LEARNING RATE SCHEDULES

DEEP LEARNING RESEARCH KITCHEN

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Outline

- Background Why do we schedule learning rates in DL?
- Which LR schedules are used in practice?
- 3 Experiments
- Scheduling other Hyperparameter
- 5 Conclusion

Outline

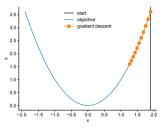
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Empirical risk minimization

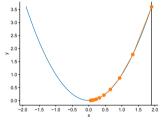
$$\theta^* = \arg\min_{\theta} \frac{1}{N} \sum_{i=1}^{N} \mathcal{L}(y_i, f(x_i; \theta))$$

- In deep learning it is a non convex optimization problem
- Find a solution through gradient descent.

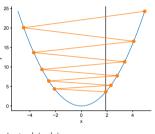
$$\theta_{t+1} = \theta_t - \alpha \nabla_{\theta_t} f(\mathbf{x}, \theta_t)$$



 α is very small



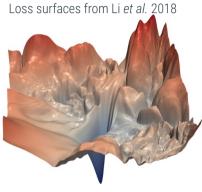
 α is reasonably big



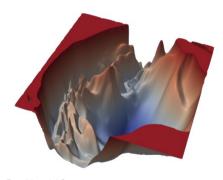
 α is to big big

Background

Motivation



ResNet-56



ResNet-110

Background

The problem with constant learning rates; Zhang *et al.* 2023

The idea is: a preset constant learning rate throughout the training is not optimal.

- ► Too high: Large jumps, potential for instability and divergence.
- ► Too low: Slow convergence, risk of getting stuck in local minima.

Background

what is a learning rate scheduler?; Zhang et al. 2023

Approach: take the learning parameter α not as a constant but as a function of t

$$\theta_{t+1} = \theta_t - \alpha(t) \nabla_{\theta_t} f(\mathbf{x}, \theta_t)$$

With this we try to enable:

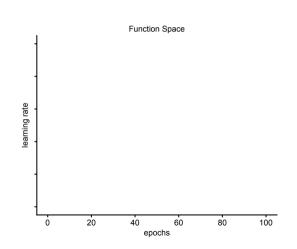
- Early rapid exploration with high learning rates.
- Finer adjustments and convergence with small learning rates.
- ► Higher stability and avoids getting stuck.

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Function space

We have a whole function space for $\alpha: \mathbb{R} \to \mathbb{R}$ Which functions are reasonable?



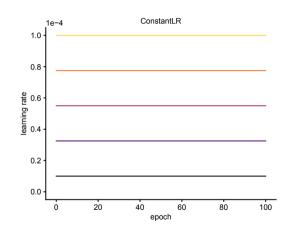
ConstantLR Schedule

constant learning rate over the whole training.

Advantages

- ▶ Trivial implementation
- Useful baseline

- More sensitive to high learning rates
- Has to comprehend for fast exploration and refinement



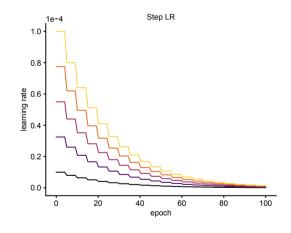
StepLR Schedule

Multiply learning rate by constant factor every *k* epochs.

Advantages

- Aggressive initial learning rate
- Smooth decay

- Potentially overshoots the solution
- Limited adaptability



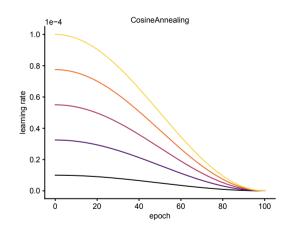
Cosine Annealing Schedule

Work done by: Loshchilov and Hutter 2016 Follow the first half of a cosine period

Advantages

- Reduces the overshot problem
- Smooth decay

- Potentially slow convergence (not so aggressive Ir in the beginning)
- More parameters to tune



Warmup Schedules

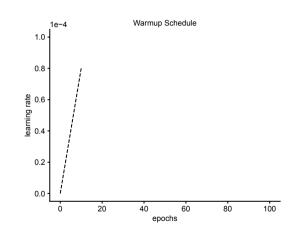
One of the first appearance w.r.t DL in He et al. 2016.

