



RoboCup@Home

Rules & Regulations

Version: 2026 Rev-1
Last Build Date: October 9, 2025 Time: 862
Last Revision Date: 2025-10-09

About this rulebook

This is the official rulebook of the RoboCup@Home competition 2026. The rulebook has been written by the 2026 RoboCup@Home Technical Committee.

How to cite this rulebook

If you refer to RoboCup@Home and this rulebook in particular, please cite:

Justin Hart, Alexander Moriarty, Katarzyna Pasternak, Johannes Kummert, Matteo Leonetti, Luis Contreras, Alina Hawkin, Vanessa Hassouna, Leroy Ruegemer, Akinobu Mitzutani, Tiago Ribeiro “Robocup@Home 2026: Rule and regulations,” <https://github.com/RoboCupAtHome/RuleBook/releases/download/2025.1/rulebook.pdf>, 2026.

```
@misc{rulebook_2025,  
  author = {Hart, Justin and Moriarty, Alexander and Pasternak, Katarzyna  
            and Kummert, Johannes and Leonetti, Matteo and Contreras, Luis  
            and Hawkin, Alina and Hassouna, Vanessa and Ruegemer, Leroy  
            and Mitzutani, Akinobu and Ribeiro, Tiago},  
  title = {RoboCup@Home 2025: Rules and Regulations},  
  year = {2025},  
  howpublished = {\url{https://github.com/RoboCupAtHome/RuleBook/releases/tag/2025.1}},  
}
```

Acknowledgments

We would like to thank the members of the Technical Committee who put up the rules and the Organizing Committee who organizes the competition. People that have been working on this rulebook as members of one of the league's committees (in alphabetical order):

Adam Golding	Justin Hart	Peter van Dooren
Akinobu Mizutani	Katarzyna Pasternak	Raphael Memmesheimer
Alex Mitrevski	Komei Sugiura	Riccardo Polvara
Alexander Moriarty	Leander von Seelstrang	Sammy Pfeiffer
Alina Hawkin	Leroy Ruegemer	Sebastian Meyer zu Borgsen
Caleb Rascon	Loy van Beek	Sven Wachsmuth
Fagner Pimentel	Luca Iocchi	Tatsuya Matsushima
Florian Lier	Luca Lach	Tijn van der Zant
Hiroyuki Okada	Luis Contreras	Vanessa Hassouna
Johannes Kummert	Matteo Leonetti	Yuma Yoshimoto
Juan Diego Pena Narvaez	Mauricio Matamoros	Yuqian Jiang
Juan Jose Garcia	Maxime St-Pierre	

We would also like to thank all the people who contributed to the RoboCup@Home league with their feedback and comments. People that have been working on this rulebook as members of the league (in alphabetical order):

Lars Janssen	Syed Ali Raza
Mark Finean	
Matthijs van der Burgh	

Contents

1	Introduction	1
1.1	RoboCup	1
1.2	RoboCup@Home	1
1.3	Organization	1
1.3.1	Executive Committee — rc-home-ec@lists.robocup.org	1
1.3.2	Technical Committee — rc-home-tc@lists.robocup.org	2
1.3.3	Organizing Committee — rc-home-oc@lists.robocup.org	2
1.4	Infrastructure	2
1.5	Leagues	2
1.5.1	Open Platform League (OPL)	3
1.6	Competition	3
1.7	Awards	3
1.7.1	Winner of the Competition	3
1.7.2	Best Human-Robot Interface Award	3
1.7.3	Best Poster Award	3
1.7.4	Open Challenge Award	4
1.7.5	Skill Certificates	4
1.7.6	Open-source software award	4
2	Concepts Behind the Competition	5
2.1	Lean Set of Rules	5
2.2	Autonomy & Mobility	5
2.3	Aiming for Applications	5
2.4	Social Relevance	5
2.5	Scientific Value	6
2.6	Time Constraints	6
2.7	No Standardized Scenario	6
2.8	Attractiveness	6
2.9	Community	6
2.10	Desired Abilities	6
3	General Rules and Regulations	9
3.1	Team Registration and Qualification	9
3.1.1	Registration and Qualification Process	9
3.1.2	Team Description Paper	9
3.1.3	Qualification Video	10
3.1.4	Team Website	10
3.1.5	Qualification	11
3.1.6	Participation Confirmation	11

3.2	Scenario	11
3.2.1	RoboCup@Home Arena	12
3.2.2	Walls, Doors, and Floor	12
3.2.3	Furniture	12
3.2.4	Changes to the <i>Arena</i>	13
3.2.5	Objects	14
3.2.6	Predefined Rooms and Locations	15
3.2.7	Predefined Person Names	15
3.2.8	Wireless network	16
3.3	Robots	16
3.3.1	Number of Robots	16
3.3.2	Appearance and Safety	16
3.3.3	Robot Specifications for the Open Platform League	16
3.4	External devices	17
3.4.1	On-site External Computing	18
3.4.2	On-line external computing	18
3.5	Organization of the Competition	18
3.5.1	Stage System	18
3.5.2	Schedule	19
3.5.3	Scoring System	19
3.6	Procedure during Tests	20
3.6.1	Safety First!	20
3.6.2	Maximum number of team members	20
3.6.3	Fair play	20
3.6.4	Expected Robot's Behavior	21
3.6.5	Robot Autonomy and Remote Control	21
3.6.6	Collisions	21
3.6.7	Removal of robots	21
3.6.8	Start Signal	22
3.6.9	Restart Rule	22
3.6.10	Entering and leaving the <i>Arena</i>	23
3.6.11	Gestures	23
3.6.12	Referees	23
3.6.13	Operators	23
3.6.14	Time limits	24
3.7	Deus Ex Machina	24
3.7.1	Procedure	24
3.7.2	Scoring	25
3.7.3	Bypassing Automatic Speech Recognition	26
3.8	Special penalties and bonuses	26
3.8.1	Penalty for not attending	26
3.8.2	Extraordinary penalties	27
3.8.3	Bonus for outstanding performance	27
3.9	Open Challenge	27
3.9.1	Procedure	28

4	Setup and Preparation	29
4.1	General Setup	29
4.2	Welcome Reception	30
4.3	Poster Teaser Session	30
4.3.1	Poster teaser session	30
4.4	Robot Inspection	31
5	Tests in Stage I	33
5.1	Help Me Carry	35
5.2	General Purpose Service Robot	38
5.3	Receptionist	41
5.4	Storing Groceries	44
6	Tests in Stage II	47
6.1	Clean the Table	49
6.2	Enhanced General Purpose Service Robot	52
6.3	Restaurant	54
6.4	Give Me a Hand	59
7	Finals	61
7.1	Scoring	61
7.1.1	Task	61
7.1.2	The Show Must Go On	62
7.1.3	Commentator	62
7.2	Final Ranking and Winner	62
	Index	62

Chapter 1

Introduction

1.1 RoboCup

ROBOCUP is an international joint project to promote AI, robotics, and related fields. It is an attempt to foster AI and intelligent-robotics research by providing standard problems where a wide range of technologies can be integrated and examined. More information can be found at <http://www.robocup.org/>.

1.2 RoboCup@Home

The ROBOCUP@HOME league aims to develop service and assistive robot technology with high relevance for future personal domestic applications. It is the largest international annual competition for autonomous service robots and is part of the RoboCup initiative. A set of benchmark tests is used to evaluate the abilities and performance of different robots in a realistic, non-standardized home environment setting. The focus is on, but is not limited to, the following domains: human-robot interaction and cooperation, navigation and mapping in dynamic environments, computer vision and object recognition under natural light conditions, object manipulation, adaptive behaviors, behavior integration, ambient intelligence, standardization and system integration. The competition is co-located with the RoboCup symposium.

1.3 Organization

@HOME is organized into three subcommittees. The current members of the committees are listed at <https://athome.robocup.org/committees/>.

1.3.1 Executive Committee — `rc-home-ec@lists.robocup.org`

The *executive committee* (EC) consists of members of the board of trustees, and representatives of each activity area, and supervises both the TC and OC. The committee is responsible for the long-term planning of the league and cast the final vote in all decisions within the competition, including those pertaining to any of the committees and any other affair that requires a qualified vote. Additionally, the EC must act when any of the committees fail, as it responds to the Trustee board and directs the league accordingly.

1.3.2 Technical Committee — rc-home-tc@lists.robocup.org

The *technical committee* (TC) is responsible for the rules of the league; its main focus is writing the rulebook and refereeing. The members of the *executive committee* (EC) are also members of the *technical committee* (TC).

1.3.3 Organizing Committee — rc-home-oc@lists.robocup.org

The *organizing committee* (OC) is responsible for the organization of the competition, namely it creates the schedule and provides information about the scenarios. The *Local Organizing Committee* (LOC), on the other hand, is responsible for the setup and organization of the competition venue.

1.4 Infrastructure

RoboCup@Home Mailing List The official @HOME mailing list can be found at robocup-athome@lists.robocup.org. You can subscribe to the mailing list at: <https://lists.robocup.org/mm/lists/robocup-athome.lists.robocup.org/>

RoboCup@Home Web Page The official @HOME website that also hosts this rulebook can be found at <https://athome.robocup.org/>

RoboCup@Home Rulebook Repository The official @HOME *Rulebook Repository* is where rules are publicly discussed before applying changes. The entire @HOME community is welcome and encouraged to actively participate in creating and discussing the rules. The *Rulebook Repository* is hosted at <https://github.com/RoboCupAtHome/RuleBook/>

RoboCup@Home Telegram Group The official @HOME *Telegram Group* is a communication channel for the @HOME community where rules are discussed, announcements are made, and questions are answered. Beyond supporting the technical aspects of the competition, the group is a meeting point to stay in contact with the community, foster knowledge exchange, and strengthen relationships. The *Telegram Group* can be reached at <https://t.me/RoboCupAtHome>

RoboCup@Home Wiki The official @HOME *Wiki* is meant to be a central place to collect information on all topics related to the @HOME league. The wiki was set up to simplify and unify the exchange of relevant information; this includes, but is not limited to, hardware, software, media, data, and more. The *Wiki* can be reached at <https://github.com/RoboCupAtHome/AtHomeCommunityWiki/wiki>

1.5 Leagues

@HOME consists of a single league, meaning teams have complete freedom in selecting their robot platform. The official league and its name is:

- *Open Platform League* (OPL)

1.5.1 Open Platform League (OPL)

The *Open Platform League* (OPL) has followed the same core philosophy since the foundation of @HOME. Its main goal is to develop and test robots that can assist humans in domestic environments. With no hardware constraints, the OPL offers teams full freedom to design and configure their own robots. This openness allows for a wide range of approaches, making the league accessible to both new and experienced teams. In this league, robots are pushed to their performance limits without being restricted by predefined design requirements.

1.6 Competition

The competition consists of two *Stages* and a *Final*. Each stage consists of a series of *Tests* that are being held in a daily life environment. The best teams from *Stage I* advance to *Stage II*, which consists of more difficult tests. The competition ends with the *Final*, where only the two highest-ranked teams of each league compete to select the winner.

1.7 Awards

The @HOME league features the *awards* described below. Note that all awards need to be approved by the *RoboCup Federation* (RCF); based on a decision by the RCF, some of them may not be awarded

1.7.1 Winner of the Competition

For each league, there will be 1st, 2nd, and 3rd place award trophies (or only 1st and 2nd place trophies if the number of teams in a league is eight or fewer).

1.7.2 Best Human-Robot Interface Award

To honor outstanding human-robot interfaces developed for interacting with robots in @HOME, a special *Best Human-Robot Interface Award* may be awarded to one of the participating teams. Special attention is given to interfaces that are open and available to the @HOME community.

The @HOME *executive committee* (EC) members nominate a set of candidates for the award and the TC elects the winner. A TC member whose team is among the nominees is not allowed to vote. No *Best Human-Robot Interface Award* is given if the EC decides there is no outstanding interface and thus no nominees.

1.7.3 Best Poster Award

To promote scientific knowledge exchange and reward teams for their efforts in presenting research contributions, all scientific posters are evaluated for the *Best OPL Poster Award*.

Candidate posters must present innovative and state-of-the-art research in a field directly applicable to @HOME, with clear and easy-to-understand results. In addition to being attractive and well-rated in the *Poster Session* (see Section 4.3), the research must also have a measurable impact on the team's performance during the competition.

The @HOME *executive committee* (EC) members nominate a set of candidates for the award and the TC elects the winner. A *technical committee* (TC) member whose team is among the nominees is not allowed to vote.

1.7.4 Open Challenge Award

To encourage teams to showcase their research to other teams during the competition off-hours, @HOME grants the *Best Open Challenge Award* to the team that presents the best open demonstration during the competition. This award is given only if a team demonstrates innovative research relevant to the global objectives of @HOME.

The @HOME TC members, with a recommendation from the team leaders, nominate a set of candidates for the award. The EC decides whether the award should be granted and then elects the winner. A *technical committee* (TC) member is not allowed to nominate their own team without a recommendation from the team leaders.

