



RoboCup@Home

Forms & Score Sheets

 $\begin{array}{cccc} & Version: \ 2025 & 1 \\ Last \ Build \ Date: \ April \ 1, \ 2025 & Time: \ 644 \end{array}$

2025-03-18

Registration Form



Team name:			
Team leader name:			
Safety first!			
_	. During operation in an e		robot is not allowed to go faster ans it may not exceed a walking
immediately if there is a rea	mote possibility of dangeror or Organizational committe	us behavior towards pecee, an Executive or Tr	owners have to stop the robot ople and/or objects. If a referee, ustee of the federation tells the stopped <i>immediately</i> .
immediately by a decision	of the RoboCup@Home Trom future competitions f	Technical Committee.	from the ongoing competition Furthermore, the team and its an a year by a decision of the
	Robot 1	Robot 2	
Size of the robot			
Emergency button(s)			
Start button			
Collision avoidance			
Voice of the robot			
Robot speaker system			
Use of external devices			
ASR Bypassing method			
Other safety issues			
Custom containers.			
External Devices:			
I have read and fully under the rules in the official Rol		catement and agree to i	t. Furthermore, I agree to obey
Date & time	$Team\ leader$		



Test:	Poster Session	enon
Team name:		-
Referee name:		-

Instructions:

- 1. Please watch all posters carefully.
- 2. There will be a team member for questions about the poster.
- 3. After viewing the poster and asking your questions you may have, please fill in the evaluation sheet below.
- 4. Is not allowed to evaluate your own team.
- 5. You may use the space below "Remarks:" to take notes for yourself.
- 6. Enter your team's name ("Team name") and your name ("referee name") on top of the sheet.
- 7. Sign the form using either "Referee" or "Team leader" slots at the bottom.

Evaluation sheet

T.	Overall score
Team	of poster (0-10)
Chief Scientist Office	
EPFL@Home	
eR@sers	
FBOT@Home	
Gentlebots	
Hibikino-Musashi@Home	
KIARO	
LAR@Home	
LASR	
LCASTOR	
LyonTech	
NimbRo@Home	
Pumas	
PUMAS-DSPL	
RoboCanes-VISAGE	
RoboFEI@Home	
RoBorregos rUNSWeep	
Serious Cybernetics Corporation (SCC)	
Sinfonia Uniandes	
SKUBA	
SOBITS	
SocRob@Home	
SUTURO-VaB	
Team of Bielefeld (ToBi)	
Tech United Eindhoven	
Tidyboy-DSPL	
Tidyboy-OPL	
Tinker	
TRAIL	
UT Austin Villa@Home	

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Test:	Help Me Carry
Team name:	
Referee name:	

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal				
Following the person to the car	300			
Perceiving the correct beg (visualize on screen or say which one)	15			
Picking up the correct bag	100			
Avoiding the crowd of people obstructing the path	50			
Avoiding the small object on the ground	50			
Avoiding the hard-to-see object	50			
Avoiding the area blocked with retractable barriers	50			
Bonus rewards				
Re-reaching the starting location	200			
Joining and staying in the queue on the way to the arena	300			
Penalties				
Dropping the bag	-50			
Deus Ex Machina Penalties				
Rediscovering the operator by natural interaction	-50			
Rediscovering the operator by unnatural interaction	-100			
Rediscovering the operator by asking them to come back	-150			
Rediscovering the operator by direct contact	-200			
$Special\ Penalties\ {\it \&Bonuses}$				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	111			
Recordings				
Duration (limit: 5:00 minutes)				
Restart after (sec)				
Score per try	1115			
Total Score	1226			
Remarks:				

 $Date \ \ \mathcal{U} \ time$ Referee $Team\ leader$

Duration (limit: 5:00 minutes)

Restart after (sec)

Score per try



				Ro	boCup @Home
Test:	General Purpose Service Robot				
Team name:					
Referee name:					
Action		Score	1^{st} try	2^{nd} try	3^{rd} try
$Main\ Goal$					
Executing the task	k associated with each command	3×400			
Bonus Rewards					
Understanding a o	command given by a non-expert operator	3×100			
Deus Ex Machi	na Penalties				
Using a custom of	perator				
Bypassing speech	recognition	3×-50			
_	nan to perform parts of the task will apply a coording to similar penalties in other Stage I to	_			
Special Penaltie	es & Bonuses				
Not attending		-500			
Using alternative	start signal	-100			
Outstanding perfe	ormance	150			
Recordings					