- Gradually increasing the learning rate until a maximum
- Continue with any schedule you like

Advantages (Gotmare et al. 2018):

- Lowers the amount of divergence of parameters by the end of training
- More stable training for higher learning rates
- Can improve training

But it introduces also new hyperparameter

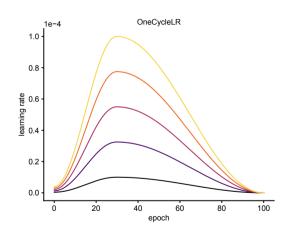


OneCycle Schedule

Proposed by: L. N. Smith and Topin 2019

- Gradually increasing the learning rate until a maximum
- 2 Staying on a plateau for exploration
- 3 Decreasing the learning rate for fine-tuning

Comes with the same advantages as warmup schedules



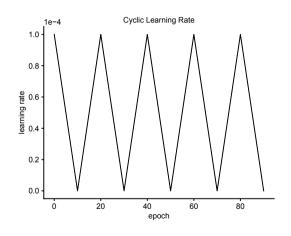
Cyclic Learning Rate Schedule

Proposed by: Schaul *et al.* 2013, L. N. Smith 2017 oscillate between min and max learning rate.

Advantages

- Explores broader region
- ▶ More flexible
- Avoiding getting stuck

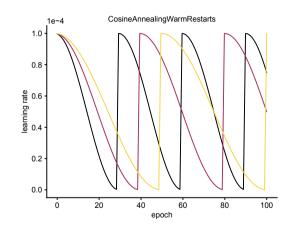
- More complex to tune
- Slow convergence
- Prone to over-fit



Cosine Annealing with Warm Restarts

Proposed by: Loshchilov and Hutter 2016 Cyclical learning rate schedule with cosine as decay.

- Single decaying cycle
- Less parameters to tune
- Focuses on smooth learning rate decay
- ► Works well with an over all decay trend Gotmare *et al.* 2018



Wrapup

Decaying Schedules:

- Step Decay: Periodical exponential decay
- Exponential Decay: Continuously differentiable version of step decay
- Cosine Annealing: Reduce learning rate following a cosine curve
- Linear Decay: Linear decay

Option to expand those with warmup

Cyclic:

- Cyclic Learning Rate: Bouncing between max mal and minimal learning rate
- Cosine Annealing with Warm Restarts: Decay with cosine and jump back to maximal learning rate
- ▶ OneCycle: combines the content of cyclic Ir schedules in one cycle

Others like piecewise constant or something else are also valid

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Setup

- ► Task: Image Classification
- Dataset: CIFAR10 Krizhevsky, Hinton, et al. 2009
- architecture: small ViT (approx. 12.5M params scaled down version from Dosovitskiy et al. 2020 at omihub777 2021)
- lacktriangle optimizer: AdamW with weight decay 10^{-4} and different learning rates Loshchilov and Hutter 2017
- Training for 100 epochs
- ▶ Batch size: 512 training, 2048 validation and testing

Metrics:

- Cross Entropy
- Accuracy
- ► Test best model w.r.t. validation accuary

Various configured learning rate scheduler

Scheduler Search Space

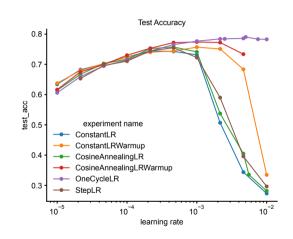
Scheduler	Parameter	Search Space
ConstantLR (warmup)	factor = 1, *	$r \in [10^{-6}, 10^{-2}]$
CosineAnnealingLR (warmup)	$T_{max} = 100$, $\eta_{min} = 10^{-6}$, \star	$r \in [10^{-5}, 10^{-2}]$
StepLR	step size = 5, $\gamma=0.9$	$lr \in [10^{-5}, 10^{-2}]$
OneCycleLR	total steps = 100	$\text{max_lr} \in [10^{-5}, 10^{-2}]$
CosineAnnealingWarmRestarts	$\mathrm{lr} \approx 4.6 \cdot 10^{-4}$	$T_0 \in [10, 50]$

^{*:} for the warmup version we choose 6 warmup epochs

Test Accuracy

Test accuracy per deployed learning rate factor

- While increasing the maximal learning rate, predictor performance varies across different schedules
- But we can spot similarities between schedules



