# Dense Hopfield networks in the teacher-student setting

Robin Thériault Supervised by Daniele Tantari

October 31, 2024

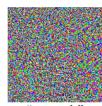
arXiv 2401.04191



Neural networks are fooled by small adversarial perturbations.



"panda" 57.7% confidence



"nematode" 8.2% confidence

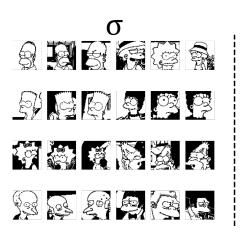


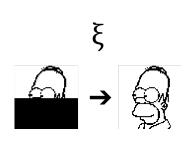
"gibbon" 99.3 % confidence

+.007 ×

#### Dense Hopfield network

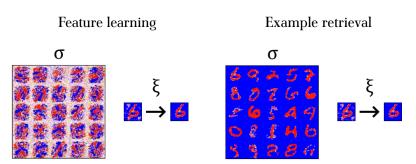
- Task: restore incomplete pattern  $\xi$  with N pixels using stored memories  $\sigma^a$ .
- Robust to adversarial perturbations.





#### Dense Hopfield Network

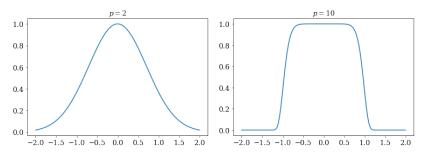
Memories can be learned from data.



Example retrieval empirically known to be robust.

#### Direct problem

Model task: retrieve memories  $\sigma^a$  by sampling  $\xi \sim P\left(\xi | \sigma; p, T\right) = \mathcal{Z}^{-1} \exp\left(-E\left[\xi\right]/T\right)$  where  $E\left[\xi\right] = -\frac{p!}{N^{p-1}} \sum_{a} \sum_{i_1 < \ldots < i_p} \xi_{i_1} \ldots \xi_{i_p} \sigma^a_{i_1} \ldots \sigma^a_{i_p}.$ 

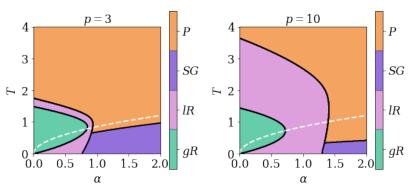


- Well-studied theoretically.
- Capacity of  $M \sim \mathcal{O}\left(N^{p-1}\right)$  i.i.d. random memories.



#### Direct problem

Parameters: temperature T and memory load  $\alpha = \frac{Mp!}{N^{p-1}}$ .



#### Caveats:

- Does not explain adversarial robustness.
- Does not capture the feature regime.
- Does not say how much data a dense net needs.
- *SG* transition hard to obtain exactly.



# Teacher-student setting

#### Teacher-student setting:

- Sample examples  $\sigma = {\{\sigma^a\}}_{a=1}^M$  from teacher with pattern  $\xi^*$ :  $\sigma^a \sim P\left(\sigma^a | \xi^*; p_{\text{teacher}}, T_{\text{teacher}}\right)$ .
- Sample pattern  $\xi$  from student with memories  $\sigma = \{\sigma^a\}_{a=1}^M$ :  $\xi \sim P(\xi | \sigma; p_{\text{student}}, T_{\text{student}}).$

Student task: recover  $\xi^*$ .

Our goal: predict student performance as a function of  $p_{\text{teacher}}$ ,  $T_{\text{teacher}}$ ,  $p_{\text{student}}$ ,  $T_{\text{student}}$  and  $\alpha$  (normalized M).

# Teacher-student setting

Compute the order parameters m, q and  $q^*$ , where

• 
$$m = \lim_{N \to \infty} \left\langle \frac{1}{N} \sum_{i} \xi_{i} \sigma_{i}^{a} \right\rangle_{\xi^{*}, \sigma, \xi}$$

• 
$$q = \lim_{N \to \infty} \left\langle \frac{1}{N} \sum_{i} \xi_i^1 \xi_i^2 \right\rangle_{\xi^*, \sigma, \xi}$$

• 
$$q^* = \lim_{N \to \infty} \left\langle \frac{1}{N} \sum_i \xi_i^* \xi_i \right\rangle_{\xi^*, \sigma, \xi}$$
.

m measures the proximity of the student pattern and memories.

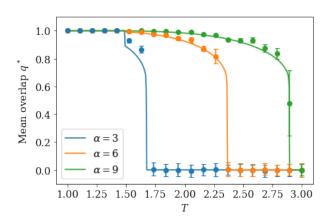
q measures the tendency of the student to stay frozen in specific configurations.

