Yuanshao Yang

Last updated: November 3, 2024

EDUCATION

Aug 2023 - Present

University of Michigan - Ann Arbor

College of Engineering

BSE, Mechanical Engineering (Concentration in Robotics)

Sept 2021 - Present

Sichuan University - Pittsburgh Institute

BSE, Mechanical Engineering

GPA: 4.00/4.00

Sichuan University, Chengdu

GPA: 3.84/4.00

Honors & Awards

Aug 2024, University of Michigan

June 2024 / Dec 2023, University of Michigan

May 2024 / Dec 2023, University of Michigan

Oct 2023, Sichuan University

Oct 2022, Sichuan University

Oct 2022, Sichuan University

Oct 2022, Sichuan University

College of Engineering Scholarship (\$2,000) College of Engineering - Dean's List University Honors

Dean's List (10 % Annual Tuition, 30/230)

Academic Star Scholarship (20 % Annual Tuition, 3/230)

Comprehensive Academic Scholarship, 2nd Prize (TOP 4 %)

Outstanding Student Leader of the Year

Projects

Series Spring Design & Evaluation for Open-Source Leg

July 2024 - Present

Instructor: Prof. Elliott Rouse, Zachary Bons

Neurobionics Lab, University of Michigan

GitHub Repository Posted

Publication: In Preparation [1]

- Generate a mechanical design of series spring with easier mounting strategies and better axial alignments
- Generate a design to measure the deflection angle of the series spring via Computer Vision
- Evaluate the hysteresis effect on assembly interfaces through different designs and manufacturing methods
- Evaluate the effect on broadening the design space from series springs

Software Library Generalization for Open-Source Leg

Mar 2024 - Present

Instructor: Prof. Elliott Rouse, Senthur Ayyappan

Neurobionics Lab, University of Michigan GitHub Repository Posted

- Conducting review of literature on structure of prosthetic legs and 3-Phase Brushless DC Motors
- Redesign the Python Library for compatibility with alternative hardware
- Add support to alternative actuator controllers to broaden hardware choices
- Evaluate actuator performance through test of Step Response and Time-Domain Specifications

Development & Motion Analysis of Robot Swimmer

Instructor: Prof. K. Alex Shorter

Mechanical Engineering, University of Michigan

GitHub Repository Posted

Publication: Accepted for Conference Proceeding [2]

- Design & optimize the E-coli based robot CAD model for 2-D motion in uniform, viscous flow
- Validate the mechanical design by CFD analysis
- Develop a path-planning algorithm for obstacle avoidance
- Design the feedback control model to perform reference tracking

WORK EXPERIENCE

Instructional Aid (IA) of ME360 - System Dynamics

Aug 2024 - Present

Dec 2023 - Aug 2024

Full Name: Modeling, Analysis and Control of Dynamic Systems

Instructor: Prof. Uduak Inyang-Udoh

Mechanical Engineering, University of Michigan

- Hold office hours and answer questions in-person / remote
- Take trial exams and offer suggestions on exam question set-ups
- Assist Graduate Student Instructor (GSI) with homework solutions

SKILLS

- General Programming: C/C++, Python
- General Computation & Simulation Tools: MATLAB & Simulink Toolbox, MSC Adams
- Data Science & Machine Learning Toolbox: Scikit-Learn, PyTorch
- Computer Vision: OpenCV
- Mechanical Design: SolidWorks, AutoCAD
- Embedded System Design: Keil MDK
- Writing & Formatting: LaTeX

Publications

- [1] Zachary Bons, Yuanshao Yang, and Elliott J. Rouse. "A Compact, Two-Part Series Spring Architecture". In Preparation. IEEE, 2024.
- [2] Yuanshao Yang, Mingkai Xia, Naike Wu, and Junhan Zhang. "Motion Analysis and Design of Bionic Swimming Robot". Proc. of 2024 IEEE International Conference on Cyborg and Bionic Systems (CBS 2024). Accepted for Presentation. Nagoya, Japan: IEEE, 2024.