



RoboCup@Home

Forms & Score Sheets

 $\begin{array}{cccc} & Version: \ 2025 & 1 \\ Last \ Build \ Date: \ April \ 15, \ 2025 & Time: \ 856 \end{array}$

2025-04-15

Registration Form



Team name:			
Team leader name:			
Safety first!			
The speed of the robots shot than the local speed limits. pace of humans (6 kph, 3.7	During operation in an ex		_
At any time when operating immediately if there is a remember of the Technical or team to stop the robot, the	note possibility of dangerour Organizational committee	us behavior towards peoplee, an Executive or Trust	le and/or objects. If a refere tee of the federation tells th
If the team does not compimmediately by a decision members can be banned fr RoboCup Federation Truste	of the RoboCup@Home Tom future competitions for	Technical Committee. Fu	erthermore, the team and i
	Robot 1	Robot 2	
Size of the robot			
Emergency button(s)			
Start button			_
Collision avoidance			
Voice of the robot			
Robot speaker system			
Use of external devices			
ASR Bypassing method			
Other safety issues			
Custom containers.			
External Devices: I have read and fully understhe rules in the official Rob	=	atement and agree to it.	Furthermore, I agree to ob
Date & time	$\frac{}{Team\ leader}$		



Test:	Poster Session	Silo
Team name:		-
Referee name:		-

Instructions:

- 1. Please watch all posters carefully.
- 2. There will be a team member for questions about the poster.
- 3. After viewing the poster and asking your questions you may have, please fill in the evaluation sheet below.
- 4. Is not allowed to evaluate your own team.
- 5. You may use the space below "Remarks:" to take notes for yourself.
- 6. Enter your team's name ("Team name") and your name ("referee name") on top of the sheet.
- 7. Sign the form using either "Referee" or "Team leader" slots at the bottom.

Evaluation sheet

T.	Overall score
Team	of poster (0-10)
Chief Scientist Office	
EPFL@Home	
eR@sers	
FBOT@Home	
Gentlebots	
Hibikino-Musashi@Home	
KIARO	
LAR@Home	
LASR	
LCASTOR	
LyonTech	
NimbRo@Home	
Pumas	
PUMAS-DSPL	
RoboCanes-VISAGE	
RoboFEI@Home	
RoBorregos rUNSWeep	
Serious Cybernetics Corporation (SCC)	
Sinfonia Uniandes	
SKUBA	
SOBITS	
SocRob@Home	
SUTURO-VaB	
Team of Bielefeld (ToBi)	
Tech United Eindhoven	
Tidyboy-DSPL	
Tidyboy-OPL	
Tinker	
TRAIL	
UT Austin Villa@Home	

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Date & time	$\overline{Referee}$	Team leader



$\Gamma \mathrm{est}$:	Help Me Carry	
Team name:		
Referee name:		

Action	Score	1^{st} try	2^{nd} trv	3^{rd} trv
Main Goal	Score	1 61 y	2 ti y	5 try
Following the person to the car	300			
Perceiving the correct beg (visualize on screen or say which one)	15			
Picking up the correct bag	100			
Avoiding the crowd of people obstructing the path	50			
Avoiding the small object on the ground	50			
Avoiding the hard-to-see object	50			
Avoiding the area blocked with retractable barriers	50			
Bonus rewards				
Re-reaching the starting location	200			
Joining and staying in the queue on the way to the arena	300			
Penalties				
Dropping the bag	-50			
Deus Ex Machina Penalties				
Rediscovering the operator by natural interaction	-50			
Rediscovering the operator by unnatural interaction	-100			
Rediscovering the operator by asking them to come back	-150			
Rediscovering the operator by direct contact	-200			
Special Penalties & Bonuses				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	111			
Recordings				
Duration (limit: 5:00 minutes)				
Restart after (sec)				
Score per try	1115			
Total Score	1226			
Remarks:				

 $\overline{Date~\mathcal{E}~time}$ $\overline{Referee}$ $\overline{Team~leader}$



Test:	General Purpose Service Robot			RC	@Hom
Team name:					
Referee name:					
		G		and .	and .
Action		Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal Executing the tas	k associated with each command	3×400			
Bonus Rewards Understanding a	command given by a non-expert operator	3×100			
Deus Ex Machi	ina Penalties				
Using a custom of	perator	3×-50			
Bypassing speech recognition		3×-50			
	nan to perform parts of the task will apply a coording to similar penalties in other Stage I to	-			
Special Penaltie	es & Bonuses				
Not attending		-500			
Using alternative	start signal	-100			
Outstanding perfe	ormance	150			
Recordings					
Duration (limit: 5	5:00 minutes)				
Restart after (sec					
Score per try		1500			
Total Score Remarks:		1650			

