Bill of Materials

| Project Name | Gesture Controlled Robotic Arm | | |
|-------------------|--------------------------------|--|--|
| Assembly Name | Mechanical System | | |
| Assembly Revision | 1 | | |
| Date of Approval | | | |
| Total Piece | 45 | | |

| S.NO | Part Name | Assemblies & Subassemblies | Part Description | Quantity | Procurement Details |
|------|-----------------|----------------------------|----------------------------------|----------|---|
| 1 | 3D Printed Body | Enclosure and Main Frame | The main body of the robotic arm | 1 | |
| 2 | Ball Bearings | Enclosure and Main Frame | Ball Bearings | 4 | |
| 3 | M3 Screws | Enclosure and Main Frame | M3 Screws | 12 | |
| 4 | M3 Bolts | Enclosure and Main Frame | M3 Bolts | 12 | |
| 5 | Washers | Enclosure and Main Frame | Washers | 12 | 2 for each bearing |
| 6 | Glue (Hot Glue) | Enclosure and Main Frame | Glue | - | as needed |
| 7 | Velcro Strips | Enclosure and Main Frame | Velcro strips in meters | 4 | helps in removing the arm and relocating it |
| 8 | | | | | |
| 9 | | | | | |
| 10 | | | | | |



