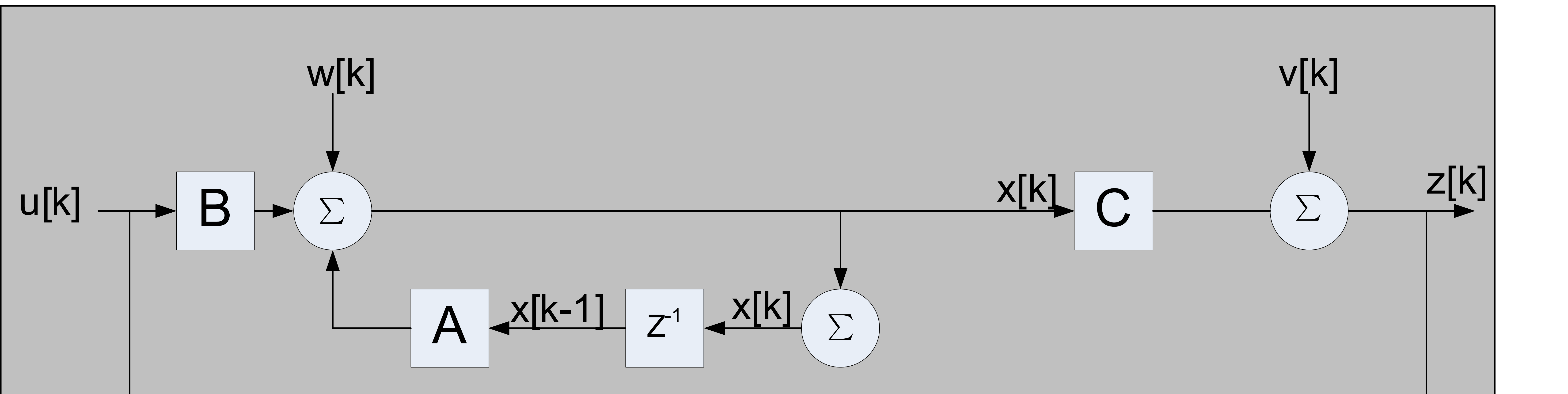LINEAR DYNAMICAL SYSTEM

KALMAN FILTER