Date & time	Referee	$\overline{Team\ leader}$

 $Date \ \ \mathcal{U} \ time$



$\Gamma\!\mathrm{est}$:	Receptionist			Ro	©Home
Team name:					
Referee name:					
Action		Score	1^{st} try	2^{nd} try	3^{rd} try
$\overline{Main~Goal}$					
Offer a free seat to	the new guest	2×100			
Show the guest aro	und (navigate to the beverage area and living room)	2×30			
Look in the direct	ion of navigation or at the navigation goal	2×15			
Tell position of fav	vorite drink	2×20			
Look at the person	n talking	2×75			
Introduce both gu	ests to each other	180			
Bonus Rewards					
Open the entrance	e door for a guest	2×200			
State a similarity	between an interest between two or more persons	50			
Describe the first groom (per correct	guest to the second guest before reaching the living visual attribute)	4×30			
Penalties					
Wrong guest inford drink or interest)	mation was memorized (continue with wrong name,	6×-20			
	guest to the second guest before reaching the living et visual attribute)	4×-30			
Introduce the wro	ng persons	-120			
Deus Ex Machi	na				
Alternative HRI		2×-75			
Not recognizing pe	eople	2×-200			
$Special\ Penaltie$	$s \ {\it \& Bonuses}$				
Not attending		-500			
Outstanding perfo	rmance	123			
Recordings					
Duration (limit: 6	:00 minutes)				
Restart after (sec)					
Score per try		1230			
Total Score		1353			
Remarks:					

 $Team\ leader$

Referee

Robo Cup @Home	Ro	boCup @Home
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Test:	Storing Groceries
Team name:	
Referee name:	

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal				
Navigating to the table	15			
Perceiving object and categorizing it correctly	5×15			
Picking up an object for transportation to the cabinet	5×50			
Perceiving objects in shelf and saying on which layer the currently	y 5×15			
handled object should be placed				
Placing an object in the cabinet	5×15			
Placing an object next to similar objects on the cabinet	5×50			
Opening the first cabinet door	200			
Opening the second cabinet door	100			
Pouring cereal into the container	300			
Bonus Rewards				
Picking up an object from the shopping bag	5×50			
Picking up a tiny object	70			
Placing a tiny object	30			
Picking up a heavy object	70			
Placing a heavy object	30			
Autonomously Picking any Object	50			
Autonomously Placing any Object	50			
Deus Ex Machina Penalties				
Perceiving object and categorizing it wrongly	10×-15			
A human handing an object over to the robot	5×-50			
A human placing an object in the cabinet	5×-15			
A human placing an object in the cabinet next to similar objects	5×-50			
A human pointing at a target location	5×-25			
A human opening the cabinet door	2×-100			
Spilling cereal while pouring	-100			
Leaving cereal in the box	-100			
A human pouring cereal in the bowl	-300			
Special Penalties & Bonuses				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	189			
Recordings	100			
Duration (limit: 7:00 minutes)				
Restart after (sec)				
Technical of all of (Sec)				
Score per try	1890			
Total Score	2079			

Remarks:		
Date & time	Referee	Team leader



Test:	Clean the Table
Team name:	
Referee name:	

Action		Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal					
Navigate to the table to pick up items		15			
Picking up the cup, bowl and drinks for	transportation	4×50			
Picking up cutlery (spoon, fork) for train	nsportation	2×80			
Picking up the plate for transportation	-	100			
Placing the tableware and cutlery inside	e the dishwasher	5×50			
Placing an item correctly (cleanable, coin the dishwasher	onvenient like a human would	d) 5×75			
Placing a drink inside the trash bin		2×50			
Bonus Rewards					
Pulling and pushing the dishwasher rack	k	2×100			
Opening and closing the dishwasher doc		2×200			
Picking up the dishwasher tab for trans	portation to the dishwasher	100			
Placing the dishwasher tab inside the d		or 200			
the tab					
Wiping the area where the drink was		2×50			
Autonomously Picking any Object		50			
Autonomously Placing any Object		50			
Deus Ex Machina Penalties					
Handing cup, bowl and drinks over to t	he robot	3×-50			
Handing cutlery over to the robot		2×-80			
Handing the plate over to the robot		-100			
Having a human place an object in the	dishwasher	5×-50			
Having a human place a drink inside th		2×-50			
A human pointing at the trash bin		2×-25			
Special Penalties & Bonuses					
Not attending		-500			
Using alternative start signal		-100			
Outstanding performance		230			
Recordings		,,,,,			
Duration (limit: 10:00 minutes)					
Restart after (sec)					
Score per try		2300			
Total Score		2530			
Remarks:					
Date & time	Referee		Team le	eader	



