Research Proposal

Yuanshao Yang

Department of Mechanical Engineering, University of Michigan

1 Introduction

- General Area to be studied
 - Personalization of Prosthesis / Orthoses / Exoskeleton design [1]
- Why this area is important
 - many people suffer from locomotor defects, thus significantly modify the biomechanics and muscle activity of joints (e.g. asymmetrical gait patterns) [2]
 - correct locomotion (e.g. gaits) defect for disabilities [3]
 - reduce energy cost for long-distance locomotion [4]

2 Research Questions

- what is already known in the field (with several critical studies)?
- Why these studies are not sufficient, thus requiring my further research?
- Key Research Questions, and Relevant Rationale

3 Plans and Methods

4 Significance, Conclusion

References

- [1] P. Slade, M. J. Kochenderfer, S. L. Delp, and S. H. Collins, "Personalizing exoskeleton assistance while walking in the real world," *Nature*, vol. 610, no. 7931, pp. 277–282, 2022.
- [2] L. Nolan, A. Wit, K. Dudziński, A. Lees, M. Lake, and M. Wychowański, "Adjustments in gait symmetry with walking speed in trans-femoral and trans-tibial amputees," *Gait & posture*, vol. 17, no. 2, pp. 142–151, 2003.
- [3] J. F. Lehmann, S. M. Condon, R. Price, et al., "Gait abnormalities in hemiplegia: their correction by ankle-foot orthoses.," Archives of physical medicine and rehabilitation, vol. 68, no. 11, pp. 763–771, 1987.
- [4] K. L. Poggensee and S. H. Collins, "How adaptation, training, and customization contribute to benefits from exoskeleton assistance," *Science Robotics*, vol. 6, no. 58, p. eabf1078, 2021.