

# Cristian Robles, Computer Engineering Graduate Student

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EDUCATION	Masters of Science, Computer Engineering, California State University Northridge	May 2026
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COURSES	Robotics and Embedded Systems, FPGA Design, Computer Architecture, Linear Systems, Digital Systems, Digital Electronics, Microprocessor Systems, System on Chip Design, Probability, Data Structures, Differential Equations, Linear Algebra
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SKILLS	C, C++, Assembly, SPI, I2C, UART, PID Control, Kalman Filters, RTOS, FPGA, VHDL, ROS, NASA F' (Flight Software Framework), Linux, Git, GitHub, Matlab, Simulink, Vivado, Solidworks CAD, 3D Printing, OrCAD PSpice, Leadership
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PROJECTS	TI-RSLK Robot Control
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- Developed and fine-tuned a PID control algorithm using the TI RSLK robot and MATLAB, optimizing motor movement and navigation performance.
- Integrated PWM motor control and encoder feedback within the embedded system using Simulink to tune the control system for speed regulation and real-time position tracking for autonomous operation.

### F Prime Embedded Systems Development

- Designed and programmed a mobile robot using NASA's F' (F Prime) flight software framework to send commands from ground data system (GDS) to onboard hardware via I2C communication.
- Developed custom F' components to control motors and control GPIO, enabling real-time robotic movement.

### Kalman Filter Simulation

- Developed and implemented linear Kalman filters in C++ to fuse simulated sensor data, achieving enhanced accuracy in position, speed, and acceleration measurements.

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## EXTRACURRICULAR ACTIVITIES

Aug 2019 — May 2023	Team Lead, CSUN Vex Robotics	Northridge
	<ul style="list-style-type: none"><li>• Engineered C++ code for self-navigating robots, integrating algorithms including PID control, pure pursuit path tracking, and odometry for spatial awareness.</li><li>• Utilized the RTOS functionality of the VEX microcontroller for real-time task scheduling and concurrent execution of sensor readings, motor control, and autonomous routines.</li><li>• Modeled and manufactured multiple mechanical subsystems for competition robots using SolidWorks CAD software, leveraging 3D printing and CNC machining for prototyping and final assembly.</li></ul>	
Aug 2021 — May 2022	President, CSUN Vex Robotics	Northridge
	<ul style="list-style-type: none"><li>• Successfully managed the club during the transition period as school resumed in-person activities following the COVID lockdown.</li><li>• Acted as the team representative in school budget meetings, effectively communicating the team's needs and advocating for necessary resources resulting in a funding increase for robotics supplies.</li><li>• Mentored individuals of all skill levels in robotics concepts through hands-on instruction.</li></ul>	
Jan 2023 — Dec 2023	Systems Subteam Member, CleanBot 3000 (Senior Project)	Northridge
	<ul style="list-style-type: none"><li>• Employed ROS2 for automation of a sanitization robot for NASA's Jet Propulsion Laboratory's clean rooms, integrating technologies like SLAM, serial communication, PID control, and path planning.</li><li>• Collaborated on building a network using a Raspberry Pi and an Ubuntu Server Linux distribution for robotic control in ROS2.</li><li>• Leveraged diagnostic tools including a logic analyzer, oscilloscope, and multimeter to troubleshoot and refine various electronic components, reducing operational downtime.</li></ul>	