Test:	Enhanced General Purpose Service Robot				@Home
Team name:					
Referee name:					
Action		Score	1^{st} try	2^{nd} try	3^{rd} try
•	be repeated unlimited times)				
=	tate an encountered problem	3×150			
Solve a problem		3×650			
Penalties					
Find repeated pro		-100			
	problem category for the 2nd time	-300			
	problem category for the 3rd (or more) time	-500			
These Penalties Machina Penalties	are applied before any percentage based Dev s	us Ex			
Deus Ex Machi	na Penalties				
Asking for location	n of a problem	3×-150			
_	an to perform parts of the task will apply a y according to similar penalties in other				
Stage II tests.		3×-650			
Special Penaltie	$es~ {\it \&}~ Bonuses$				
Not attending		-500			
Using alternative		-100			
Outstanding perfo	ormance	240			
Recordings Duration (limit: 1 Restart after (sec)	,				
Score per try		2400			
Total Score		2640			
Referee Informarobot in remarks	ation: Note each problem (category, item, lo	ecation) and ma	ark if the	y are stat	ed by the
Remarks:					
Date & time			Team le	eader	

Remarks:



Test:	Restaurant	@H
Team name:		
Referee name:		

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Regular Rewards			<u> </u>	
Detect calling or waving customer	2×100			
Reach a customer's table without prior guidance/training	2×100			
Understand and confirm the order received to the customer	2×200			
Communicate the order to the barman	2×100			
Return to the customer table with the order	2×100			
Serve the order to the customer	2×200			
Bonus Rewards				
Use an unattached tray to transport	2×200			
Regular Penalties				
Being guided to a table	2×-200			
Not making eye-contact when taking an order	2×-80			
Not reaching the bar (barman has to move from behind the bar to intera	ct 2×-80			
with the robot)				
Deus ex Machina Penalties				
Asking the Barman to handover object to the robot	4×-50			
Guest needing to take the object from a tray or the robot's hand	4×-50			
Being told/pointed where is a table/Kitchen-bar	2×-100			
Special Penalties & Bonuses				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	200			
Recordings				
Duration (limit: 15:00 minutes)				
Restart after (sec)				
Score per try	2000			
Total Score	2200			



Test:	New HRI	
Team name:		
Referee name:		

Action	\mathbf{Score}	1^{st} try	2^{nd} try	3^{rd} try
Regular Rewards				
Receive an object from the operator	5×100			
Place an object at the correct location	5×100			
Penalties				
Place an object at the wrong location	5×-75			
Deus Ex Machina Penalties				
Instruct the user how to hand over an object	5×-75			
$Special\ Penalties\ {\it \&Bonuses}$				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	100			
Recordings				
Duration (limit: 10:00 minutes)				
Restart after (sec)				
Score per try	1000			
Total Score	1100			

Remarks:

Date & time	$\overline{Referee}$	$\overline{Team\ leader}$



T			RoboCup @Home
Test:	Final Demonstration		
Team name:		_	
Referee name:		_	
Action		Score	Single try
•	n be repeated unlimited times)		
	state an encountered EGPSR problem	3×150	
Solve a EGPSR p		3×650	
	r of the Apartment	600	
Closing the Dishw		600	
Closing a Cabinet	5 Door	300	
Custom Task			
Custom Task			
Custom Task			
Penalties			
=	GPSR problem category	-100	
	EGPSR problem category for the 2nd time	-300	
	EGPSR problem category for the 3rd (or more) time	-500	
Deus Ex Mach			
Asking for location	_	3×-150	
,	lies if the robot continues scoring afterwards)	-50	
_	nan to perform parts of the task will apply a		
	y according to similar penalties in other		
Stage II tests.		3×-650	
Recordings			
Duration (limit: 1	,		
Restart after (sec			
Total Score		3900 _	
Referee Inform robot in remarks	ation: Note each problem (category, item, location)	and mark if the	hey are stated by the
Remarks:			
Date $& time$	Referee	Team	leader