COMP390: Evolving a Sorting Algorithm with SNGP

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Project Description

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- ▶ Re-implement Kinnear's work using Single Node Genetic Programming, a variant of GP invented by Dr David Jackson [1]

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Aims:

- ▶ Replicate K. E. Kinnear's work [3] in evolving a sorting algorithm using Genetic Programming
- Re-implement Kinnear's work using Single Node Genetic Programming, a variant of GP invented by Dr David Jackson
 [1]
- Compare the effectiveness of the two approaches to evolving a sorting algorithm

What Was Achieved?

Successfully replicated Kinnear's work

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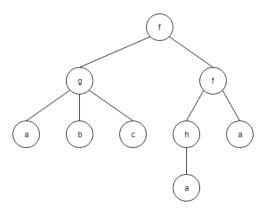
Successfully replicated Kinnear's work

Unable to evolve a sort using SNGP

What is genetic programming?

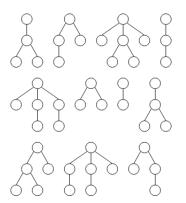
Genetic programming is applying genetic algorithms to programmes in order to generate a programme that performs well in a given problem domain.

Programmes are encoded as a tree of primitive functions and terminals

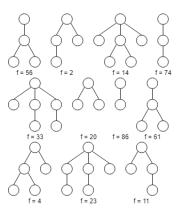


This tree encodes the programme f(g(a, b, c), f(h(a), a)), where f, g, and h are functions and a, b, and c are terminals.

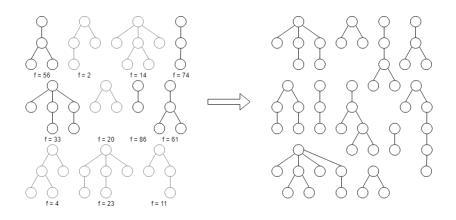
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Each member of the population is executed, evaluated, and given a fitness score



A new population is created by selecting some of the most fit members of the initial population and performing genetic operations on them to create new programmes

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Reproduction



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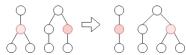
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Crossover



A random node is selected in each of the chosen programmes. The subtrees rooted at the selected nodes are swapped.

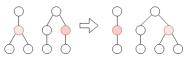
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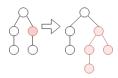
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Mutation



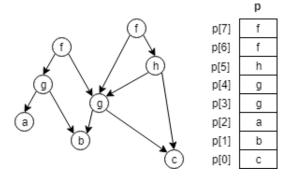
A random node is selected in the chosen programme. A new, random subtree is generated to replace the subtree rooted at the selected node.

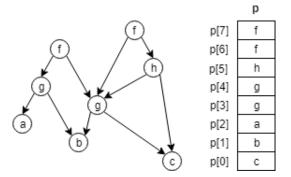
This process is repeated until a programme with high enough fitness is generated

► SNGP is a variation of GP that organises the whole population into a single interlinked graph

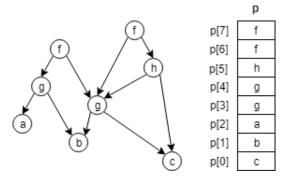
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- ► The subtree rooted at each node in the graph is considered to be an individual programme
- ➤ The graph is structured in such a way that a form of dynamic programming can be used to increase the efficiency of evaluating the population

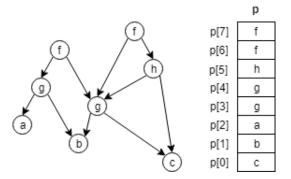




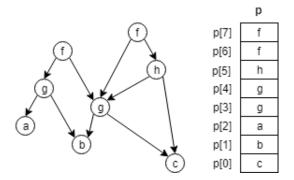
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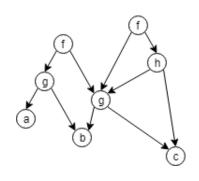


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- Remaining elements store a random function
- ► Each function's operands are chosen from elements with a smaller index





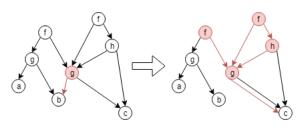
This graph contains the following programmes:

- a
- **▶** b
- **c**
- **▶** g(b, c)
- ▶ g(a,b)
- ► h(g(b, c), c)
- ► f(g(a, b), g(b, c))
- ► f(g(b, c), h(g(b, c), c))

SNGP Operators

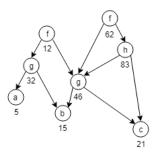
SNGP has only one genetic operator:

Successor Mutate



A random node is chosen and one of its operands is randomly changed. This causes the programmes represented by both the chosen node and all of its predecessors to be altered.

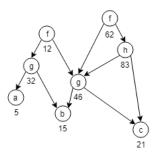
Calculating Fitness - 1



Each individual is executed, evaluated and given a fitness, and then the whole population is given a fitness as a whole.

If a change to the population does not improve this overall fitness, the change is reverted and a different node is selected for the genetic operator.

Calculating Fitness - 2



There are two methods of giving the population a fitness:

- ➤ SNGP/A: The fitness of the population is the average of each individual fitness. In the diagram above this fitness is 34.5.
- ➤ SNGP/B: The fitness of the population is the fitness of best individual. In the diagram above this fitness is 83.

Benefits

- When using pure functions the graph structure allows for dynamic programming by re-using the results from executing subtrees, making evaluation more efficient.
- A single application of successor mutate can modify many individuals at once
- When re-evaluating after successor mutate, results from the previous generation can be used to speed up the evaluation of the graph.
- ▶ SNGP tends to find solutions more often than SNGP [1, 2].
- ➤ SNGP allows for a single programme to re-use code, resulting in smaller programmes [1].

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However:

When using functions with side effects SNGP cannot make use of dynamic programming as the result of executing subtrees changes depending on what was executed before.

Reproducing Kinnear's Results

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With a population of 1000 Kinnear's method would consistently find a solution within 50 generations.

Implementation Details - 1

Implementation based on example code provided by Dr Jackson from his past experiments with GP, and also on an implementation of the TinyGP system found in the book "A Field Guide to Genetic Programming" [5].

Some changes from Dr Jackson's code has to be made to follow Kinnear's method.

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