1.7.5 Skill Certificates

The @HOME league features certificates for best demonstrated skills in *Navigation*, *Manipulation*, *Person Recognition*, and *Natural Language Processing*. A team receives the certificate if it scores at least 75% of the attainable points for that skill across all tests and challenges. For example, if a robot scores manipulation points during the *Help-me-Carry* test to open the door, that will count for the *Manipulation* certificate. Note that the certificate will only be awarded if the team is *not* the overall winner of the competition.

1.7.6 Open-source software award

Since Nagoya 2017, RoboCup@Home awards the best contribution to the community by means of an open-source software solution. To be eligible for the award, the software must be easy to read, well-documented, follow standard design patterns, actively maintained, and meet the IEEE software engineering metrics of scalability, portability, maintainability, fault tolerance, and robustness. Additionally, the open-source software must be available as a framework-independent standalone library to ensure it can be reused with any software architecture.

Candidates must submit their application to the *technical committee* (TC) at least one month before the competition via a short paper (maximum 4 pages), in the same format as the *Team Description Paper* (TDP) (see Section 3.1.2), including a brief explanation of the approach, comparison with state-of-the-art techniques, statement of the used metrics and software design patterns, and the name of the teams and other collaborators using the software.

The @HOME *executive committee* (EC) members nominate a set of candidates for the award and the *technical committee* (TC) elects the winner. A *technical committee* (TC) member whose team is among the nominees is not allowed to vote.

Chapter 2

Concepts Behind the Competition

A set of conceptual key criteria forms the foundation of the @HOME competition. These criteria represent a shared understanding of the general concept of the competition. The specific rules are detailed in the @HOME Rules & Regulations.

2.1 Lean Set of Rules

To enable diverse, general, and transmissible approaches in the @HOME competition, the rule set should be as concise as possible. However, it must also be specific enough to eliminate ambiguity and prevent disagreements during the competition. If discrepancies or multiple interpretations arise, decisions will be made by the *technical committee* (TC) and on-site referees.

Note: Once the test scoresheet is signed the *technical committee* (TC)'s decision is final and cannot be reversed.

2.2 Autonomy & Mobility

The aim of @HOME is to foster mobile autonomous service robotics and natural human-robot interaction. Thus, all robots participating in the RoboCup@Home competition must be *mobile* and *autonomous*, meaning that humans are not allowed to directly (remotely) control the robot, including through verbal commands.

2.3 Aiming for Applications

To drive technological advancement and maintain the competition's interest, the scenario and the tests will steadily increase in complexity. While fundamental abilities are tested, the focus will shift toward real-world applications with higher levels of complexity and uncertainty. In @HOME, solutions that are practical, reliable, general, cost-effective, and applicable are highly valued.

2.4 Social Relevance

The competition and its tests should produce outcomes that are socially relevant, as the goal is to demonstrate the value of autonomous robotic applications to the public. This should be achieved by showing applications where robots directly help or assist humans in everyday

situations. Examples include a personal robot assistant, a guide robot for the blind, or robot care for the elderly.

2.5 Scientific Value

@HOME should not only highlight current practical applications, but also encourage the presentation of innovative approaches, even if they are not yet fully applicable or require special configurations. Therefore, approaches with high scientific value are rewarded.

2.6 Time Constraints

To accommodate many teams and tests, as well as to promote simplicity in setup procedures, the setup time and test duration are very limited.

2.7 No Standardized Scenario

The competition scenario should be simple, effective, available worldwide, and low-cost. As uncertainty is a key part of the competition, no standardized scenario will be provided. Instead, the scenario is expected to reflect typical environments of the country where the competition is held.

It could be a domestic setting like a living room or kitchen, or an office, supermarket, or restaurant. The scenario may change annually to ensure the tests remain relevant and engaging. Additionally, tests may occur in previously unknown environments, such as nearby public spaces.

2.8 Attractiveness

The competition should be appealing to both the audience and the public. Thus, approaches that are highly attractive and original are rewarded.

2.9 Community

While teams compete against each other during the competition, members of the @HOME league are expected to collaborate and share knowledge to advance robotic technology collectively.

The *RoboCup@Home mailing list* and the *Rulebook Repository* can be used to communicate with other teams and discuss league-specific issues such as rule changes or proposals for new tests. Additionally, every team is expected to share technical, scientific, and team-related information in a Team Description Paper and on their team website.

Finally, all teams are invited to submit papers on related research to the ROBOCUP SYMPOSIUM, which accompanies the annual RoboCup World Championship.

2.10 Desired Abilities

The following are the key technical abilities that the tests in @HOME aim to evaluate

- Navigation in dynamic environments
- Fast and easy calibration and setup (the ultimate goal is to have a robot up and running out of the box)
- Object recognition
- Object manipulation
- Detection and recognition of humans
- Natural human-robot interaction
- Speech recognition
- Gesture recognition
- Robot applications (@HOME is aiming for applications of robots in daily life)
- Ambient intelligence, such as communicating with surrounding devices, retrieving information from the internet, etc.

Chapter 3

General Rules and Regulations

These are the general rules and regulations for the competition in the ROBOCUP@HOME league. Each rule in this section implicitly includes the phrase “*unless stated otherwise*”. This means that any additional or contrary rules, particularly those related to test specifications, take precedence over the rules stated in this section.

3.1 Team Registration and Qualification

3.1.1 Registration and Qualification Process

Each year, there are three phases in the process towards participation in @HOME:

1. *Preregistration*
2. *Qualification* announcement
3. Final *Registration* for qualified teams

The *Preregistration* process is initiated by a call for participation sent to the *RoboCup@Home mailing list*. Preregistration requires a *Team Description Paper*, a *Qualification Video*, and a *Team Website*. The expected contents of these are described below.

3.1.2 Team Description Paper

The *Team Description Paper* (TDP) is an 8-pages scientific paper that must include a description of your main research, including the scientific contribution, goals, scope, and results. The *Team Description Paper* (TDP) has to be written in English and formatted using the template of the RoboCup International Symposium without any alterations. The paper should contain the following items:

- The focus of research and the contributions in the respective fields
- Innovative technology (if any)
- Re-usability of the system for other research groups
- Applicability of the robot in real-world scenarios
- Photo(s) of the robot(s) used

As an appendix on the 9th page (after the references), please include:

- Team name
- Contact information
- Website URL

- Names of the team members
- Photo(s) of the robot(s), unless included before
- Description of the hardware used
- A brief, compact list of *external devices* (see Section 3.4), if any
- A brief, compact list of any used 3rd party software packages (e.g. ROS' `object_recognition` should be listed, but `OpenCV` doesn't have to be because it is a rather standard library)
- **[Open Platform League only]** A brief description of the hardware used by the robot(s)

During the qualification process, the *Team Description Paper* (TDP) will be scored according to its scientific value, novelty, and contributions.

3.1.3 Qualification Video

As a proof of running hardware, each team has to provide a *Qualification Video* that demonstrates at least two of the following minimum requirements:

- Human-robot interaction
- Safe navigation (indoors, with obstacle avoidance)
- Object detection and manipulation
- People detection
- Speech recognition
- Speech synthesis (clear and loud)

It is also recommended that the video include some of the following abilities:

- Activity recognition
- Complex speech recognition
- Complex action planning
- Gesture recognition
- Failure recovery

The video should not exceed 10 min, be self-explanatory and be designed for a general audience. It must show the robot solving complex tasks relevant to @HOME. In particular, to qualify for the competition, the video must demonstrate that the robot is able to successfully solve at least one test from the current or previous year's rule book. For robots moving slowly, we recommend speeding up the video, but please indicate the speed factor being used when doing so (e.g. 2x). The same rule applies for slow motion scenes.

3.1.4 Team Website

The *Team Website* should be designed for a broader audience and include scientific material (scientific papers, datasets, and documented open source code). The requirements for the website are as follows:

1. **Language:** The *Team Website* must be in English. Other languages may be available, but English must be default language.
2. **Team:** A comprehensive list of all team members, including brief profiles.

3. **RoboCup:** Link to the league website and previous participations of the team at ROBOCUP (not necessarily only @HOME).
4. **Scientific approach:** Include a research statement, a description of the used approach, and information on scientific achievements.
5. **Publications:** Relevant *publications* from at least the last five years should be included. Downloadable publications are scored higher during the qualification process.
6. **Open source material:** Blueprints, datasets, repositories, or any other contributions to the league are highly valued during the qualification process.
7. **Multimedia:** Photos and videos of the robot(s) used should be included and easily accessible.

3.1.5 Qualification

During the *Qualification Process*, a selection will be made by the *organizing committee* (OC). The following factors are evaluated in the decision process:

- The scientific value, novelty, and contributions of the *Team Description Paper* (TDP)
- The number of abilities and the complexity of the tasks shown in the *Qualification Video*
- The contents of the *Team Website*, where relevant publications and open source resources are highly valued

In addition, the following evaluation criteria are considered:

- The performance in previous competitions
- Relevant scientific contributions and publications
- Any additional contributions to the @HOME league

Important note for the Standard Platform Leagues: Only unmodified robots may compete in Standard Platform Leagues. Any *unauthorized* modification made to the robot that are found in the qualification material will automatically disqualify the team in the qualification process.

3.1.6 Participation Confirmation

In order to have as many participating teams as possible, qualified teams *must* contact the *organizing committee* (OC) to confirm (or cancel) the participation several months in advance. Confirming attendance implies that the team has sufficient resources to register for the competition and commits to attend the event. Qualified teams that do not confirm their participation may be disqualified.

3.2 Scenario

Most competition tests take place in the ROBOCUP@HOME*Arena*, but some tests may take place outside, in a previously unknown public place. In this section, the *Arena* and its contents are described, including the furnishing and other information common to all tests and leagues.

3.2.1 RoboCup@Home Arena

The ROBOCUP@HOME *Arena* is a realistic home setting (an apartment) composed of interconnected rooms. The minimal configuration consists of:

- a bedroom,
- a dining room,
- a living room, and
- a kitchen

There is typically one *Arena* per league. Depending on the local organization, there may be multiple *Arenas* that differ, and a robot must be prepared to perform any task in any *Arena*.

The arena is designed to resemble a typical apartment in the hosting country, including all necessities and decorations found in a *normal* home. Note that what is considered *normal* may vary by culture and location. Decorations can include, but are not limited to, plants, mirrors, paintings, posters, plates, picture frames, wall clocks, candles with holders, and books.

3.2.2 Walls, Doors, and Floor

The indoor home setting will be surrounded by high and low *walls*, which are built up using standard fair construction material.

1. **Walls:** Walls are fixed and cannot be modified during the competition. The minimum wall height is 60 cm; a maximum height is not specified, but must allow the audience to view the competition.
2. **Doors:** Rooms are connected by doors (at least one). All doors have handles, not knobs, and can be closed at any time. It is expected that robots can open these doors or find alternative paths around them. Doors must meet minimum accessibility requirements, with a recommended width of 915 mm.
3. **Floor:** The floor and doorways are even, so there are no major steps or stairs. Minor variations, such as carpets, floor transitions, and small gaps (especially at doorways), can be expected.
4. **Appearance:** The floor and walls are mostly monochromatic, but may have textures like carpets or posters on walls.

3.2.3 Furniture

The *Arena* is furnished with typical objects common to the host country. The minimal configuration consists of:

- a bed,
- a couch,
- a small table,
- a small dinner table with two chairs,
- two trash bins,
- an open cupboard or a small table with a television and remote control,
- a chest of drawers,
- a high cabinet with doors



Figure 3.1: An example of a ROBOCUP@HOME scenario

- a bookcase, and
- a coat rack

The kitchen in the *Arena* includes:

- a dishwasher,
- a microwave,
- a sink, and
- a refrigerator (with some cans and plastic bottles inside)

A typical *Arena* setup is shown in Figure 3.1a.

Chest of drawers

The chest of drawers has at least two drawers located between 90 cm and 120 cm from the floor. These drawers require U-shaped handles for easy access.

High Cabinet

A high cabinet is any shelf-like furniture where objects can be placed. The minimum distance between shelves is 30 cm. The Cabinet must have two side-by-side doors blocking the access to at least the lower three shelves. These doors require U-shaped handles for easy access.

Fridge

At least one functional fridge is required in the *Arena* and must be at least 120 cm in size.

3.2.4 Changes to the *Arena*

Since robots should be able to function in the real world, the *Arena* is not fixed and might change without notice.

1. **Major changes:** Furniture that is not fully static in everyday environments may be moved slightly between tests. In particular, furniture will not change rooms or move drastically within a room, but a couch or table may be slightly rotated or moved. Fixed locations for such furniture items should not be assumed. Walls will stay in place and rooms will retain their function. Passages might be blocked.
2. **Minor Changes:** Slightly moved chairs, slightly closed doors, or similar adjustments may occur at any time, even during a test.