 $q^*$  measures the student performance.

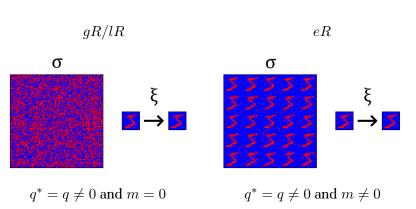


Consider  $p_{\text{teacher}} = p_{\text{student}}$  and  $T_{\text{teacher}} = T_{\text{student}}$ .

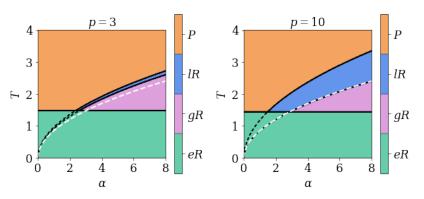
- Study the performance  $q^*$ .
- Plot: calculations (lines) consistent with simulations (dots).



Obtain feature learning (gR/lR) and example retrieval (eR) phases.



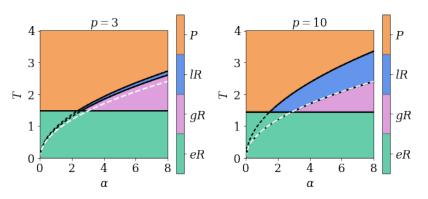
Obtain feature learning (gR/lR) and example retrieval (eR) phases.



- $P: q^* = q = 0 \text{ and } m = 0$
- gR/lR:  $q^* = q \neq 0$  and m = 0
- ullet eR:  $q^* = q \neq 0$  and  $m \neq 0$

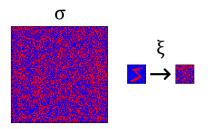


Obtain feature learning (gR/lR) and example retrieval (eR) phases.



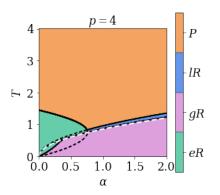
The gR transition overlaps with the direct model SG transition. arXiv 2401.04191

- Next:  $p_{\text{teacher}} = 2$  and  $p_{\text{student}} \ge 3$ .
- ullet In this regime, teacher examples are noisy, so eR is inaccurate.



#### Case 1:

- $M \sim \mathcal{O}\left(N^{p-1}\right)$   $T_{\mathrm{teacher}} \sim \mathcal{O}\left(N^{1-2/p}\right)$ , i.e. can infer  $\xi^*$  despite large  $T_{\mathrm{teacher}}$ .



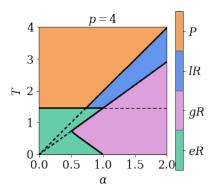
Extensive tolerance to teacher noise.

arXiv 2401.04191



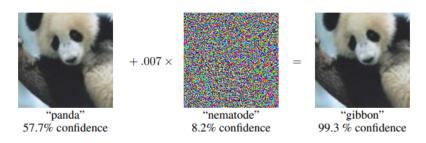
#### Case 2:

- $T_{\text{teacher}} \sim \mathcal{O}(1)$
- $M \sim \mathcal{O}\left(N^{p/2}\right)$ , i.e. much smaller M than in the first case.



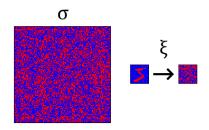
Avoids pattern interference.

Neural networks are fooled by small adversarial perturbations.

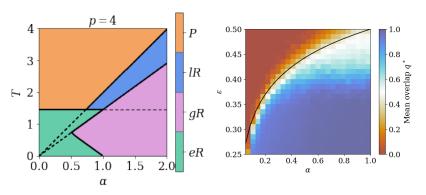


Neural networks with more parameters are more robust.

When  $p_{\text{teacher}}=2$  and  $p_{\text{student}}\geq 3$ , memories  $\sigma^a$  are noisy, so eR is inaccurate.

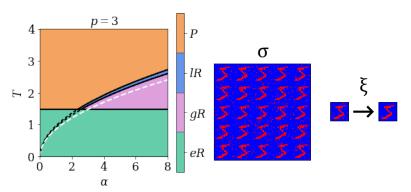


Study adversarial attacks of size  $\varepsilon$  at  $T_{\mathrm{student}} = 0$ .



- Right plot: calculations (line) agree with simulations (image).
- Adversarial robustness increases with the memory load  $\alpha$ , in line with empirical observations of neural networks. arXiv 2401.04191

Adversarial attacks fail when  $p_{\text{teacher}} = p_{\text{student}}$  and  $T_{\text{teacher}} = T_{\text{student}}$  because eR is accurate.



