

1)

$$x_0 = x_k = x_i$$

$$f_0 = f_0 + f_k$$

$$f_0(t) = D \dot{x}_0(t) = D \dot{x}_i(t)$$

$$f_k(t) = k x_k(t) = k x_i(t)$$

$$f_0 = D \dot{x}_i(t) + k x_i(t)$$

homogeneous solution:

$$[\dot{x}_H(t) + \frac{k}{D} x_H(t) = 0]$$

$$\Rightarrow x_H(t) = C e^{-\frac{k}{D} t}$$

$$\Rightarrow x_i(t) = c(t) e^{-\frac{k}{D} t}$$

$$\dot{x}_i(t) = \dot{c}(t) e^{-\frac{k}{D} t} - \frac{k}{D} c(t) e^{-\frac{k}{D} t}$$

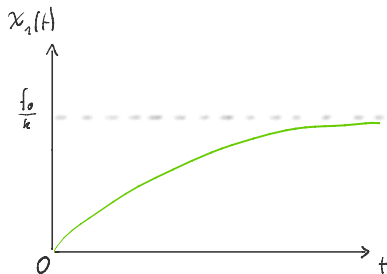


$$\dot{c}(t) e^{-\frac{k}{D} t} - \frac{k}{D} c(t) e^{-\frac{k}{D} t} = \frac{f_0}{D} - \frac{k}{D} c(t) e^{-\frac{k}{D} t}$$

$$\dot{c}(t) = \frac{f_0}{D} e^{\frac{k}{D} t} \Rightarrow c(t) = \frac{f_0}{k} e^{\frac{k}{D} t} + c' \Rightarrow x_i(t) = \left(\frac{f_0}{k} e^{\frac{k}{D} t} + c' \right) e^{-\frac{k}{D} t}$$

$$x_i(0) = 0 = \frac{f_0}{k} + c' \Rightarrow c' = -\frac{f_0}{k}$$

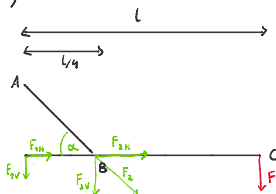
$$\Rightarrow x_i(t) = \frac{f_0}{k} \left(1 - e^{-\frac{k}{D} t} \right)$$



$$x_i(t) = \frac{f_0}{k}$$

$$t \rightarrow \infty$$

2)



$$F_{1H} = \cos(\alpha) F_2 \quad F_{1V} = \sin(\alpha) F_2$$

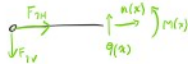
$$M: \sin(\alpha) F_2 \frac{l}{4} = -F l \Rightarrow F_2 = -\frac{4F}{\sin(\alpha)} = -1,7 \text{ kN}$$

$$\Rightarrow F_{1H} = -\frac{4F}{\tan(\alpha)} = -1,2 \text{ kN}$$

$$\Rightarrow F_{2V} = -4F = -1,2 \text{ kN}$$

$$H: F_{1H} = -F_{2H} \Rightarrow F_{1H} = \frac{4F}{10\sin(\alpha)} = 7,2 \text{ kN}$$

$$V: F_{1V} + F_{2V} = -F \Rightarrow F_{1V} = -F + 4F = 3F = 0,9 \text{ kN}$$



$$M(x) = F_{1V} x = 3F x$$

$$M(x) = (l-x) F$$

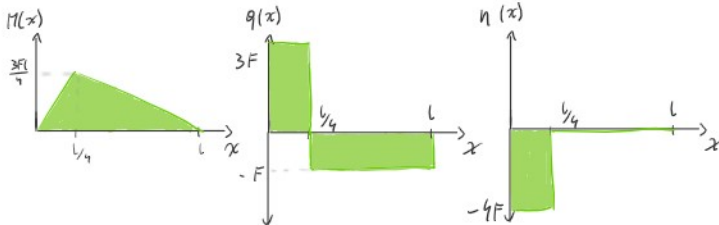
$$M\left(\frac{l}{4}\right) = \frac{3Fl}{4} = 0,675 \text{ kNm}$$

$$M\left(\frac{l}{4}\right) = \frac{3Fl}{4} = 0,675 \text{ kNm} \quad \checkmark$$

$$q(x) = F_{1V} = 3F = 0,9 \text{ kN}$$

$$q(x) = -F = -0,3 \text{ kN}$$

$$n(x) = -F_{1H} = -4F = -7,2 \text{ kN} \quad n(x) = 0$$



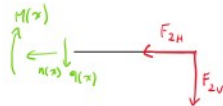
$$F_{2H} = \cos(\alpha) F_2 \quad F_{2V} = \sin(\alpha) F_2$$