3.2.5 Objects

Some tests in the RoboCup@Home league involve recognizing and manipulating objects (see Figure Figure 3.1b). The *technical committee* (TC) will compile a list of at least 30 objects for this purpose. Each object will have a picture, an official name, and an *Object Category* (e.g., an *Apple* is in the *Fruits* category). Most objects are lightweight and easy to grasp with one hand. Every *Object Category* has an assigned *Predefined Location*, where objects of that category are usually found during tests (for example, an *Fruits* can be found on the *Kitchen Table*). These locations are announced during the *Setup Days* (see Section 4).

Objects are provided at the competition for training. Teams may keep at most five training objects at a time and for up to one hour. Modifying the objects is not allowed.

Two types of objects are used in the tasks:

1. **Known Objects:** Objects previously known to the robot, divided into:
 - 1.1. **Consistent Objects:** Objects whose image appears in the list of objects.
 - 1.2. **Similar Objects:** Objects not in the list but similar enough to one of the listed objects that a person would consider them the same kind (e.g., an apple with a different color or a cloth with a different pattern).
 - 1.3. **Standard Objects:** Objects chosen from the *YCB Dataset*.¹ These are published six months in advance on the ROBOCUP@HOME website², for teams to acquire and train on beforehand.
2. **Unknown Objects:** Any other object not in the object list but can be grasped or handled (e.g., *Arena* decorations).

The minimal configuration of *Known Objects* consists of:

- **Tableware:** Dish, bowl, cup (or mug), and napkin (see Figure 3.2a).
- **Cutlery:** Fork, knife, and spoon.
- **Trash Bags:** Large plastic trash bags, preferably with a handle.
- **Bags:** Lightweight and with stiff, vertical handles (see Figure 3.2b).
- **Dry Food Container:** Dry food containers (see Figure 3.2d).
- **Disks or books:** A set of discs (LP, CD, DVD, or BluRay) or books.
- **Coat rack:** A rack or pole to hang coats and other clothes.
- **Trays:** A transport objects like trays or baskets, intended for bimanual manipulation (see Figure 3.2c).
- **Pourable:** An object whose content can be poured (such as a cereal box).

¹<http://www.ycbbenchmarks.com/object-set/>

²<https://athome.robocup.org/standard-objects>

- **Heavy object:** Weighing between 1.0 kg and 1.5 kg.
- **Tiny object:** A lightweight object not larger than 5 cm (such as paper, a teabag, or a pen).
- **Fragile object:** An object that is easy to break (such as a chocolate egg).
- **Deformable object:** A flexible object that may change shapes (such as cloth).
- **Garbage bag:** A garbage bag that can be tied.

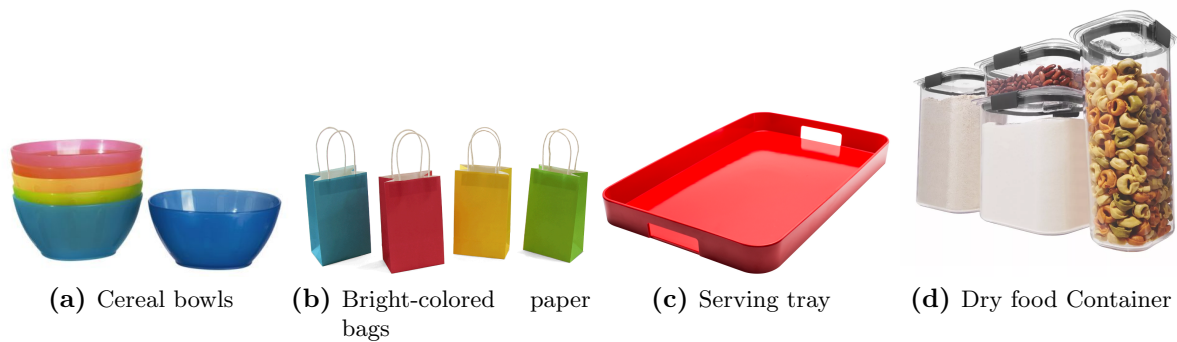


Figure 3.2: Example of object containers

During the competition, objects can be requested based on their *Object Category*, physical attributes, or a combination of both. Relevant attributes to be used are:

- Color (such as red, blue, black with white dots, etc.).
- Relative estimated size (smallest, largest, big one, etc.).
- Relative estimated weight (lightest, heaviest).
- Relative position to other objects (left of, rightmost, etc.).
- Description (is fragile, is a container, can be poured, requires two hands, etc.).

Remark: Measurements are estimations and based on common sense. It is acceptable for robots to consider similar objects to be about the same size or weight.

3.2.6 Predefined Rooms and Locations

Some tests require robots to interact with *Predefined Location* where people or objects may be found. The *Arena* includes at least two *doors*, named *Entrance* and *Exit*, which connect to and from the *Arena*.

Room names, predefined locations, and location classes are announced during the *Setup Days* (see Section 4).

3.2.7 Predefined Person Names

Some tests involve memorizing a person's name. Each person in the *Arena* is assigned a *Predefined Name* by the *technical committee* (TC). The list of names contains 25 % male, 25 % female, and 50 % gender-neutral names taken from the list of most commonly used names in the United States. Predefined names are announced during the *Setup Days* (see Section 4).

3.2.8 Wireless network

For wireless communication, an *Arena Network* is provided. The actual infrastructure depends on the local organization. Reliability and performance of the network are not guaranteed, so robots are expected to be able to function without it.

The following rules apply:

- Only the *Arena Network* can be used during tests.
- Only the active team in a task is allowed can use the *Arena Network*.
- The *Arena Network* provides one Virtual Local Area Network (VLAN) per team.
- Each VLAN has its own SSID and password.
- VLAN traffic is isolated from others teams.
- Each VLAN is also connected to the Internet.

Teams broadcasting unauthorized wireless networks will be disqualified. This includes networks with concealed SSIDs. It is recommended to check all devices for any unauthorized wireless network activity.

3.3 Robots

3.3.1 Number of Robots

1. **Registration:** The maximum *number of robots* per team is *two*.
2. **Regular Tests:** Only one robot is allowed per test. Different robots can be used for different test runs.

3.3.2 Appearance and Safety

Robots must have a product-like appearance and be safe to operate. The following rules apply to all robots:

1. **Cover:** Internal hardware (electronics and cables) must be fully covered to ensure safety. The use of visible duct tape is strictly prohibited.
2. **Loose cables:** No loose cables should hang out of the robot.
3. **Safety:** The robot must not have sharp edges or protruding parts that could harm people.
4. **Annoyance:** The robot must not emit continuous loud noises or use blinding lights.
5. **Marks:** The robot must not display any artificial marks or patterns.
6. **Driving:** Obstacle avoidance is mandatory to ensure safe movement.

The compliance with these rules will be verified during *Robot Inspection* (see [4.4](#)).

3.3.3 Robot Specifications for the Open Platform League

Robots competing in the RoboCup@Home Open Platform League must comply with security specifications to ensure they do not pose any risk to people or property while operating.

Size and Weight

1. **Dimensions:** The robot must fit within the dimensions of an average door, which are typically 200 cm by 70 cm in most countries. The *technical committee* (TC) may allow the qualification and registration of larger robots, but they cannot guarantee that these robots can actually enter the *Arena* due to local restrictions. If in doubt, please contact the *Local Organizing Committee* (LOC).
2. **Weight:** While there are no specific weight restrictions, the robot's total weight and the pressure it exerts on the floor must not exceed local regulations for the construction of offices and/or buildings in the country where the competition is held.
3. **Transportation:** Team members are responsible for quickly removing the robot from the *Arena*. The robot must be transportable by the team members in a way that is both quick and easy.

Appearance

Open Platform League (OPL) robots should appear as safe, finished products rather than early-stage prototypes. This includes ensuring that all internal hardware (electronics and cables) is completely covered for safety. While covering the robot's internal components with a t-shirt is not prohibited, it is not recommended.

Emergency Stop Button

1. **Accessibility and visibility:** Each robot must have an easily accessible and visible *Emergency Stop* button.
2. **Color:** The *Emergency Stop* button must be colored red and must be the only red button on the robot. The *technical committee* (TC) may ask the team to tape over or remove any other red buttons present on the robot.
3. **Robot behavior:** When the *Emergency Stop* button is pressed, the robot and all its parts must stop moving immediately.

Start Button

1. **Requirements:** As explained in Section 3.6.8, teams that cannot perform the default start signal (opening the door) must provide a *Start Button* that can be used to start tests. Teams must inform the TC in advance of any test that involves a start signal, including the *Robot Inspection*.
2. **Definition:** The *Start Button* can be any “one-button procedure” that is easy for a referee to execute, such as releasing the *Emergency Stop*, pressing a green button, or using a software button in a graphical user interface.

Note: All robot requirements will be tested during the *Robot Inspection* (see 4.4).

3.4 External devices

Everything that a team uses during a test and is not part of the robot is considered an *External Device*. All *External Devices* must be authorized by the *technical committee* (TC) during the

Robot Inspection test (see Section 4.4). The TC specifies whether an *External Device* can be used freely or under referee supervision, and determines its impact on scoring.

Note: The use of wireless devices, such as hand microphones and headsets, is not allowed, with the exception of *External Computing* as specified below. The competition organizers do not guarantee or take any responsibility for the availability or reliability of the network or the internet connection in the *Arena*. Teams can thus use *External Computing* resources at their own risk.

3.4.1 On-site External Computing

Computing resources that are not physically attached to the robot are considered *External Computing* resources. The use of up to five *External Computing* resources is allowed, but only in the *Arena Network* (see Section 3.2.8) and with a prior approval of the *technical committee* (TC).

Teams must inform the *technical committee* (TC) about the use of any *External Computing* at least one month before the competition. **Note:** Robots must be able to operate safely even if *External Computing* is unavailable.

External Computing devices must be placed in the *External Computing Resource Area* (ECRA), which is announced by the *technical committee* (TC) during the *Setup Days*. A switch connected to the *Arena* wireless network will be available to teams in the *External Computing Resource Area* (ECRA). During a *Test Block*, at most two laptops and two people from different teams are allowed in the *External Computing Resource Area* (ECRA) simultaneously, one member each of the teams up next. No peripherals, such as screens, mice, keyboards, and so forth, are allowed to be used.

During a *Test Slot*, everyone must stay at least 1m away from the *External Computing Resource Area* (ECRA). Interacting with anything in the *External Computing Resource Area* (ECRA) after the referee has given the start signal for a test will result in the test being stopped with a score of zero.

If a laptop is used as *External Computing*, a team can only place it in the *External Computing Resource Area* (ECRA) if their *Test Slot* is up next and must remove the device immediately after the test.

3.4.2 On-line external computing

Teams are allowed to use *External Computing* through the internet connection of the *Arena Network*; this includes cloud services or online APIs.

3.5 Organization of the Competition

3.5.1 Stage System

The competition is divided into two stages, followed by a *Final*. Each stage consists of a series of tasks designed to test specific robot capabilities, with the *Final* being the final evaluation of the teams' overall performance.

1. **Robot Inspection:** All teams must pass a *Robot Inspection* during the *Setup Days* to be eligible for competition. (see Section 4.4)

2. **Stage I:** The first stage of the competition, *Stage I*, is open to all teams that have passed the *Robot Inspection* test. This stage includes tasks that test basic robot capabilities.
3. **Stage II:** *Stage II*, is open to the top 50% of teams from *Stage I*. If the total number of teams is less than 12, up to 6 teams may advance to *Stage II*. This stage requires more complex advanced or combinations of abilities.
4. **Final:** The top *three teams*, namely the ones with the highest score after *Stage II*, advance to the *Final*. The final round features a single integrated task that tests all abilities evaluated throughout the competition.

In cases where there is no significant score difference between teams, the *technical committee* (TC) may decide to include additional teams in the next stage.

3.5.2 Schedule

1. **Test Blocks:** Each test is scheduled within a Test Block. During each Test Block, each qualified team is assigned at least two Test Slots. The Restaurant test is an exception, requiring only one Test Slot.
2. **Test Slots:** During a Test Slot, a team has a specified amount of time to complete the task.
3. **Participation is default:** Teams must inform the *organizing committee* (OC) in advance if they are skipping a Test Block. If they do not provide such notification, they may be penalized for not attending (see Section 3.8.1).

	Day 1	Day 2	Day 3	Day 4
Block 1 (9:00–11:00)	Storing Groceries	Help Me Carry	Restaurant	
	—Break—			Finals
Block 2 (13:00–15:00)	Receptionist	GPSR	HRI	
	Stage 2			
Block 3 (17:00–19:00)	Open Challenge	Clean the Table	EGPSR	

Table 3.1: Example schedule. Each team has at least two Test Slots assigned in every Test Block.

Note that the actual allocation of blocks will be announced by the *organizing committee* (OC) during the *Setup Days* (see Table 3.1).

3.5.3 Scoring System

The scoring system for the competition is designed to evaluate robot performance based on task completion. Each task has a primary objective and a set of bonus scores. Teams must complete parts of the main objective to receive any points. Bonuses are not awarded otherwise.

The scoring system has the following constraints:

1. **Final:** The final score is normalized.

