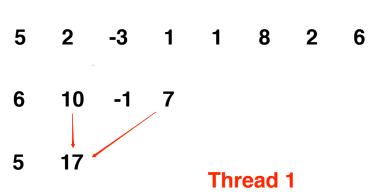
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Pairwise summation



sum revisited

10

17

Synchronize Threads

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5 2 -3 1

6 10 -1 7

5 17

Thread 0

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- ▶ Let $n = 2^m$ be the length of the vector.
- ▶ Denote the vector by $(x_{(0,0)}, \ldots, x_{(0,n-1)})$
- ▶ Spawn 1 grid with a single block of n/2 threads.
- Do:
 - 1. Set offset = n/2.
 - 2. For parallel threads $j = 0, \ldots, \text{ offset } -1, \text{ compute:}$

$$x_{(i, j)} = x_{(i-1, j)} + x_{(i-1, j+\text{offset})}$$

- 3. Synchronize threads.
- 4. Integer divide offset by 2.
- 5. Return to step 2 if offset > 0.

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```
1 #include <stdio.h>
 2 #include < stdlib . h>
 3 #include <math.h>
 4 #include <cuda.h>
  #include <cuda_runtime.h>
6
7
    * This program computes the sum of the elements of
    * vector v using the pairwise (cascading) sum algorithm.
10
11
   #define N 8 // length of vector v. MUST BE A POWER OF 2!!!
13
14
   // Fill the vector v with n random floating point numbers.
   void vfill(float* v, int n){
    int i:
16
17
     for (i = 0; i < n; i++)
18
       v[i] = (float) rand() / RAND_MAX:
19
20
21
   // Print the vector v.
   void vprint(float* v, int n){
24
     int is
25
     printf("v = \n"):
26
     for (i = 0; i < n; i++)
27
       printf("%7.3f\n", v[i]);
28
29
     printf("\n");
30
```

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```
Pairwise—sum the elements of vector v and store the result in v
        [0].
   __global__ void psum(float* v){
33
     int t = threadIdx.x; // Thread index.
     int n = blockDim.x; // Should be half the length of v.
34
35
36
     while (n != 0) {
37
       if(t < n)
38
         v[t] += v[t + n];
39
       __syncthreads();
40
       n /= 2;
41
42
43
44
   int main (void){
45
     float *v_h, *v_d; // host and device copies of our vector,
           respectively
46
47
     // dynamically allocate memory on the host for v_h
48
     v_h = (float*) malloc(N * sizeof(*v_h));
49
50
     // dvnamically allocate memory on the device for y_d
51
     cudaMalloc ((float **) &v_d, N *sizeof(*v_d));
52
53
     // Fill v_h with N random floating point numbers.
54
     vfill(v<sub>-</sub>h . N):
55
56
     // Print v_h to the console
57
     vprint(v_h, N);
```

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pairwise_sum.cu

```
58
     // Write the contents of v h to v d
59
     cudaMemcpv(v_d, v_h, N * sizeof(float), cudaMemcpvHostToDevice):
60
61
     // Compute the pairwise sum of the elements of v_d and store the
           result in v_d[0].
62
     psum <<< 1. N/2 >>> (v_d):
63
64
     // Write the pairwise sum, v_d[0], to v_h[0].
65
     cudaMemcpy(v_h, v_d, sizeof(float), cudaMemcpyDeviceToHost);
66
67
     // Print the pairwise sum.
68
     printf("Pairwise sum = \%7.3 \text{ f} \cdot \text{n}", v_h[0]):
69
70
     // Free dynamically—allocated host memory
71
     free(v_h):
72
73
     // Free dynamically-allocated device memory
74
     cudaFree(v_d):
75 }
```

```
nvcc pairwise_sum.cu —o pairwise_sum
     ./pairwise_sum
3
     0.840
5
     0.394
6
     0.783
     0.798
8
     0.912
9
     0.198
10
     0.335
11
     0.768
12
```

5.029

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Pairwise sum =

- ► SIMD: "Single Instruction, Multiple Data"
- ► Under this paradigm, the thread in a kernel call write to different memory spaces.
- When threads write to the same memory (SISD), problems can arise.

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sisd.cu: violating the SIMD paradigm

```
#include <stdio.h>
  #include <stdlib.h>
  #include <cuda.h>
  #include <cuda_runtime.h>
   __global__ void colonel(int *a_d){
     *a_d = blockDim.x * blockIdx.x + threadIdx.x;
 7
8
9
10
   int main(){
11
12
     int a = 0. *a d:
13
14
     cudaMalloc((void **) &a_d . sizeof(int)):
15
     cudaMemcpy(a_d, &a, sizeof(int), cudaMemcpyHostToDevice);
16
17
     colonel <<<4.5>>>(a_d):
18
19
     cudaMemcpy(&a, a_d, sizeof(int), cudaMemcpyDeviceToHost);
20
21
     printf("a = %d \ n", a);
22
     cudaFree(a_d);
23
24 }
```

What is the output?

sisd.cu: violating the SIMD paradigm

```
1 > nvcc sisd.cu -o sisd
2 > ./sisd
3 a = 14
```

► The output is unpredictable because the threads modify the same variable in an unpredictable order.

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► Texts:

- J. Sanders and E. Kandrot. CUDA by Example. Addison-Wesley, 2010.
- 2. D. Kirk, W.H. Wen-mei, and W. Hwu. *Programming massively parallel processors: a hands-on approach.*Morgan Kaufmann, 2010.
- Code:
 - skeleton.cu
 - ► simple.cu
 - vectorsums.cu
 - pairwise_sum.cu

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 Series materials are available at http://will-landau.com/gpu.