Test Accuracy Groups

OneCycle Learning Rate:

- Seems to work best in the current setup
- ► Able to handle high maximal learning rate

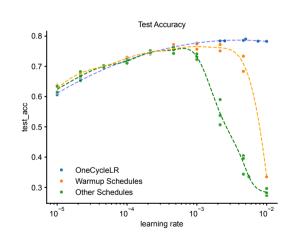
Purly Decaying / Constant

- ► Similar to OneCycle for small learning rates
- ► Begin to diverge very early

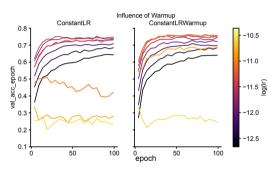
Warmup Schedules:

(ConstantLR and CosineAnnealingLR with Warmup)

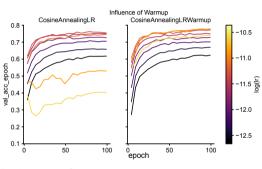
- Seems to produce slightly better results
- Makes training more stable



Influence of Warmup



Constant Learning Rate

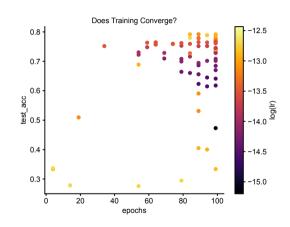


Cosine Annealing

Convergence / Divergence

At which epoch was the model at its best and how high was the learning rate?

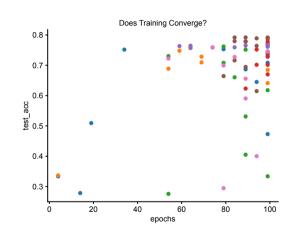
- Convergence region (upper right): smooth gradient towards maximal accuracy late in the training process
- Divergence / under-fit region (lower left): high learning rates and low accuracy early in training



Convergence / Divergence

At which epoch was the model at its best and how high was the learning rate?

- Convergence region (upper right): smooth gradient towards maximal accuracy late in the training process
- Divergence / under-fit region (lower left): high learning rates and low accuracy early in training



Limitations

Setup

- Dataset size. Other datasets might reveal a higher variance in training behavior
- ▶ Model Complexity: The simplified ViT could be not as sensitive as large scale models

Training

- Limited exploration space
- Tuning only for scheduler hyperparameter, leaving other parameters constant
- Training duration
- Used metrics could be expanded also F1 score, ...
- ► No statistical significance conducted.

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Overview

Learning rate is not the only hyperparameter that benefits from scheduling. Benefits:

- Fine-tuning hyperparameter values throughout training can lead to better performance and stability.
- Allows for more sophisticated training strategies that adapt to the learning process.

Exmaples of current research schedules 3 other parameter:

- ▶ Batch Size: S. L. Smith et al. 2017
- Momentum: Sun et al. 2021
- Weight Decacy: Xie et al. 2024

But you can basically schedule everything you want.

Batch Size

Work done by: S. L. Smith et al. 2017

Instead of increasing the learning rate they propose to increase the batch-size.

- More accurate estimate of the true gradient
- lacktriangle Update step size is proportional to both the learning rate and the batch size \to batch size effectively reduces the learning rate

Advantages

- Reduced the number of parameter-updates required
- Their scaling rules enable them to use existing hyperparameter-configurations

Momentun

Work done by Sun et al. 2021

Problem: Momentum β as fixed hyperparameter. Setting it could be quite challenging

$$\theta_{t+1} = \theta_t - \alpha \nabla_{\theta_t} f(\mathbf{x}; \theta_t) + \beta(\theta_t - \theta_{t-1})$$

Solution: Adaptive heavy ball momentum (Polyak momentum), inspired by the optimal choice of momentum for quadratic optimization problems. Adjusts automatically based on past gradients \rightarrow no manual tuning needed Advantages:

- Convergences faster than those with fixed momentum.
- ► More robust w.r.t. large learning rates
- ► Might generalize better to unseen data.

Weight Decay

Work done by: Xie et al. 2024

Problem: Weight decay is a regularization technique, helps prevent over-fitting. But large weight decay can lead to large gradient norms during the final stages of training. This could lead to: Destabilize training, Hinder convergence

Solution: Paper proposes Scheduled-Weight-Decay (SWD), dynamically adjusts the weight decay strength based on the gradient norm.