2. **Minimum score:** The minimum total score per test in *Stage I* and *Stage II* is *0 points*. While teams generally cannot receive negative points, penalties can result in a total score below zero. Specifically, teams may receive penalties for not attending (see Section 3.8.1) and for extraordinary violations (see Section 3.8.2).

3.6 Procedure during Tests

3.6.1 Safety First!

1. **Emergency Stop:** At any time, if a robot exhibits dangerous behavior towards people or objects, the owners must immediately stop it.
2. **Stopping on request:** If a referee, member of the Technical or Organizational committee, an Executive or Trustee of the federation stops the robot (by pressing the emergency button) there will be no discussion. Similarly, if they tell the team to stop the robot, the robot must be stopped *immediately*.
3. **Penalties:** Failure to comply results in immediate disqualification from the ongoing competition by the @HOME *technical committee* (TC). Additionally, the team and its members may be banned from future competitions for at least one year by the RoboCup Federation Trustee Board.

3.6.2 Maximum number of team members

1. **Regular Tests:** During regular tests, only one team member is allowed inside the *Arena*. Exceptions are tests that explicitly require volunteer assistance.
2. **Setup:** During the setup, the number of team members inside the *Arena* is not limited.

3.6.3 Fair play

Fair Play and cooperative behavior are expected from all teams throughout the competition, especially:

- while evaluating other teams,
- while refereeing, and
- when interacting with other teams' robots.

This includes the following:

- not attempting to cheat (e.g., pretending autonomous behavior where there is none),
- not exploiting the rules (e.g., not attempting to solve the task but trying to score), and
- not intentionally causing other robots to fail.
- not modifying robots in standard platforms.

Violating this rule may result in penalties such as negative scores, disqualification for a test, or even the entire competition.

3.6.4 Expected Robot's Behavior

Unless stated otherwise, it is expected that the robot behaves and reacts as a polite and friendly human would. This applies to both how the robot performs tasks and how it interacts with humans. As rule of thumb, one may ask any non-scientist how they would solve the task.

Please note that average users may not be familiar with the specific procedures for operating a robot. Therefore, interactions should be as natural as those with a human.

3.6.5 Robot Autonomy and Remote Control

1. **No touching:** During a test, the participants are not allowed to physically touch the robot(s) unless it is a “natural” way required by the task.
2. **Natural interaction:** The only allowed means to interact with the robot(s) are gestures and speech.
3. **Natural commands:** Anything that resembles direct control is forbidden.
4. **Remote Control:** Remotely controlling the robot(s) is strictly prohibited. This includes pressing buttons, or intentionally influencing sensors.
5. **Penalties:** Disregard of these rules will lead to disqualification for a test or for the entire competition.

3.6.6 Collisions

1. **Touching:** Gentle *touching* of objects is acceptable but not advised. Robots must not crash into anything. The “safety first” rule (Section 3.6.1) takes precedence over any other rule.
2. **Major collisions:** If a robot crushes into something during a test, it is immediately stopped. Additional penalties may apply.
3. **Functional touching:** Robots are allowed to apply pressure on objects, push furniture and, and interact with the environment using structural parts other than their manipulators. This is known as *functional touching*. However, the robot must clearly announce the interaction and kindly request not being stopped.

Remark: Referees may immediately stop a robot if there is suspicion of *dangerous* behavior.

3.6.7 Removal of robots

Robots that do not comply with the rules are stopped and removed from the *Arena*.

1. It is the decision of the referees and the *technical committee* (TC) member monitoring the test if and when to remove a robot.
2. When told to do so by the referees or the *technical committee* (TC) member, the team must immediately stop the robot, and remove it from the *Arena* without disturbing the ongoing test.
3. More than one team member is allowed to enter the *Arena* after the robot has been stopped to quickly remove it.

3.6.8 Start Signal

The default *start signal* (unless stated otherwise) is *door opening*. Other start signals are allowed but must be authorized by the *technical committee* (TC) during the Robot Inspection (see Section 4.4).

1. **Door opening:** The robot starts outside the *Arena* and is accompanied by a team member. The test begins when a referee (not a team member) opens the door.
2. **Start button:** If the robot cannot start automatically after the door is open, the team may use a start button to initiate the test.
 - 2.1. It must be a physical button on the robot (e.g., a dedicated one or releasing the eStop).
 - 2.2. It is allowed to use the robot's contact/pressure sensors (e.g., pushing the head or an arm joint).
 - 2.3. The use of the start button must be announced to the referees before the test starts.
 - 2.4. There may be penalties for using a start button in some tests.
3. **Ad-hoc start signal:** Other start signals are allowed but must be approved by the *technical committee* (TC) during the Robot Inspection (see Section 4.4).
These include:

- Verbal instructions
- Custom HRI interfaces (touchscreen, apps, software, etc.)

Remark: There may be penalties for using Ad-hoc start signals in some tests. The use of mice, keyboards, and devices connected to *External Computing Resource Area* (ECRA) computers is strictly forbidden.

4. **No penalties for physical constraints (HSR only):** In cases where a physical issue (e.g., a door bump) prevents the league from ensuring a standard start signal with full safety for the HSR robot, no penalties will be applied. The following guidelines apply:
 - The team must document the physical issue and notify the committee prior to the Robot Inspection.
 - The issue must be reviewed and approved by the league's rules committee.
 - An alternative start method will be determined on-site in consultation with the committee.

This rule ensures fairness and flexibility while addressing unavoidable physical challenges during league operations.

3.6.9 Restart Rule

During any test, teams are allowed to perform a single restart per attempt under the following conditions:

- A restart may only be requested until the robot completes a major scoring action.
- The test time continues running until the team exits the *Arena* with the robot.
- A restart incurs a penalty of 30 s, subtracted from the total time.
- After exiting, the team may requeue at the back of the line and begin their attempt again within their remaining time.
- Only one restart is permitted per test attempt.

- Only points scored after a restart are counted; points scored before the restart are not considered if a restart was requested.

3.6.10 Entering and leaving the *Arena*

1. **Start position:** Unless stated otherwise, the robot starts outside of the *Arena*.
2. **Entering:** The robot must autonomously enter the *Arena*.

3.6.11 Gestures

Hand gestures may be used to control the robot in the following way:

1. **Definition:** The teams define the hand gestures by themselves.
2. **Approval:** Gestures need to be approved by the referees and *technical committee* (TC) member monitoring the test. Gestures should not involve more than the movement of both arms. This includes, for example, expressions of sign language or pointing gestures.
3. **Instructing operators:** It is the responsibility of the team to instruct operators.
 - 3.1. The team may only instruct the operator when told to so by a referee.
 - 3.2. The team may only instruct the operator in the presence of a referee.
 - 3.3. The team may only instruct the robot for as long as allowed by the referee.
 - 3.4. When the robot has to instruct the operator, it is the robot that instructs the operator and *not* the team. The team is not allowed to guide the operator further, such as telling them to come closer or repeat a command.
 - 3.5. The robot is allowed to instruct the operator at any time.
4. **Receiving gestures:** Unless stated otherwise, it is not allowed to use a speech command to set the robot into a special mode for receiving gestures.

3.6.12 Referees

All tests are monitored by a referee, who is a member of the *technical committee* (TC). The referee may appoint an assistant to help with timekeeping and score sheets.

The following rules apply:

1. **Selection:** Referees are chosen by *executive committee* (EC), *technical committee* (TC), *organizing committee* (OC).
2. **Referee instructions:** Right before each test, the referee selects one or more assistants to aid during the test. The assistants will be instructed by the referee.

3.6.13 Operators

Unless stated otherwise, robots are operated by the referee or by a person selected by the referee. If the robot fails to understand the default operator, the team may request the use of a custom operator. A penalty may apply when using a custom operator.

3.6.14 Time limits

1. **Stage I:** Unless stated otherwise, the time limit for each test in *Stage I* is *5 minutes*.
2. **Stage II:** Unless stated otherwise, the time limit for each test in *Stage II* is *10 minutes*.
3. **Inactivity:** Robots must not stand still or get stuck in endless loops. If a robot is not progressing in the task (and is clearly not attempting to do so), it is considered inactive. The robot must be removed from the *Arena* after 30 seconds of inactivity.
4. **Requesting time:** A robot (not the team) can request the referees to extend the inactivity time limit for a time-consuming process (e.g., 60 seconds). This time cannot exceed 3 minutes and can only be used once per test.
5. **Setup time:** Unless stated otherwise, there is no setup time. Robots need to be ready to enter the *Arena* no later than one minute after the door has been closed to the previous team.
6. **Time-up:** When the time is up, the team must immediately remove their robot(s) from the *Arena*. No more additional score will be giving.
7. **Show must go on:** In special cases, the referee may allow the robot to continue the test for demonstration purposes, but no additional points will be scored.

3.7 Deus Ex Machina: Bypassing Features With Human Help

Because the Show Must Go On

Robots can't score unless they accomplish the main goal of a task. However, in many real-life situations, a minor malfunction may prevent the robot from accomplishing a task. To prevent this situation, while fostering awareness and human-robot interaction, robots are allowed to request human assistance during a test.

3.7.1 Procedure

The procedure to request human assistance while solving a task is as follows:

1. **Request help:** The robot must indicate loud and clear that it requires human assistance. It must be clearly stated:
 - The nature of the assistance
 - The particular goal or desired result
 - How the action must be carried out (when necessary)
 - Details about how to interact with the robot (when necessary)
 - Detailed information to identify objects for picking and placing (e.g. object name, color or location). The provided information needs to show that objects were perceived by the robot.
2. **Supervise:** The robot must be aware of the human's actions, being able to tell when the requested action has been completed, as well as guiding the human assistant (if necessary) during the process.
3. **Acknowledge:** The robot must politely thank the human for the assistance provided.

Example

In the following example, a robot has to clean the table but is unable to grasp the spoon.

R: I am sorry, but the spoon is too small for me to take.
 Could you please help me with it?
 Please say "robot yes" or "robot no" to confirm.

H: *Robot, yes!*

R: Thank you! Please follow my instructions.
 Please take the purple spoon from the table. It is on my left.
 (The robot also shows the result of the perception, e.g. by pointing at the spoon or showing a picture with a bounding box on the screen)

H: (Referee takes purple spoon)

R: I saw you took the spoon.
 Would you be so kind as to follow me to the kitchen?
 Please keep the spoon visible in front of you so I can track you. Thank you!

R: You can stop following me now.
 As you can see, the dishwasher is already open.
 Please place the spoon in the gray basket on the lower tray.

R: Lovely! Thanks for your help.
 I'll let you know if I need further assistance.

3.7.2 Scoring

There is no limit in the amount of times a robot can request human assistance, but score reduction applies every time it is requested.

1. **Partial execution:** A reduction of 10% of the maximum attainable score is applied when the robot request a partial solution (e.g. pointing to the person the robot is looking for or placing an object within grasping distance). The referee decides whether the requested action is simple enough to corresponds to a partial execution or not.
2. **Full awareness:** A reduction of 20% of the maximum attainable score is applied when the robot is able to track and supervise activity, detecting possible, and when the requested action has been completed.
3. **No awareness:** A reduction of 30% of the maximum attainable score is applied when the robot has to be told when the requested action has been completed.
4. **Bonuses:** No bonus points can be scored when the robot requests help to solve part of a task that normally would grant a bonus.
5. **Score reduction overlap:** The score reduction for multiple requests of the same kind do not stack, but overlap. The total reduction applied corresponds to the worst execution (highest reduction of all similar help requests). This means, a robot won't be reduced again for requesting help to transport a second object, but a second reduction will apply when the robot asks for a door to be opened.
6. **Allowed types of assistance:** The types of assistance allowed in a given task are specified in the respective task description. It should be noted that only the assistance types explicitly mentioned in a task description are actually allowed in a task; other types of assistance are not allowed and will nullify the obtained points for the part of the task in which they are applied. For instance, if a task focused on manipulation does not explicitly

mention a Deus Ex Machina penalty for instructing a person to perform a manipulation activity, it should not be assumed that this is a loophole that can be exploited.

3.7.3 Bypassing Automatic Speech Recognition

Giving commands to the robot is essential in many tests. When the robot is not able to receive spoken commands, teams are allowed to provide means to bypass ASR via an Alternative method for HRI (see Section 3.7.3). Nonetheless, Automatic Speech Recognition is preferred.

The following rules apply in addition to the ones specified in section Section 3.7.2

1. **ASR with Default Operator:** No score reduction. The command is given by the human operator who must speak (not shout) loud and clear. The *default operator* may repeat the command up to three times.
2. **ASR with Custom Operator:** A reduction of 10% of the maximum attainable score is applied when a *custom operator* is requested. The Team Leader chooses a person who gives the command *exactly as instructed by the referee*.
3. **Gestures:** A reduction of 20% of the maximum attainable score is applied when a gesture (or set of gestures) is used to instruct the robot.
4. **Alternative Natural Input Method:** A reduction of up to 20% of the maximum attainable score is applied when a *alternative HRI interface*, is used to instruct the robot. Natural alternative HRI interfaces (see Section 3.7.3) must be previously approved by the TC during the Robot Inspection (see Section 4.4).