$$H: F_{2H} = F_{2H} = \cos(\alpha) F_2 = 50 \text{ N}$$

$$V: F_{3V} = F_1 - F_{2V} = F_1 - \sin(\alpha) F_2 = -26,6 \text{ N}$$

$$M: M_0 = \frac{2}{3} l F_1 - l F_{2V} = l \left(\frac{2}{3} F_1 - \sin(\alpha) F_2 \right) = -69,9 \text{ Nm}$$



$$n(x) = -F_{3H} = -50 \text{ N}$$

$$n(x) = -F_{2H} = -50 \text{ N}$$

$$q(x) = F_{3V} = -26,6 \text{ N}$$

$$q(x) = -F_{2V} = -86,6 \text{ N}$$

$$M(x) = -F_{3V} x + M_0$$

$$M(x) = -(l-x) F_{2V} = -(l-x) \sin(\alpha) F_2$$

$$= -(F_1 - \sin(\alpha) F_2) x + \left(\frac{2}{3} F_1 - \sin(\alpha) F_2 \right) l$$

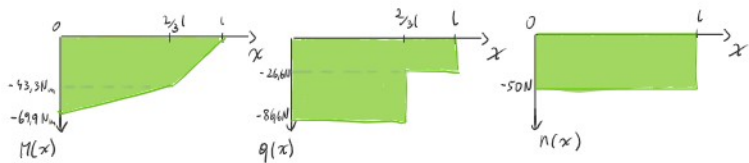
$$\Rightarrow M\left(\frac{2}{3}l\right) = -\frac{2}{3} l \sin(\alpha) F_2 = -43,3 \text{ Nm}$$

$$= \sin(\alpha) F_2 (x-l) - F_1 \left(\frac{2}{3} l - x \right)$$

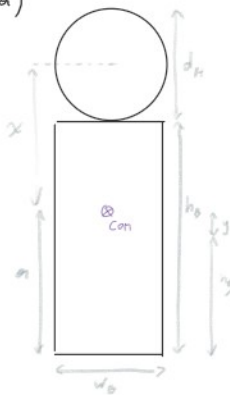
$$\frac{dM(x)}{dx} = \sin(\alpha) F_2 > 0$$

$$\Rightarrow M\left(\frac{2}{3}l\right) = -\frac{2}{3} l \sin(\alpha) F_2 = -43,3 \text{ Nm}$$

$$\frac{dM(x)}{dx} = \sin(\alpha) F_2 - F_1 > 0$$



3 a)



Body : Cuboid - Inertia

$$I_{cm}^{(w)} = \frac{1}{12} m_B (h_B^2 + w_B^2)$$

$$I_B = I_{cm}^{(w)} + m_B y^2 = \frac{1}{12} m_B (h_B^2 + w_B^2) + m_B \left(a - \frac{h_B}{2}\right)^2 = 15,25 \text{ kg m}^2$$

Head : Sphere - Inertia

$$I_{cm}^{(s)} = \frac{2}{5} m_H r^2 = \frac{1}{10} m_H d_H^2$$

$$\Rightarrow I_H = I_{cm}^{(s)} + m_H x^2 = \frac{1}{10} m_H d_H^2 + m_H \left(h_B - a + \frac{d_H}{2}\right)^2 = 5,565 \text{ kg m}^2$$

$$\Rightarrow I = I_B + I_H = \frac{m_B}{12} (h_B^2 + w_B^2) + m_B \left(a - \frac{h_B}{2}\right)^2 + \frac{m_H d_H^2}{10} + m_H \left(h_B - a + \frac{d_H}{2}\right)^2 = 20,815 \text{ kg m}^2$$

b)

$$\vec{v}_{12} = \vec{v}_2 - \vec{v}_1 = \begin{pmatrix} -1 \\ 0 \\ 5 \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \\ 3,7 \end{pmatrix} = \begin{pmatrix} -3 \\ 0 \\ 1,3 \end{pmatrix}$$

$$\Rightarrow |\vec{v}_{12}| = \sqrt{(-3)^2 + 1,3^2} = 3,27 \text{ m/s}$$

$$\omega = \frac{v}{r} = \frac{|\vec{v}_{12}|}{a} = 4,09 \text{ rad/s}$$

$$L = \omega I = 85,13 \text{ kg m}^2/\text{s}$$

c) Conservation of angular momentum:

$$|\vec{L}_1 = \vec{L}_2| \Rightarrow I_1 \omega_1 = I_2 \omega_2$$

$$I_2 = I_{(\text{sphere})} = \frac{2}{5} m r^2 = \frac{1}{10} (m_H + m_D) d_s^2 = 5,184 \text{ kg m}^2$$

$$\Rightarrow \omega_2 = \frac{I_1 \omega_1}{I_2} = \underline{\underline{16,42 \text{ rad/s}}}$$

d)

$$\frac{m v_1^{(z)^2}}{2} = m g h$$

$$h = \frac{v_1^{(z)^2}}{2g} = \frac{3,7^2}{2 \cdot 9,81} = \underline{\underline{0,7 \text{ m}}}$$