Clarifies why accurate example retrieval is adversarially robust.



## Summary of results

- The teacher-student feature learning phase transition overlaps the direct problem spin-glass phase transition.
- Feature learning can resist extensive teacher noise and pattern interference.
- As seen in neural networks, feature learning becomes more adversarially robust as the memory load increases.
- Our model clarifies why the example retrieval phase of dense Hopfield networks is adversarially robust.

arXiv 2401.04191



# Dense Hopfield model

Sampling:  $\xi \sim P\left(\xi | \sigma; p, T\right) = \mathcal{Z}^{-1} \exp\left(-E\left[\xi\right] / T\right)$  where

- $E\left[\xi\right] = -\frac{p!}{N^{p-1}} \sum_{a} \sum_{i_1 < \ldots < i_p} \xi_{i_1} \ldots \xi_{i_p} \sigma^a_{i_1} \ldots \sigma^a_{i_p},$
- $P(\xi|\sigma;p,T)$  is sampled with a Monte-Carlo simulation.
- $E[\xi]$  reduces to  $E[\xi] = -\frac{1}{N} \sum_{a} \sum_{i \neq j} \xi_i \xi_j \sigma_i^a \sigma_j^a$  when p = 2,
- MC reduces to  $\xi_i = \operatorname{sign}\left(\sum_a \sigma_i^a \sum_j \xi_j \sigma_j^a\right)$  when T = 0.

# Overlapping gR and SG lines

Sampling:  $\xi \sim P\left(\xi | \sigma; p, T\right) = \mathcal{Z}^{-1}\left(\sigma\right) \exp\left(-E\left[\xi | \sigma\right] / T\right)$  where  $\mathcal{Z}\left(\sigma\right)$  is a normalization constant.

The gR line overlaps with the SG line because

- $P(\sigma) = \frac{1}{2^{MN}} \frac{\mathcal{Z}(\sigma)}{\langle \mathcal{Z} \rangle}$ ,
- $\lim_{N\to\infty} \left\{ \frac{\log \mathcal{Z} \log \langle \mathcal{Z} \rangle}{N} \right\} = 0$  in the paramagnetic phase.

#### Adversarial robustness formula

Adversarial boundary: 
$$\varepsilon^* = \frac{[\eta \alpha]^{\frac{1}{p-1}}}{[\eta \alpha]^{\frac{1}{p-1}}+1}$$
 where  $\eta = \frac{2[\beta^*]^2}{(1-2\beta^*)^2}$  when  $p=4$ .

# Bibliography I



F. Alemanno, L. Camanzi, G. Manzan, and D. Tantari, "Hopfield model with planted patterns: A teacher-student self-supervised learning model," *Applied Mathematics and Computation*, vol. 458, p. 128253, 2023. [Online]. Available: https://www.sciencedirect.com/science/article/pii/S0096300323004228



E. Gardner, "Multiconnected neural network models," *Journal of Physics A: Mathematical and General*, vol. 20, no. 11, p. 3453, 1987.



D. Krotov and J. J. Hopfield, "Dense associative memory for pattern recognition," *Advances in neural information processing systems*, vol. 29, 2016.



D. Krotov and J. Hopfield, "Dense associative memory is robust to adversarial inputs," *Neural computation*, vol. 30, no. 12, pp. 3151–3167, 2018.

# Bibliography II

- I. J. Goodfellow, J. Shlens, and C. Szegedy, "Explaining and harnessing adversarial examples," *arXiv* preprint *arXiv*:1412.6572, 2014.
- H. Ramsauer, B. Schäfl, J. Lehner, P. Seidl, M. Widrich, T. Adler, L. Gruber, M. Holzleitner, M. Pavlović, G. K. Sandve *et al.*, "Hopfield networks is all you need," *arXiv preprint* arXiv:2008.02217, 2020.
- J. Puigcerver, R. Jenatton, C. Riquelme, P. Awasthi, and S. Bhojanapalli, "On the adversarial robustness of mixture of experts," in *Advances in Neural Information Processing Systems*, S. Koyejo, S. Mohamed, A. Agarwal, D. Belgrave, K. Cho, and A. Oh, Eds., vol. 35. Curran Associates, Inc., 2022, pp. 9660–9671. [Online]. Available: https://proceedings.neurips.cc/paper\_files/paper/2022/file/3effb91593c4fb42b1da1528328eff49-Paper-Conference.pdf