Alternative interfaces for HRI

Alternative methods and interfaces for HRI offer a way for a robot to start or complete a task. Any reasonable method may be used, with the following criteria:

- **Intuitive to use and self-explanatory:** a manual should not be needed. Teams are not allowed to explain how to interface with the robot.
- **Effortless use:** Must be as easy to use as uttering a command.
- **Is smart and preemptive:** The interface adapts to the user input, displaying only the options that make sense or that the robot can actually perform.
- Exploits the best of the device being used (eg. touch screen, display area, speakers, etc.)

Preferably, the alternative HRI must be also adapted to the user. Consider localization (with English as the default), but also potential users of service robots at their home. For example: elderly people and people with physical disabilities.

3.8 Special penalties and bonuses

3.8.1 Penalty for not attending

1. **Automatic schedule:** All teams are automatically scheduled for all tests.
2. **Announcement:** If a team cannot participate in a test (for any reason), the team leader has to announce this to the *organizing committee* (OC) at least *60 minutes* before the test slot begins.

3. **Penalties:** A team that is not present at the start position when their scheduled test begins is not allowed to participate in the test. If the team has not announced its absence, it receives a penalty of *250 points*.

3.8.2 Extraordinary penalties

1. **Penalty for cheating:** If a team member is found cheating or breaking Fair Play, the team will be automatically disqualified from the running test, and receives a penalty of *500 points*. The *technical committee* (TC) may also disqualify the team for the entire competition.
2. **Penalty for faking robots:** If a team starts a test, but it does not solve any of the partial tasks (and is obviously not trying to do so), a penalty of *250 points* is imposed. The decision is made by the referees and the monitoring *technical committee* (TC) member.
3. **Extra penalty for collision:** In case of major, grossly negligent collisions the *technical committee* (TC) may disqualify the team for a test (the team receives *0 points*), or for the entire competition.
4. **Not showing up as referee or jury member:** If a team does not provide a referee or jury member who is present at the Arena on time, the team receives a penalty of *250 points*. Jury members missing a performance to evaluate are excluded from the jury, and the team is disqualified from the test (receives *0 points*). This will be remembered for qualification decisions in future competitions.
5. **Modifying or altering standard platform robots:** If any unauthorized modification is found on a Standard Platform League robot, the responsible team will be immediately disqualified for the entire competition. This will be remembered for qualification decisions in future competitions.

3.8.3 Bonus for outstanding performance

1. For every regular test in *Stage I* and *Stage II*, the @Home *technical committee* (TC) can decide to give an extra bonus for *outstanding performance* of up to 10% of the maximum test score.
2. This is to reward teams that do more than what is needed to solely score points in a test but show innovative and general approaches to enhance the scope of @Home.
3. If a team believes it deserves this bonus, it should inform the *technical committee* (TC) in advance and provide a brief explanation.
4. The decision to grant the bonus and its extent is solely at the discretion of the *technical committee* (TC).

3.9 Open Challenge

On the first two competition days after the end of the regular test blocks, teams will have an opportunity to present an *Open Challenge* in which they demonstrate their novel research and approaches.

3.9.1 Procedure

1. **Participation:** Teams have to announce whether they want to perform an *Open Challenge* to the OC during the *Setup Days*.
2. **Time:** Each team gets a 10 minute time slot for the *Open Challenge*; of these, 8 minutes are for presenting and 2 minutes are for questions by the audience.
3. **Arena Changes:** The team can rearrange the arena when their time slot starts, but all changes need to be reverted as soon as their time slot ends.
4. **Focus:** While the demonstrations are intended to share research insights, we still want to see robots performing; in particular, the *Open Challenge* should not be turned into a pure academic lecture.
5. **Leagues:** Ideally, the open challenges of all @HOME leagues will be scheduled consecutively to allow all participants to view all demonstrations. However, if more than 12 teams across the leagues register for the *Open Challenge*, each league will hold its *Open Challenge* concurrently to accommodate the increased number of participants.
6. **Award:** The *Open Challenge* does not contribute any points towards the official competition score, but participating teams are eligible to receive the *Best Open Challenge Award* (see [1.7.4](#)).

Chapter 4

Setup and Preparation

Prior to the RoboCup@Home competition, all arriving teams will have an opportunity to set up their robots and prepare for the competition in a *Setup & Preparation* phase. This phase is scheduled to start on the first day of the competition, namely when the venue opens and the teams arrive. During the *Setup Days*, teams can assemble and test their robots. On the last setup day, a *Welcome Reception* will be held. To foster the knowledge exchange between teams, a conference-like *Poster Session* takes place during the reception. Additionally, all teams have to get their robots inspected by members of the *technical committee* (TC) to be allowed to participate in the competition.

Regular tests are not conducted during the setup & preparation phase. The competition starts with *Stage I* (see Section 5).

Table 4.1: Stage System and Schedule per League (distribution of tests and stages over days may vary)

Setup & Preparation	Stage I	Stage II	Finals
	$\xrightarrow{\text{advance}}$ All teams that passed Inspection	$\xrightarrow{\text{advance}}$ Best 6 (< 12) or best 50% (≥ 12)	$\xrightarrow{\text{advance}}$ Best 3 teams

4.1 General Setup

Depending on the schedule, the *Setup & Preparation* phase lasts for one or two days.

1. **Start:** The *Setup & Preparation* starts when the venue opens for the first time.
2. **Intention:** During the *Setup & Preparation*, teams arrive, bring or receive their robots, and assemble and test them.
3. **Tables:** The local organization will set up and randomly assign team tables.
4. **Groups:** Depending on the number of teams, the *organizing committee* (OC) may form multiple groups of teams (usually two) for the first (and second stage). The *organizing committee* (OC) will assign teams to groups and announce the assignment to the teams.
5. **Arena:** The *Arena* is available to all teams during the *Setup & Preparation*. The *organizing committee* (OC) may schedule special test or mapping slots in which *Arena* access is limited to one or more teams exclusively (all teams get slots). Note, however, that the

Arena may not yet be complete and that the last work is conducted in the *Arena* during the *Setup Days*.

6. **Objects:** The delegation of EC, TC, OC and local organizers will buy the objects (see Section 3.2.5). Note, however, that the objects may not be available at all times and not from the beginning of the *Setup & Preparation*.

4.2 Welcome Reception

Since Eindhoven 2013, RoboCup@Home holds an own *Welcome Reception* in addition to the official opening ceremony. During the *Welcome Reception*, a *Poster Session* is held in which teams present their research focus and latest results (see Section 4.3).

1. **Time:** The *Welcome Reception* is held in the evening of the last setup day.
2. **Place:** The *Welcome Reception* takes place in the @Home *Arena* and/or in the @HOME team area.
3. **Snacks & drinks:** During the *Welcome Reception*, snacks and beverages (beers, sodas, etc.) are served.
4. **Organization:** It is the responsibility of the OC and the local organizers to organize the *Welcome Reception* and *Poster Session*, including:
 - 4.1. organizing poster stands (one per team) or alternatives for presenting the posters,
 - 4.2. organizing snacks and drinks, and
 - 4.3. inviting officials, sponsors, the local organization, and the trustees of the RoboCup Federation to the event.
5. **Poster presentation:** During the *Welcome Reception*, the teams give a poster presentation on their research focus, recent results, and their scientific contribution. Both the poster and the teaser talk are evaluated by a jury (see Section 4.3).

4.3 Poster Teaser Session

Before the *Welcome Reception* and *Poster Session*, a *Poster Teaser Session* is held. In this teaser session, each team can give a short presentation of their research and the poster being presented at the poster session.

4.3.1 Poster teaser session

1. **Presentation:** Each team has a maximum of three minutes to give a short presentation of their poster.
2. **Time:** The *Poster Teaser Session* is to be held before the *Welcome Reception* and *Poster Session* (see Section 4.2).
3. **Place:** The *Poster Session* may be held in or around the *Arena*, but should not interfere with the *Robot Inspection* (see Section 4.4).
4. **Evaluation:** The teaser and poster presentations are evaluated by a jury consisting of members of the other teams. Each team has to provide one person (preferably the team-leader) to follow and evaluate the entire *Poster Teaser Session* and the *Poster Session*.

5. **Criteria:** For each of the following evaluation criteria, a maximum of 10 points is given per jury member:
 - 5.1. Novelty and scientific contribution
 - 5.2. Relevance for RoboCup@Home
 - 5.3. Presentation (quality of poster, teaser talk, and discussion during the *Poster Session*)
6. **Score:** The points given by each jury member are scaled to obtain a maximum of 50 points. The total score for each team is the mean of the jury member scores. To neglect outliers, the N best and worst scores are left out:

$$score = \frac{\sum \text{team-leader-score}}{\text{number-of-teams} - (2N + 1)}, N = \begin{cases} 1, & \text{number-of-teams} \geq 10 \\ 2, & \text{number-of-teams} < 10 \end{cases}$$

7. **Sheet collection:** The evaluation sheets are collected by the *organizing committee* (OC) at a later time (announced beforehand by the *organizing committee* (OC)), allowing teams to continue knowledge exchange during the first days of the competition (*Stage I*).
8. **OC Instructions:**
 - Prepare and distribute evaluation sheets before the *Poster Teaser Session*.
 - Collect the evaluation sheets.
 - Organize and manage the poster teaser presentations and the *Poster Session*.

4.4 Robot Inspection

Safety is the most important issue when interacting with humans and operating in the same physical workspace. Because of this, all participating robots are inspected before participating in RoboCup@Home. Every team needs to get their robot(s) inspected and approved so that they can participate in the competition.

1. **Procedure:** The *Robot Inspection* is conducted like a regular test, namely it starts with opening of the arena door (see Section 3.6.8). One team after another (and one robot after another) has to enter the *Arena* through a designated entrance door, move to the *Inspection Point*, and leave the arena through the designated exit door. In between entering and leaving, the robot is inspected by the *technical committee* (TC).
2. **Checked aspects:** During the *Robot Inspection*, each robot is checked for compliance with the competition rules (see Section 3.3), in particular:
 - emergency button(s)
 - collision avoidance (a TC member steps in front of the robot)
 - voice of the robot (it must be loud and clear)
 - custom containers (bowl, tray, etc.)
 - external devices (including wireless network), if any
 - Alternative human-robot interfaces (see Section 3.7.3).
 - **Standard Platform robots**
 - no modifications have been made
 - specification of the *Official Standard Laptop* (OSL) (if required)
 - **Open Platform robots**

- robot speed and dimension
 - start button (if the team requires it)
 - robot speaker system (plug for RF transmission)
 - other safety issues (duct tape, hanging cables, sharp edges etc.)
3. **Re-inspection:** If the robot is not approved in the inspection, it is the responsibility of the team to get the approval at a later point. Robots are not allowed to participate in any test before passing the *Robot Inspection*.
 4. **Time limit:** The robot inspection is interrupted after three minutes (per robot). When told so by the TC — in case of time interrupt or failure — the team has to move the robot out of the *Arena* through the designated exit door.
 5. **Appearance Evaluation:** In addition to the inspection, the TC evaluates the appearance of the robots. Robots are expected to look nice (no duct tape, no cables hanging loose etc.). In case of objection, the TC may penalize the team with a penalty of maximum 50 points.
 6. **Accompanying team member:** Each robot is accompanied by only one team member (the team leader is advised).
 7. **OC instructions (at least two hours before the *Robot Inspection*):**
 - Announce the entry and exit doors.
 - Announce the location of the *Inspection Point* in the *Arena*.
 - Specify and announce where and when the poster teaser and the poster presentation session take place.

Chapter 5

Tests in Stage I

Help Me Carry	35
General Purpose Service Robot	38
Receptionist	41
Storing Groceries	44

5.1 Help Me Carry

The robot's owner needs help carrying a bag from the car to the starting location.

Main Goal: The robot assists the operator in retrieving a bag from a designated car location outside and returning to the starting point.

Optional Goals:

1. Return to the starting location autonomously
2. Follow the queue of people returning to the arena in appropriate manner.

Focus

Person following, navigation in unmapped environments, social navigation.

Setup

- **Locations:**
 - The test is performed outside the arena in a public space.
 - The robot starts at a predefined location, announced before the test.
- **People:**
 - The operator is standing in front of the robot.
 - Three to four additional people are used to simulate a crowd and later form a queue.
- **Objects:**
 - At least two bags are placed near the car location.
 - A small object on the ground.
 - A hard-to-see object.
 - Retractable barriers.
- **Uncontrolled environment:** There are no restrictions on other people walking by, standing near, or observing the robot throughout the test.