- High Gradient Norm Lower Weight Decay
- Low Gradient Norm Higher Weight Decay

This feedback loop leads to:

- Simpler Hyperparameter Tuning
- Improved Convergence
- Better Generalization

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Conclusion

- ► Learning rate scheduler are a reasonable aspect in improving training neural networks
 - ► They can speed up training
 - Find better optima
 - Stabilize training
- But the also open up a huge parameter space to optimize.
- ▶ Tuning one schedule does not mean we can map those result on any other schedule.
- ► There is no single 'best' schedule for every model.
- Scheduling other parameters could be use-full for boosting performance. But still come at the cost of tuning additional parameters.

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Thank you for your attention

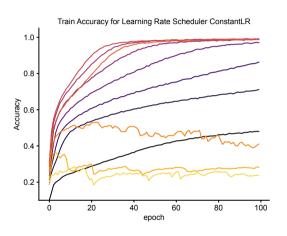
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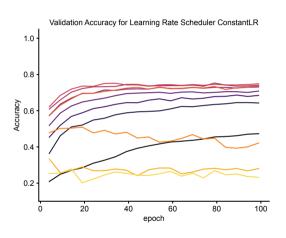
Questions?

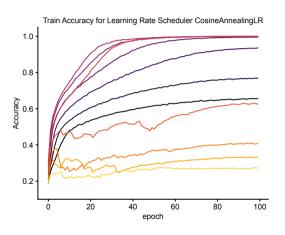
GitHub:

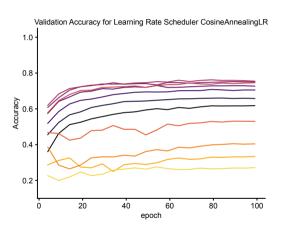
https://github.com/RobinU434/DeepLearningResearchKitchen.git

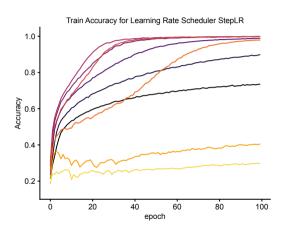


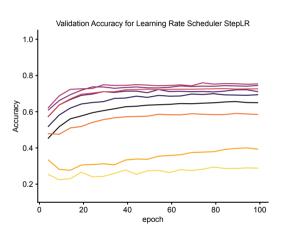


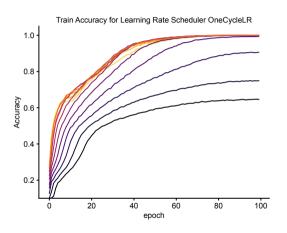


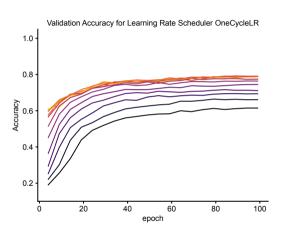


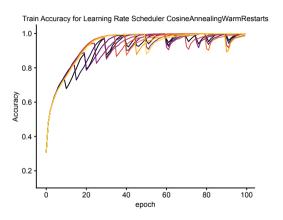


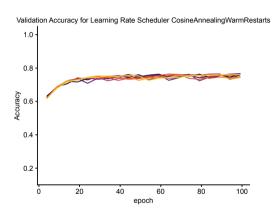












$$\mathbf{x}^{k+1} = \mathbf{x}^k - \gamma \mathbf{g}^k + \beta_k (\mathbf{x}^k - \mathbf{x}^{k-1}),$$

$$\beta_{k+1} = \mathbf{Proj}_{[0,1-\delta]} \left(\left[1 - \sqrt{\gamma \frac{\|\mathbf{g}^k - \mathbf{g}^{k-1}\|}{\|\mathbf{x}^k - \mathbf{x}^{k-1}\|}} \right]^2 \right),$$

Infinite Learning Rate Schedule

When your training budget is infinite you can follow approaches like:

- Cyclical Learning Rates (CLR) for Long-Range Optimization: multiple cycles of increasing and decreasing the learning rate, allowing the model to explore a wider range of learning rates and potentially avoid getting stuck in local minima.
- ▶ AutoLRS: Automatic Learning-Rate Schedule by Bayesian Optimization on the Fly Jin et al. 2021