Total Score 1650 Remarks:

1500

Date & time	$\overline{Referee}$	Team leader
RoboCun@H	ome Forms & Score Sheets / Draft version for Rob	oCup 2025 (Revision 2025-03-18 1)

 $Date \ \ \mathcal{U} \ time$



$\Gamma\!\mathrm{est}$:	Receptionist			Ro	©Home
Team name:					
Referee name:					
f Action		Score	1^{st} \mathbf{try}	2^{nd} try	3^{rd} try
Main Goal					
Offer a free seat to	the new guest	2×100			
=	und (navigate to the beverage area and living room)	2×30			
	ion of navigation or at the navigation goal	2×15			
Tell position of fav		2×20			
Look at the person	9	2×75			
Introduce both gu	ests to each other	180			
$Bonus\ Rewards$					
Open the entrance	9	2×200			
	between an interest between two or more persons	50			
Describe the first groom (per correct	guest to the second guest before reaching the living visual attribute)	4×30			
Penalties					
Wrong guest infordrink or interest)	mation was memorized (continue with wrong name,	6×-20			
	guest to the second guest before reaching the living et visual attribute)	4×-30			
Introduce the wro	ng persons	-120			
Deus Ex Machi	na				
Alternative HRI		2×-75			
Not recognizing pe	eople	2×-200			
$Special\ Penaltie$	$s \ {\it \& Bonuses}$				
Not attending		-500			
Outstanding perfo	rmance	123			
Recordings					
Duration (limit: 6	,				
Restart after (sec)					
Score per try		1230			
Total Score		1353			
Remarks:					
Remarks:					

 $Team\ leader$

Referee



Test:	Storing Groceries
Team name:	
Referee name:	

Action		Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal					
Navigating to the table		15			
Perceiving object and categorizing it cor	rectly	5×15			
Picking up an object for transportation	to the cabinet	5×50			
Perceiving objects in shelf and saying of	on which layer the currently	5×15			
handled object should be placed					
Placing an object in the cabinet		5×15			
Placing an object next to similar objects	on the cabinet	5×50			
Opening a cabinet door		2×100			
Pouring cereal into the container		300			
Bonus Rewards					
Picking up an object from the shopping	bag	50			
Picking up a tiny object		70			
Placing a tiny object		30			
Picking up a heavy object		70			
Placing a heavy object		30			
Deus Ex Machina Penalties					
A human handing an object over to the	robot	5×-50			
A human placing an object in the cabine	et	5×-15			
A human placing an object in the cabine	et next to similar objects	5×-50			
A human pointing at a target location		5×-25			
A human opening the cabinet door		2×-100			
Spilling cereal while pouring		-100			
Leaving cereal in the box		-100			
A human pouring cereal in the bowl		-300			
Special Penalties & Bonuses					
Not attending		-500			
Using alternative start signal		-100			
Outstanding performance		149			
Recordings					
Duration (limit: 7:00 minutes)					
Restart after (sec)					
Score per try		1490			
Score per try		1490			
Total Score		1639			
Remarks:					
Date & time	 Referee		Team le	eader	

RoboCup @Home
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Test:	Clean the Table
Team name:	
Referee name:	

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal				
Navigate to the table to pick up items	15			
Picking tableware (cup, bowl, plate) for transportation to the dishwasher	3×50			
Picking up cutlery (spoon, fork) for transportation to the dishwasher	2×80			
Picking up a drink for transportation to the trash bin	2×50			
Placing the tableware and cutlery inside the dishwasher	5×50			
Placing an item correctly (cleanable, convenient like a human would) in the dishwasher	5×75			
Placing a drink inside the trash bin	2×50			
Bonus Rewards				
Pulling out the dishwasher rack	100			
Pushing in the dishwasher rack	100			
Opening the dishwasher door	200			
Closing the dishwasher door	200			
Picking up the dishwasher tab for transportation to the dishwasher	100			
Placing the dishwasher tab inside the dishwasher's hatch intended for the tab	200			
Wiping the area where the drink was	2×50			
Deus Ex Machina Penalties				
Handing tableware over to the robot	3×-50			
Handing cutlery over to the robot	2×-80			
Handing a drink over to the robot	2×-50			
Having a human place an object in the dishwasher	5×-50			
Having a human place a drink inside the trash bin	2×-50			
A human pointing at the trash bin	2×-25			
Special Penalties & Bonuses				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	215			
Recordings				
Duration (limit: 10:00 minutes)				
Restart after (sec)				
Score per try	2150			
Total Score	2365			