Procedure

1. **Following the operator:** The robot should inform the operator when it is ready to follow them. The operator walks naturally towards the designated car location. Upon arrival, the operator points to one of the bags.
2. **Obstacles:** The robot encounters the following obstacles along its way (in arbitrary order): (a) a small object on the ground, (b) a hard-to-see object, (c) a crowd of people obstructing the path, and (d) a small area blocked using retractable barriers.
3. **Picking up the bag:** The robot must identify and pick up the bag pointed at by the operator.
4. **Bag delivery:** The robot takes the bag to the starting location. It may place the bag on the floor.
5. **Optional goals:**
 - 5.1. **Following the queue:** After reaching the car, a few of the people that formed the crowd obstructing the robot return to the starting location in a queue. The robot

can decide to join the queue on its way back, in a manner that appears natural to the people in the queue.

Additional Rules and Remarks

1. **Car location:** A fixed location outside the arena is designated as the “car” area. No actual car is required.
2. **Reaching the car:** The robot can reach the car location only by following the operator (the location is unknown before the test).
3. **Deus ex Machina:** Penalties apply if the robot loses the operator and needs help recovering. The following forms of assistance are penalized:
 - 3.1. Natural interaction (e.g., waving and calling)
 - 3.2. Unnatural interaction (e.g., raising both hands and jumping)
 - 3.3. Returning in front of the robot to resume following.
 - 3.4. Physical contact (e.g., pulling the robot’s hand)

Penalties are only applied if the robot continues to score after the interaction. Penalties can be applied multiple times up to a total of 250 points.

Referee Instructions

The referees need to:

- Assign one volunteer as the operator.
- Assign three to four people to obstruct the robot’s path and later form a queue.
- Choose positions for the bags and assign a bag to the operator.
- Choose the order of the obstacles that the robot will face outside while following the operator.
- Designate a location outside as a car location.
- Designate a location for the queue to form. The queue is composed of the same people that form the crowd.
- Mind the robot when it moves around.
- Ensure the operator follows the robot’s instructions, steps over small obstacles, and walks naturally around objects.

OC Instructions

At least two hours before test:

- Select and announce the robot’s starting point.
- Select which bags will be used in the test.
- Organize retractable barriers.

Score Sheet

The maximum time for this test is **5:00** minutes.

Action	Score
<i>Main Goal</i>	
Following the person to the car	300
Perceiving the correct beg (visualize on screen or say which one)	15
Picking up the correct bag	100
Avoiding the crowd of people obstructing the path	50
Avoiding the small object on the ground	50
Avoiding the hard-to-see object	50
Avoiding the area blocked with retractable barriers	50
<i>Bonus rewards</i>	
Re-reaching the starting location	200
Joining and staying in the queue on the way to the arena	300
<i>Penalties</i>	
Dropping the bag	-50
<i>Deus Ex Machina Penalties</i>	
Rediscovering the operator by natural interaction	-50
Rediscovering the operator by unnatural interaction	-100
Rediscovering the operator by asking them to come back	-150
Rediscovering the operator by direct contact	-200
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	111
Total Score (excluding special penalties & standard bonuses)	1115

5.2 General Purpose Service Robot

The robot is asked to understand and execute commands requiring a wide range of different abilities.

Main Goal: Execute three commands issued by the operator.

Optional Goals:

1. Understand a command given by a non-expert operator.

Focus

Task planning, object/people detection and recognition, object feature recognition, object manipulation

Setup

- **Locations:**

- **Task location:** The task takes place inside the *Arena*. Commands may require the robot to leave the room. The *Arena* is in its nominal configuration for this task.
- **Start location:** The robot starts outside the *Arena*. When the door opens, it must navigate towards the *Instruction Point*.
- **Instruction point:** The robot returns to this point after completing each command to receive the next one.

- **People:**

- **Professional Operator:** Typically the referee, issues standard commands to the robot.
- **Non-Expert Operator (optional):** A person without robotics expertise (e.g., from the audience). The referee provides the intended command goal to this operator, who then issues the instruction using their own wording.

For example, the generated command might be *"Bring me a coke from the kitchen."* then the non-expert operator will be told *"The robot should bring you a coke, which is found in the kitchen."*, who then tells the robot *I want a coke. Go to the kitchen and get me one."*

If the robot consistently fails to understand the non-expert operator (e.g. after two retries), teams can default to a custom operator.

Procedure

1. **Instruction point:** At least two hours before the test, the referees announce the location of the *Instruction Point*.
2. **Test start:** The robot moves to the *Instruction Point* when the arena door is open.
3. **Command execution:** The operator instructs the robot to execute a command and the robot performs the task.
4. **Back to the instruction point:** The robot goes back to the *Instruction Point* and waits for the next command.

5. **Pausing the Timer:** The referee pauses the timer as soon as the robot reaches the instruction point to reset the arena for the next command. The timer resumes once the referee signals the start of the next command.

Additional Rules and Remarks

1. **Partial scoring:** The main task allows partial scoring (per *completed* command).
2. **Command generator:** Tasks will be generated using the official command generator¹.
3. **Non-Expert Operators:**
 - Referees must not assist non-expert operators in phrasing the commands.
 - Teams are not allowed to coach, instruct, or bias non-expert operators. Doing so results in disqualification from the task.
4. **Deus ex Machina:** Score reductions apply in the following cases:
 - Use of a custom operator
 - Bypassing speech recognition with an alternative HRI.
 - Receiving human assistance to accomplish a command
 - Instructing a human assistant to perform the whole task

Referee Instructions

- Provide the commands to the operators.

OC Instructions

At least two hours before the test:

- Generate the robot commands (do not reveal them to the teams).
- Announce the location of the instruction point.
- Recruit volunteers to assist during the test.

During the test:

- Restore the arena to its nominal state before each command execution.

Score Sheet

The maximum time for this test is **5:00** minutes.

¹<https://github.com/RoboCupAtHome/CommandGenerator>

Action	Score
<i>Main Goal</i>	
Executing the task associated with each command	3×400
<i>Bonus Rewards</i>	
Understanding a command given by a non-expert operator	3×100
<i>Deus Ex Machina Penalties</i>	
Using a custom operator	3×-50
Bypassing speech recognition	3×-50
Instructing a human to perform parts of the task will apply a percentage penalty according to similar penalties in other Stage I tests.	3×-400
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	150
Total Score (excluding special penalties & standard bonuses)	1500

5.3 Receptionist

Description

The robot has to guide two new guests to the living room, introduce them to each other, and offer them a seat.

Main goal: The robot welcomes and assists two newcomers at a party, offering them a seat and maintaining appropriate gaze direction during conversation (at person speaking, direction of navigation).

Optional goals:

1. Open the entrance door for each arriving guest.
2. Visually describe the first guest for the second guest before reaching the living room
3. Identify similarities between the guests and the host and incorporate them into the conversation.

Focus

System Integration, Human-Robot Interaction, Person Detection, Person Recognition

Setup

- **Location:**

- The test takes place in the living room.
- The robot starts inside the *Arena* at a predefined location.
- A table with drinks is prepared near the living room
- **Entrance:** The entrance door is open by default. The team leader can request it to be closed to allow the robot to earn additional points by opening it for the guests.

- **People:**

- **Host:** The host's name, favorite drink and interest will be announced before the test. The host is the only person seated in the living room until the robot offers a seat to a guest.
- **Arriving Guests:** Each guest has a name, favorite drink, and one interest. Guests arrive separately. An arriving guest will either step in front of the robot or wait behind the door if it is closed. The robot must guide each guest to the beverage area and then to the living room, where they are introduced to each other.
- **Passive Guests:** A few other individuals (including possibly spectators) are standing in small groups of two or three throughout the arena, but do not obstruct key areas such as the couch, chairs, or beverage table.

Procedure

Both guests arrive separately. The robot either opens the door for the guest or waits for them at the starting location. It greets the guest and asks for their name. The robot then guides the guest to the beverage area, asks for their favorite drink, and indicates whether that drink is available and where it is located on the table. At a freely chosen moment, the robot also asks

for the guest's interest. Afterward, it escorts the guest to the living room and offers a seat. Once both guests are seated, the robot introduces them to each other.

- **Greeting guests:** Each guest paces slightly left and right during conversation. Other people may appear in the background.
- **Looking at person:** The robot must look at the person it is talking to. Guests will move slightly to confirm the robot dynamically follows them with its gaze. Points for gaze tracking are awarded only if the robot continuously tracks the moving person.
- **Looking at direction of navigation:** The robot must look in the direction it is navigating. Persistently looking in an unrelated direction or at unrelated people during navigation results in a score deduction.
- **Smalltalk** The robot asks each guest for one interest.
- **Finding the drink** The robot shows each guest the beverage table, asks for their favorite drink, and tells them if and where the drink is available (left, center, right).
- **Seating People:** The robot must clearly point to a location or seat for each guest.
- **Switching Places:** After being seated, guests may switch seats.
- **Introductions:** When introducing two people to each other, the robot must clearly identify each guest by name, state their favorite drink, and mention one interest.

Additional rules and remarks

1. **Opening Door Timing:** The test time starts either when the first guest enters the arena or 2 minutes after the start signal, whichever comes first.
2. **Misunderstanding:** Asking a guest to repeat themselves is acceptable. However, using an incorrect name, drink, or interest will result in a 20 point penalty per item.
3. **Partial Scoring:** The main task allows partial scoring per guest.
4. **Additional Seating:** Referees may add chairs to the living room area.
5. **Deus ex Machina:** Score reduction applies per guest as follows:
 - **Custom Operator:** Since the main focus of the test is HRI, no custom operator is allowed.
 - **Alternative HRI:** Using alternative HRI methods to understand a guest results in a 75 point penalty.
 - **Recognizing People:** If the robot requires help to identify a person, 200 points are deducted.

Instructions

To Referee

The referees need to:

- Assign name, drink and one interest to three volunteers.
- Arrange and rearrange people in the living room.
- Change the selection of drinks in the beverage area.
- Open the entrance door upon request from the robot.

To OC

During setup day:

- Announce the location of the beverage area.

At least two hours before test:

- Announce the starting position.
- Announce host's name, favorite drink and interest.
- Recruit five volunteers: one as the host, two as arriving guests and two as passive guests.

Score sheet

The maximum time for this test is **6:00** minutes.

Action	Score
<i>Main Goal</i>	
Offer a free seat to the new guest	2×100
Show the guest around (navigate to the beverage area and living room)	2×30
Look in the direction of navigation or at the navigation goal	2×15
Tell position of favorite drink	2×20
Look at the person talking	2×75
Introduce both guests to each other	180
<i>Bonus Rewards</i>	
Open the entrance door for a guest	2×200
State a similarity between an interest between two or more persons	50
Describe the first guest to the second guest before reaching the living room (per correct visual attribute)	4×30
<i>Penalties</i>	
Wrong guest information was memorized (continue with wrong name, drink or interest)	6×-20
Describe the first guest to the second guest before reaching the living room (per incorrect visual attribute)	4×-30
Introduce the wrong persons	-120
<i>Deus Ex Machina</i>	
Alternative HRI	2×-75
Not recognizing people	2×-200
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Outstanding performance (see sec. 3.8.3)	123
Total Score (excluding special penalties & standard bonuses)	1230

5.4 Storing Groceries

The robot stores groceries into a cabinet with shelves. Objects are sorted on the shelves based on similarity, for instance an apple is stored next to other fruits.

Main goal: Move objects from a table to the cabinet, grouping them by category or similarity. Refilling the cereal container.

Optional goals:

1. Opening the cabinet doors
2. Moving a *tiny* object
3. Moving a *heavy* object
4. Picking Objects from the shopping bag

Focus

Object detection and recognition, object feature recognition, object manipulation.

Setup

• **Locations:**

- **Start location:** Before the test, the robot waits outside the *Arena* and navigates to the testing area when the door is open.
- **Test location:** The testing area has a cabinet and a table nearby.

• **People:**

- No people are involved in the test, unless the robot requires human assistance.

• **Furniture:**

- **Table:** The table has 5–10 objects placed on it and the robot can choose which ones to grasp and in what order. On smaller tables, new objects will be added as the robot frees up space.
- **Shopping Bag:** A shopping bag with 5–10 additional items is placed on the ground next to the table.
- **Cabinet:** The cabinet contains objects arranged in groups — either by category or similarity — on different shelves.
- **Cabinet door:** The cabinet is initially closed. If the robot cannot open the door, it must clearly request assistance from the referee.

• **Objects:**

- **Table objects:** The object on the table are arranged arbitrarily.
- **Cabinet objects:** The objects are placed behind the cabinet doors and cannot be accessed unless the doors are open.
- **Containers:** The container for the cornflakes is placed on the table.

Procedure

1. **Table location:** At least two hours before the test, the referees announce which table and cabinet that will be used in the test, along with the approximate table location.
2. **Test start:** The robot enters the testing area once the arena door is opened.
3. **Storing groceries:** After identifying the table, the robot moves the objects from the table to the cabinet.
4. **Pouring cereal:** The robot pours cereal into the designated open container.

