# COMP390: Evolving a Sorting Algorithm with SNGP

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Introduction

Overview of Genetic Programming

Overview of Single Node Genetic Programming

Reproducing Kinnear's Results

Attempting SNGP

Conclusion

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# **Project Description**

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#### Aims:

- ▶ Replicate K. E. Kinnear's work [2] in evolving a sorting algorithm using Genetic Programming
- Re-implement Kinnear's work using Single Node Genetic Programming, a variant of GP invented by Dr David Jackson
  [1]
- Compare the effectiveness of the two approaches to evolving a sorting algorithm

# What Was Achieved?

Successfully replicated Kinnear's work

## What Was Achieved?

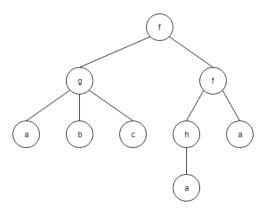
Successfully replicated Kinnear's work

Unable to evolve a sort using SNGP

# What is genetic programming?

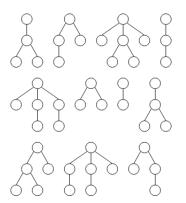
Genetic programming is applying genetic algorithms to programmes in order to generate a programme that performs well in a given problem domain.

Programmes are encoded as a tree of primitive functions and terminals

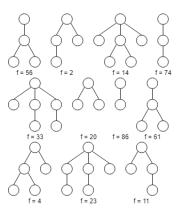


This tree encodes the programme f(g(a, b, c), f(h(a), a)), where f, g, and h are functions and a, b, and c are terminals.

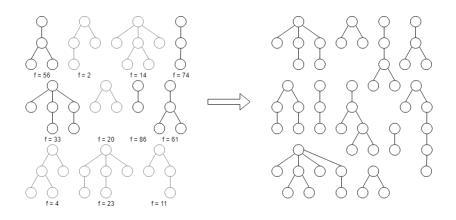
An initial population of random programmes is created



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Each member of the population is executed, evaluated, and given a fitness score



A new population is created by selecting some of the most fit members of the initial population and performing genetic operations on them to create new programmes

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## Reproduction



A programme is copied over to the new population without any changes

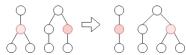
#### There are three main genetic operators:

## Reproduction



A programme is copied over to the new population without any changes

#### Crossover



A random node is selected in each of the chosen programmes. The subtrees rooted at the selected nodes are swapped.

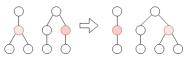
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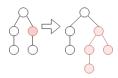
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## Crossover



A random node is selected in each of the chosen programmes. The subtrees rooted at the selected nodes are swapped.

#### Mutation



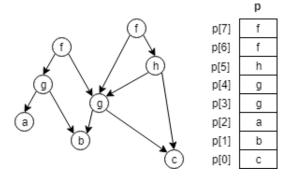
A random node is selected in the chosen programme. A new, random subtree is generated to replace the subtree rooted at the selected node.

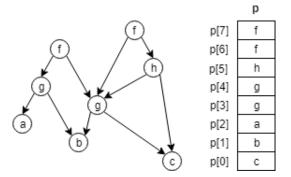
This process is repeated until a programme with high enough fitness is generated

► SNGP is a variation of GP that organises the whole population into a single interlinked graph

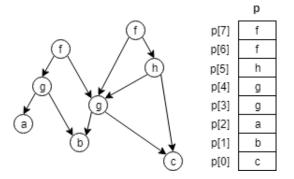
- ► SNGP is a variation of GP that organises the whole population into a single interlinked graph
- ► The subtree rooted at each node in the graph is considered to be an individual programme

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- ► The subtree rooted at each node in the graph is considered to be an individual programme
- ➤ The graph is structured in such a way that a form of dynamic programming can be used to increase the efficiency of evaluating the population

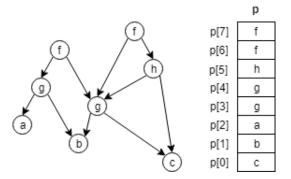




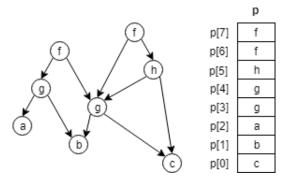
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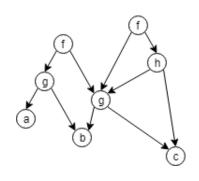


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- Graph nodes are stored in an array
- ► Terminals are stored in lowest elements
- Remaining elements store random function
- ► Each functions operands are chosen from elements with a smaller index





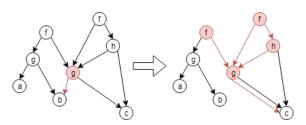
This graph contains the following programmes:

- a
- **▶** b
- **c**
- **▶** g( b, c )
- ▶ g( a, b )
- ► h( g( b, c ), c )
- ► f( g( a, b ), g( b, c ) )
- ► f( g( b, c ), h( g( b, c ), c ) )

# **SNGP** Operators

SNGP has only one genetic operator:

## Successor Mutate



# **Bibliography**

- [1] Jackson, D.
  - A new, node-focused model for genetic programming. In *Genetic Programming* (2012), A. Moraglio, S. Silva, K. Krawiec, P. Machado, and C. Cotta, Eds., Lecture Notes in Computer Science, Springer Berlin Heidelberg, pp. 49–60.
- [2] KINNEAR, K. E. Evolving a sort: Lessons in genetic programming. In in Proceedings of the 1993 International Conference on Neural Networks (1993), IEEE Press, pp. 881–888.