Remarks:

$ate \ \mathcal{E} \ time$	Referee	$Team\ leader$



Test:	Enhanced General Purpose Service Robot			Ro	boCup @Home
	Emilanced General I urpose Service Robot				
Team name:					
Referee name:					
Action		Score	1^{st} try	2^{nd} try	3^{rd} try
Main Goal (car	be repeated unlimited times)				
Find and clearly s	state an encountered problem	3×150			
Solve a problem		3×650			
Penalties	11	100			
Find repeated pro		-100			
	problem category for the 2nd time	-300 500			
	problem category for the 3rd (or more) time	-500			
Deus Ex Machi Asking for locatio		<i>3</i> ×- <i>150</i>			
=	an to perform parts of the task will apply a	<i>5</i> ∧-1 <i>00</i>			
~	y according to similar penalties in other				
Stage II tests.		3×-650			
Special Penaltie	$es~\mathcal{E}~Bonuses$				
Not attending		-500			
Using alternative	start signal	-100			
Outstanding perfe	ormance	240			
Recordings					
Duration (limit: 1	10:00 minutes)				
Restart after (sec					
Score per try		2400			
- 0					
Total Score		2640			
Referee Informates	ation: Note each problem (category, item, loca	ation) and ma	ark if the	y are stat	ed by the
Remarks:					
Date & time	$\overline{Referee}$	_	$\overline{Team \ l}$	eader	



Restaurant	@Ног

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Regular Rewards		-	-	-
Detect calling or waving customer	2×100			
Reach a customer's table without prior guidance/training	2×100			
Take an order.	2×300			
Serve an order.	2×300			
Bonus Rewards				
Use an unattached tray to transport	2×200			
Regular Penalties				
Not making eye-contact when taking an order	2×-80			
Not reaching the bar (barman has to move from behind the bar to inte	eract 2×-80			
with the robot)				
Deus ex Machina Penalties				
Being guided to a table	2×-200			
Asking the Barman to handover object to the robot	4×-50			
Guest needing to take the object from a tray or the robot's hand	4×-50			
Being told/pointed where is a table/Kitchen-bar	2×-100			
$Special\ Penalties\ {\it \&Bonuses}$				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	200			
Recordings				
Duration (limit: 15:00 minutes)				
Restart after (sec)				
Score per try	2000			
Total Score	2200			

Remarks:

Date & time	$\overline{Referee}$	$\overline{Team\ leader}$



Test:	New HRI	
Team name:		_
Referee name:		_

Action	Score	1^{st} try	2^{nd} try	3^{rd} try
Regular Rewards				
Doing stuff	1500			
$Special\ Penalties\ {\it \&Bonuses}$				
Not attending	-500			
Using alternative start signal	-100			
Outstanding performance	150			
Recordings				
Duration (limit: 10:00 minutes)				
Restart after (sec)				
Score per try	1500			
Total Score	1650			

Remarks:

$Date \ \mathcal{C} \ time$	$\overline{Referee}$	Team leader



_			RoboCup @Home
Test:	Final Demonstration		
Team name:		_	
Referee name:		_	
Action		Score	Single try
	n be repeated unlimited times)		
=	state an encountered EGPSR problem	<i>3</i> ×150	
Solve a EGPSR p		3×650	
	r of the Apartment	600	
Closing the Dishw		600	
Closing a Cabinet	Door	300	
Penalties			
=	SPSR problem category	-100	
- ·	EGPSR problem category for the 2nd time	-300	
Solving repeated	EGPSR problem category for the 3rd (or more) time	-500	
Deus Ex Mach	ina Penalties		
Asking for locatio	n of a problem	3×-150	
Instructing a hum	nan to perform parts of the task will apply a		
percentage penalt	y according to similar penalties in other		
Stage II tests.		3×-650	
Recordings Duration (limit: 1 Restart after (sec	•		
Total Score		<i>3900</i> _	
Referee Inform robot in remarks	ation: Note each problem (category, item, location) a	and mark if t	hey are stated by the
Remarks:			
Date & time		\overline{Team}	leader