Additional rules and remarks

1. **Table:** The approximate location of the table will be announced in advance, and it will be positioned near the cabinet.
2. **Incorrect categorization:** The score is reduced if an object is stored on the cabinet, but not on a shelf with similar objects; this reduction is applied per incorrectly stored object.
3. **New category:** Objects that do not semantically belong to any of the categories represented on the shelves should be grouped together on a new shelf.
4. **Deus Ex Machina:** The scores are reduced if human assistance is received, in particular for:
 - telling or pointing out to the robot where to place an object
 - moving an object instead of the robot
 - opening the cabinet doors
5. **Communicating Perception:** The robot must clearly communicate its perception to the referee. Pointing at the object or attempting to pick it up is sufficient. If using visualization, the robot must indicate where the referee should look and ensure the display is clearly accessible. If the team wants to utilize bounding boxes make sure **only** one object with a bounding box is shown at a time, so the referee is easily able to check and verify. The surrounding scene must also be visible, cropped views alone are insufficient.

OC Instructions

At least two hours before the test:

- Announce which table and cabinet will be used.
- Announce a rough location for the table.
- Select which bags will be used.
- Select which container will be used.

Referee Instructions

The referee needs to:

- Place 5–10 objects on the table.
- Place container and cornflakes on the table.
- Place 5–10 objects in a bag near the table.
- Place objects in the cabinet, grouping them by category or likeliness.
- Close the door of the cabinet.

Score sheet

The maximum time for this test is **7:00** minutes.

Action	Score
Main Goal	
Navigating to the table	15
Perceiving object and categorizing it correctly	5×15
Picking up an object for transportation to the cabinet	5×50
Perceiving objects in shelf and saying on which layer the currently handled object should be placed	5×15
Placing an object in the cabinet	5×15
Placing an object next to similar objects on the cabinet	5×50
Opening the first cabinet door	200
Opening the second cabinet door	100
Pouring cereal into the container	300
Bonus Rewards	
Picking up an object from the shopping bag	5×50
Picking up a tiny object	70
Placing a tiny object	30
Picking up a heavy object	70
Placing a heavy object	30
Autonomously Picking any Object	50
Autonomously Placing any Object	50
Deus Ex Machina Penalties	
Perceiving object and categorizing it wrongly	10×-15
A human handing an object over to the robot	5×-50
A human placing an object in the cabinet	5×-15
A human placing an object in the cabinet next to similar objects	5×-50
A human pointing at a target location	5×-25
A human opening the first cabinet door	-200
A human opening the second cabinet door	-100
Spilling cereal while pouring	-100
Leaving cereal in the box	-100
A human pouring cereal in the bowl	-300
Special Penalties & Bonuses	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	189
<hr/>	
Total Score (excluding special penalties & standard bonuses)	1890

Chapter 6

Tests in Stage II

Clean the Table	49
Enhanced General Purpose Service Robot	52
Restaurant	54
Give Me a Hand	59

6.1 Clean the Table

The robot cleans up a table after a meal. All dishes and cutlery must be placed inside the dishwasher and drinks must be placed inside the trash.

Main goals: Clean up all the objects on the table. Tableware and cutlery must be placed correctly inside the dishwasher and drinks must be placed inside the trash bin.

Optional goals:

1. Opening the dishwasher door
2. Pulling out the dishwasher rack
3. Placing a dishwasher tab inside the dishwasher
4. Wipe the table area where the drink was

Focus

Object perception, manipulation in narrow spaces, and task planning.

Setup

- **Locations:**

- **Start Location:** Before the test, the robot waits outside the Arena and navigates to the testing area when the door is open.
- **Test location:** This test takes place in the kitchen.

- **People:**

- No people are involved in the test, unless the robot requires human assistance.

- **Furniture:**

- **Dishwasher:** A dishwasher is located close to the dining table.
- **Trash bin:** A trash bin is located in the kitchen.

- **Objects:**

- **Table setting:** The table has a total of seven objects in a typical setting for a meal for one person. The cutlery and tableware objects may be randomly stacked as it is common after a meal. The object distribution is as follows:
 - * *Cutlery:* Any two objects (fork, knife, or spoon).
 - * *Tableware:* Any three objects (except cutlery), at least one of which is a dish.
 - * *Drinks:* Any two drinks from the object set.
- **Dishwasher tab:** The tab can be found at a location announced before the test and should be autonomously placed inside the tab slot in the dishwasher.
- **Wiping Object:** The wiping object (i.e. a sponge) can be found at a location announced before the test.

Procedure

1. **Dishwasher door and rack:** Half an hour before the test, the team informs the referees:

- whether the dishwasher door should be closed and, if the door is open, whether the rack should be pushed in
2. **Test start:** The robot moves to the kitchen when the arena door is open.
 3. **Table clean up:** The robot cleans the table by putting:
 - cutlery and tableware items inside the dishwasher
 - drinks in the trash bin

Additional Rules and Remarks

1. **Safe placing:** Objects must be placed with care, namely the robot should place rather than throw or drop objects.
2. **Dishwasher door:** The dishwasher door is open and the racks are pulled out by default. The team leader can, however, request the dishwasher to be closed for bonus points. If the robot fails to open the door, it must clearly state this and request the referee to open the door.
3. **Correct item placement:** The items should be placed in the rack correctly, namely in the location and in a manner as a person would put them.
4. **Deus ex Machina:** The scores are reduced if human assistance is received, in particular:
 - pointing to an object or telling the robot where an object is
 - handing an object over to the robot
5. **Communicating Perception:** The robot must clearly communicate its perception to the referee. Pointing at the object or attempting to pick it up is sufficient. When using visualization, make sure the robot tells the referee where to look and make the visualization easily accessible. If the team wants to utilize bounding boxes make sure **only** one object with a bounding box is shown at a time so the referee is easily able to check and verify. Also make sure the surrounding scene is visible, i.e. just showing a cropped bounding box is not enough.

OC Instructions

During the *Setup Days*:

- Provide official cutlery and tableware for training.
- Announce what is the object used for wiping.

At least two hours before the test:

- Announce the predefined location of the dishwasher tab.
- Announce the predefined location of the object used for wiping.

Referee Instructions

The referee needs to:

- Place objects on the table (two pieces of cutlery, three pieces of tableware and two drinks)

Score sheet

The maximum time for this test is **10:00** minutes.

Action	Score
Main Goal	
Navigate to the table to pick up items	15
Picking up the cup, bowl and drinks for transportation	4×50
Picking up cutlery (spoon, fork) for transportation	2×80
Picking up the plate for transportation	100
Placing the tableware and cutlery inside the dishwasher	5×50
Placing an item correctly (cleanable, convenient like a human would) in the dishwasher	5×75
Placing a drink inside the trash bin	2×50
Bonus Rewards	
Pulling and pushing the dishwasher rack	2×100
Opening and closing the dishwasher door	2×200
Picking up the dishwasher tab for transportation to the dishwasher	100
Placing the dishwasher tab inside the dishwasher's hatch intended for the tab	200
Wiping the area where the drink was	2×50
Autonomously Picking any Object	50
Autonomously Placing any Object	50
Deus Ex Machina Penalties	
Handing cup, bowl and drinks over to the robot	3×-50
Handing cutlery over to the robot	2×-80
Handing the plate over to the robot	-100
Having a human place an object in the dishwasher	5×-50
Having a human place a drink inside the trash bin	2×-50
A human pointing at the trash bin	2×-25
Special Penalties & Bonuses	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	230
<hr/>	
Total Score (excluding special penalties & standard bonuses)	2300

6.2 Enhanced General Purpose Service Robot

The robot is asked to maintain the household by cleaning up the arena and assisting people.

Main Goal: Solve different problems in the arena.

Focus

Task planning, object/people detection and recognition, object feature recognition, object manipulation

Setup

The arena is in its default state apart from problems set up for the robot to solve:

1. Problems:

- **Trash:** Objects on the floor are to be thrown in the trash.
- **Objects:** Objects that are not in their default location should be returned to their default location (see 3.2.5).
- **Persons:** Some persons in the arena will have requests for the robot. They will raise their hand if the robot is in the same room.

Procedure

1. **Test start:** The robot enters when the arena door is open.
2. **Finding Problems:** The robot has to find problems to solve on its own.

Additional rules and remarks

1. **Number of Problems:** The number of problems depends on the arena size the minimum count of generated problems is 8.
2. **Repeating Problem Category:** Solving the same Category of Problem incurs a penalty.
3. **Solving more:** You can continue solving problems to compensate for penalties.
4. **Partial Scoring:** The main task allows partial scoring (per *solved* problem).
 - 4.1. **Scores:** Score reduction is applied as a percentage depending on the solution.
 - 4.2. **Penalties:** The Repetition penalty is applied before any partial penalties
 - 4.3. **Example:** If picking up trash off the floor is valued as 60% of the solution, then requesting a handover should be a $650 \times 0.6 = 390$ points penalty for the first pick and $(650 - 300) \times 0.6 = 210$ for the second pick.
5. **Command Generator:** Problems and commands will be generated using the official command generator¹.
6. **Finding People:** Finding a person and stating they need help counts as finding the problem.
7. **Understanding Commands:** The robot must correctly interpret and repeat commands given by people. Correctly repeating the command given by a person counts as partially solving the problem.

¹<https://github.com/RoboCupAtHome/CommandGenerator>

Referee instructions

- Set up the problems in the arena.
- Provide commands to volunteers.

OC instructions

At least two hours before the test:

- Generate the problems and commands (do not reveal them to the teams!).
- Recruit volunteers to assist during the test.

Score sheet

The maximum time for this test is **10:00** minutes.

Action	Score
<i>Main Goal (can be repeated unlimited times)</i>	
Find and clearly state an encountered problem	3×150
Solve a problem	3×650
<i>Penalties</i>	
Find repeated problem category	-100
Solving repeated problem category for the 2nd time	-300
Solving repeated problem category for the 3rd (or more) time	-500
<i>These Penalties are applied before any percentage based Deus Ex Machina Penalties</i>	
<i>Deus Ex Machina Penalties</i>	
Asking for location of a problem	3×-150
Instructing a human to perform parts of the task will apply a percentage penalty according to similar penalties in other Stage II tests.	3×-650
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	240
Total Score (excluding special penalties & standard bonuses)	2400

6.3 Restaurant

Description

The robot is required to retrieve and serve orders to customers in a real, previously unknown restaurant environment.

Main goal: Detect calling or waving customer, autonomously navigate to their tables, take their orders, and serve them accordingly.

Optional goal: Use an unattached tray to transport the order.

Focus

This task focuses on *Task planning*, *Online mapping*, *Navigation in unknown environments*, *Gesture detection*, *Verbal interaction* and *Object manipulation*.

Setup

- **Locations:**

- This task takes place in a real restaurant fully equipped and in business. If this is not possible, an alternative venue may be selected, provided it resembles a restaurant environment and is outside the *Arena*.
- The *Restaurant* location will remain undisclosed until the start of the test.
- The robot starts next to the *Kitchen-bar*. It is a designated table located near the restaurant's kitchen.

- **People:**

- A *Professional Barman* (member of the *technical committee* (TC)) awaits at the other side of the *Kitchen-bar* for orders to be placed. The *Professional Barman* assists the robot on request.
- There may be real customers and staff present.
- There are at least three tables occupied by professional customers (member of the *organizing committee* (OC), *technical committee* (TC) or other teams).
- There are at least two tables occupied with regular customers.
- Customers may call the robot any time, even simultaneously.

- **Furniture:** The furniture is not standardized and remains unchanged during the test.

- **Objects:**

- Objects to fulfill orders are located on the *Kitchen-bar*.
- Each order consists of 2–3 objects, randomly selected.
- All edible/drinkable objects from the list of standard objects (see Section 3.2.5) are eligible to be part of the orders.

Procedure

1. The referee instructs the team to bring the robot to the start location.
2. The referee gives the start signal and starts the timer.
3. The team leaves the area after the start signal.

4. A *technical committee* (TC) member follows the robot ready to press the emergency stop button.
5. The robot detects a calling or waving customer and navigates to their table.
6. The robot take the customer's order, place the order, and deliver it.
7. **Optionally**, the robot may use an unattached tray to transport the order.

Additional rules and remarks

- **Remarks:**

- This test occurs in a public area. Any physical contact with people or furniture results in immediate emergency stop.
- Since this task is performed outside the arena, the time limit may be longer than the others tasks.
- The availability of wireless, external computing devices, or electrical outlets can't be guaranteed. Assume unavailability.
- The robot must interact with the customers directly. Teams are not allowed to assist or instruct them.
- The robot may use up to one minute to instruct the *Professional Barman*.
- The robot may request guidance to a customer's table.
- The robot may:
 - * Take and place several orders before delivery,
 - * Alternate between order-taking and serving, or
 - * Handle one order at a time.
- The robot should politely confirm the order to the client when receiving it, keeping the guest pleased.
- The robot can either transport each object individually, or using a tray. All delivered objects must be placed on the customer's table.
- For tray delivery, the robot must:
 - * Place the items on the tray,
 - * Pick up and transport the tray,
 - * Deliver the items by either directly placing them on the table or placing the tray first.
- If requested, the *Professional Barman* will place the order in a basket or tray for the robot to deliver it.
- Only two team members are allowed near the robot upon arrival for watching and charging.
- If audience interference makes task execution impossible, the team may immediately repeat the test.
- Each Deus Ex Machina penalty for skipping manipulation is capped at twice per order so receiving an order with three objects is not more punishing.
- If the robot detects a customer but does not reach their table, it must clearly identify the person (e.g., show a picture) to earn partial points.
- When at the front of the queue, teams may begin startup procedures with the robot stationary. Once called, the robot must be brought directly and steadily to the start location—only minor adjustments are allowed (no back-and-forth or full turns).

