



Motor 1 Pins

enable

11 → (WiringPi: 0)

control

13 → (WiringPi: 2)

15 → (WiringPi: 3)

Motor 2 Pins

enable

22 → (WiringPi: 6)

control

16 → (WiringPi: 4)

18 → (WiringPi: 5)