- **Disqualification:**

- Touching the robot after the start signal.
- Mapping the environment in advance.

Instructions:

To Referee

The referee needs to:

- Prepare orders for each client.

To OC

The OC needs to:

- **During Setup days:** Check with local (security) management if the possible location, including a sufficient queuing area, can be used for the restaurant test.
- **1 hour before the test:** Gather all teams and robots to move to some nearby queuing area and instruct the teams how/when to move to the actual test location.

Score sheet

The maximum time for this test is **15:00** minutes.

Action	Score
<i>Regular Rewards</i>	
Detect calling or waving customer	2×100
Reach a customer's table without prior guidance/training	2×100
Understand and confirm the order received to the customer	2×200
Communicate the order to the barman	2×100
Return to the customer table with the order	2×100
Serve the order to the customer	2×200
<i>Bonus Rewards</i>	
Use an unattached tray to transport	2×200
<i>Regular Penalties</i>	
Being guided to a table	2×-200
Not making eye-contact when taking an order	2×-80
Not reaching the bar (barman has to move from behind the bar to interact with the robot)	2×-80
<i>Deus ex Machina Penalties</i>	
Asking the Barman to handover object to the robot	4×-50
Guest needing to take the object from a tray or the robot's hand	4×-50
Being told/pointed where is a table/ <i>Kitchen-bar</i>	2×-100
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	200
<hr/>	
Total Score (excluding special penalties & standard bonuses)	2000

6.4 Give Me a Hand

Description

The robot assists a human in organizing new items by receiving them and placing them in specified locations using natural interaction.

Main goal: New items have arrived at the house. The operator takes each item from a container, hands it to the robot, and instructs the robot to place it at a designated location within the room.

Focus

Object perception, Human perception, Verbal interaction, and Human-Robot Interaction.

Setup

- **Locations:**
 - This test takes place inside the Arena in a single room.
- **People:**
 - The operator remains in a fixed location during the test.
 - Other people (e.g., referee, assistant) may be present in the room.
- **Objects:**
 - A container (box or bag) containing five random known objects (see 3.2.5).
 - Several visually similar delivery locations (e.g., identical bowls, plates, or bins) placed within the room to create ambiguity.

Procedure

1. The robot starts outside the arena and navigates to the designated room once the door is opened.
2. The robot approaches the operator, who remains stationary throughout the test.
3. The operator picks up an object from the container and hands it to the robot.
4. The operator issues a verbal instruction for where to place the item. Instructions may include gestures and references to landmarks.
5. The robot delivers the item to the specified location, then returns to the operator for the next object.
6. Steps 3–5 repeat until all five items are delivered.

Additional rules and remarks

1. **Handover:**
 - The robot must clearly signal its readiness to receive the item (e.g., by holding its manipulator still, using lights, audio cues, or verbal prompts).
 - The manipulator must be positioned within 10–20 cm of the operator’s hand, without initiating contact.
 - The operator must complete the handover; the robot must not reach, grasp, or initiate movement toward the human.
 - Explicit verbal guidance from the operator (e.g., “Place the item in my gripper, I’ll close it in 3...2...1”) is considered *Deus ex Machina* and will result in penalties.
 - The robot may, however, issue natural cues such as: “I detect the object in my hand. I will close my gripper in 3 seconds, please be careful.”.
2. **Delivery:**

- Delivery instructions may combine verbal commands with gestures (e.g., *"Put this on that plate, next to the flower vase"* while pointing).
- The robot is expected to use natural interaction to confirm ambiguous instructions.
- Since the target locations are intentionally ambiguous, the robot can request clarification from the operator before proceeding. This should be done through natural interaction, such as verbal questions or multimodal cues (e.g., pointing, asking *"Which one?"*).
- Full points are awarded only if the object is placed in the correct container or within a few centimeters of the intended target.
- Human-robot interaction must be natural: robots must first capture the operator's attention (e.g., by gesture, light, or audio) before initiating clarification — especially if the operator is distracted or not directly facing the robot.
- Interactions where the robot talks without attention capture (e.g., asking questions while the operator is busy elsewhere) are discouraged and may affect scoring.

Instructions:

Referee instructions

The referee needs to:

- Randomly select five known scenario objects and corresponding delivery locations.
- Assign the operator's location in the room.

OC Instructions

At least two hours before the test:

- Announce the room for the test.
- Arrange target containers and placement items (such as similar bowls, dishes, or bins) around the room to create ambiguity in delivery instructions.

Score sheet

The maximum time for this test is **10:00** minutes.

Action	Score
<i>Regular Rewards</i>	
Approach a calling operator	100
Approach the human's hand without contact	5×50
Receive an object from the operator	5×100
Use natural interaction to clarify ambiguous delivery locations	5×50
Place an object at the correct location	5×100
<i>Penalties</i>	
Initiating unattended interaction (e.g., talking to the open air)	5×-50
Place an object at the wrong location or by guessing the intended location	5×-75
<i>Deus Ex Machina Penalties</i>	
Instruct the user how to hand over an object	5×-75
<i>Special Penalties & Bonuses</i>	
Not attending (see sec. 3.8.1)	-500
Using alternative start signal (see sec. 3.6.8)	-100
Outstanding performance (see sec. 3.8.3)	160

Total Score (excluding special penalties & standard bonuses)	1600
---	------

Chapter 7

Finals

The competition ends with the Finals on the last day, where the two teams with the highest total score compete.

Even though each league has its own first, second and third place, the *Finals* are meant to show the best of all leagues to the jury members as well as the audience and, thus, warrants a single schedule slot.

7.1 Scoring

The final score and ranking are determined by the jury evaluations and by the previous performance (in Stages I and II) of the team, in the following manner:

1. The influence of the final ranking is 50 %.
2. The influence of the total sum of points scored by the team in Stage I and II is 50 %.

There is no maximum score during the Final.

These demonstrations are carried out in a serialized fashion, one League performing after another in one *Arena*.

7.1.1 Task

The procedure for the demonstration is the same as for Enhanced General Purpose Service Robot (see Task 6.2) with the added tasks of:

1. **Closing Furniture:** Doors of the Cabinet as well as the Dishwasher need to be closed.
2. **Welcome Guest:** There is an additional person waiting behind the exit door. The person will state their request after being welcomed by the robot. The door must be opened without human assistance. As the position is known, there will be no points awarded for finding this person.
3. **Custom Tasks:** Additional reasonable household task.

Custom Tasks

1. **Requesting Additional Tasks:** Additional reasonable household tasks may be requested for scoring during the team leader meetings. These tasks must be approved by the *technical committee* (TC).
2. **Arena-Specific Tasks:** Depending on the arena setup, certain household chores may be delegated to the robot for completion. Examples of tasks that may be handled by the robot include, but are not limited to, window cleaning and picture alignment on the wall.
3. **Team-Supplied Items** In the event that additional items are necessary for the completion of a task (e.g., clothing for folding, watering cans), the requesting team is responsible for supplying these items.
 - 3.1. **Standardization** These items must be regular household items (no markers, no custom printed handles etc.).

- 3.2. **Availability** All requested items must be provided and made available to the competitors prior to the day of the final. At least two identical copies of each item must be supplied to ensure adequate access.

7.1.2 The Show Must Go On

To ensure a good experience for the audience the teams are allowed to restart the robot inside the arena.

1. All previously collected points will be kept.
2. The tasks may be rearranged by the Referee during a restart.
3. The restart penalty is only applied if the robot continues scoring afterwards.

7.1.3 Commentator

The team will be asked to provide a commentator to explain the robot's behavior and answer questions to produce a better viewing experience for the audience.

Score sheet

The maximum time for this test is **10:00** minutes.

Action	Score
<i>Main Goal (can be repeated unlimited times)</i>	
Find and clearly state an encountered EGPSR problem	3×150
Solve a EGPSR problem	3×650
Opening the Door of the Apartment	600
Closing the Dishwasher	600
Closing a Cabinet Door	300
Custom Task	
Custom Task	
Custom Task	
<i>Penalties</i>	
Find repeated EGPSR problem category	-100
Solving repeated EGPSR problem category for the 2nd time	-300
Solving repeated EGPSR problem category for the 3rd (or more) time	-500
<i>Deus Ex Machina Penalties</i>	
Asking for location of a problem	3×-150
Restart (only applies if the robot continues scoring afterwards)	-50
Instructing a human to perform parts of the task will apply a percentage penalty according to similar penalties in other Stage II tests.	3×-650
Total Score (excluding special penalties & standard bonuses)	3900

7.2 Final Ranking and Winner

The winner of the competition is the team that gets the highest ranking in the *Finals*.

The second place will be the team that got the second-highest ranking in the *Finals*.

The third place will be the team with the lowest score in the *Finals*.

Index

- alternative HRI interface, [26](#)
- Arena, [11–15](#), [17](#), [18](#), [20–24](#), [29–32](#), [38](#), [41](#), [44](#), [54](#), [61](#)
- Arena doors, [15](#)
- Arena Network, [16](#), [18](#)
- Arena walls, [12](#)
- awards, [3](#)
- Bags, [14](#)
- Best Human-Robot Interface Award, [3](#)
- Best Open Challenge Award, [4](#), [28](#)
- Best OPL Poster Award, [3](#)
- Coat rack, [14](#)
- Consistent Objects, [14](#)
- custom operator, [26](#)
- Cutlery, [14](#)
- default operator, [26](#)
- Deformable object, [15](#)
- Disks or books, [14](#)
- door opening, [22](#)
- Dry Food Container, [14](#)
- Emergency Stop, [17](#)
- Entrance, [15](#)
- executive committee, [1–4](#), [23](#)
- Exit, [15](#)
- External Computing, [18](#)
- External Computing Resource Area, [18](#), [22](#)
- External Device, [17](#), [18](#)
- External Devices, [17](#)
- external devices, [10](#)
- Fair Play, [20](#)
- Final, [3](#), [18](#), [19](#)
- Finals, [29](#), [61](#), [62](#)
- Fragile object, [15](#)
- Functional touching, [21](#)
- functional touching, [21](#)
- Garbage bag, [15](#)
- Heavy object, [15](#)
- Human-Robot Interaction, [41](#)
- Known Objects, [14](#)
- Local Organizing Committee, [2](#), [17](#)
- Major collisions, [21](#)
- Manipulation, [4](#)
- Natural Language Processing, [4](#)
- Navigation, [4](#)
- Object Category, [14](#), [15](#)
- Official Standard Laptop, [31](#)
- Open Challenge, [27](#), [28](#)
- Open Platform League, [2](#), [3](#), [17](#)
- organizing committee, [2](#), [11](#), [19](#), [23](#), [26](#), [29](#), [31](#), [54](#)
- outstanding performance, [27](#)
- Person Detection, [41](#)
- Person Recognition, [4](#), [41](#)
- Poster Session, [3](#), [29–31](#)
- Poster Teaser Session, [30](#), [31](#)
- Pourable, [14](#)
- Predefined Location, [14](#), [15](#)
- Predefined Name, [15](#)
- Preregistration, [9](#)
- publications, [11](#)
- Qualification, [9](#)
- Qualification Process, [11](#)
- Qualification Video, [9–11](#)
- Registration, [9](#)
- Home mailing list, [6](#), [9](#)
- RoboCup Federation, [3](#)
- Robot Inspection, [16–19](#), [30–32](#)
- Rulebook Repository, [2](#), [6](#)
- Setup & Preparation, [29](#), [30](#)
- Setup Days, [14](#), [15](#), [18](#), [19](#), [28–30](#), [50](#)
- Similar Objects, [14](#)
- Stage I, [3](#), [19](#), [20](#), [24](#), [27](#), [29](#), [31](#)

Stage II, [3](#), [19](#), [20](#), [24](#), [27](#), [29](#)
Standard Objects, [14](#)
Start Button, [17](#)
start signal, [22](#)
System Integration, [41](#)

Tableware, [14](#)
Team Description Paper, [4](#), [9–11](#)
Team Website, [9–11](#)
technical committee, [2](#), [4](#), [5](#), [14](#), [15](#), [17–23](#), [27](#),
[29](#), [31](#), [54](#), [55](#), [61](#)
Telegram Group, [2](#)
Test Block, [18](#)
Test Slot, [18](#)
Tests, [3](#)
Tiny object, [15](#)
Touching, [21](#)
Trash Bags, [14](#)
Trays, [14](#)

Unknown Objects, [14](#)

Welcome Reception, [29](#), [30](#)
Wiki, [2](#)

YCB Dataset, [14](#)