

robopoly.epfl.ch

P. Bobbink
M. Pagnamenta

C9

R5

R4

C2

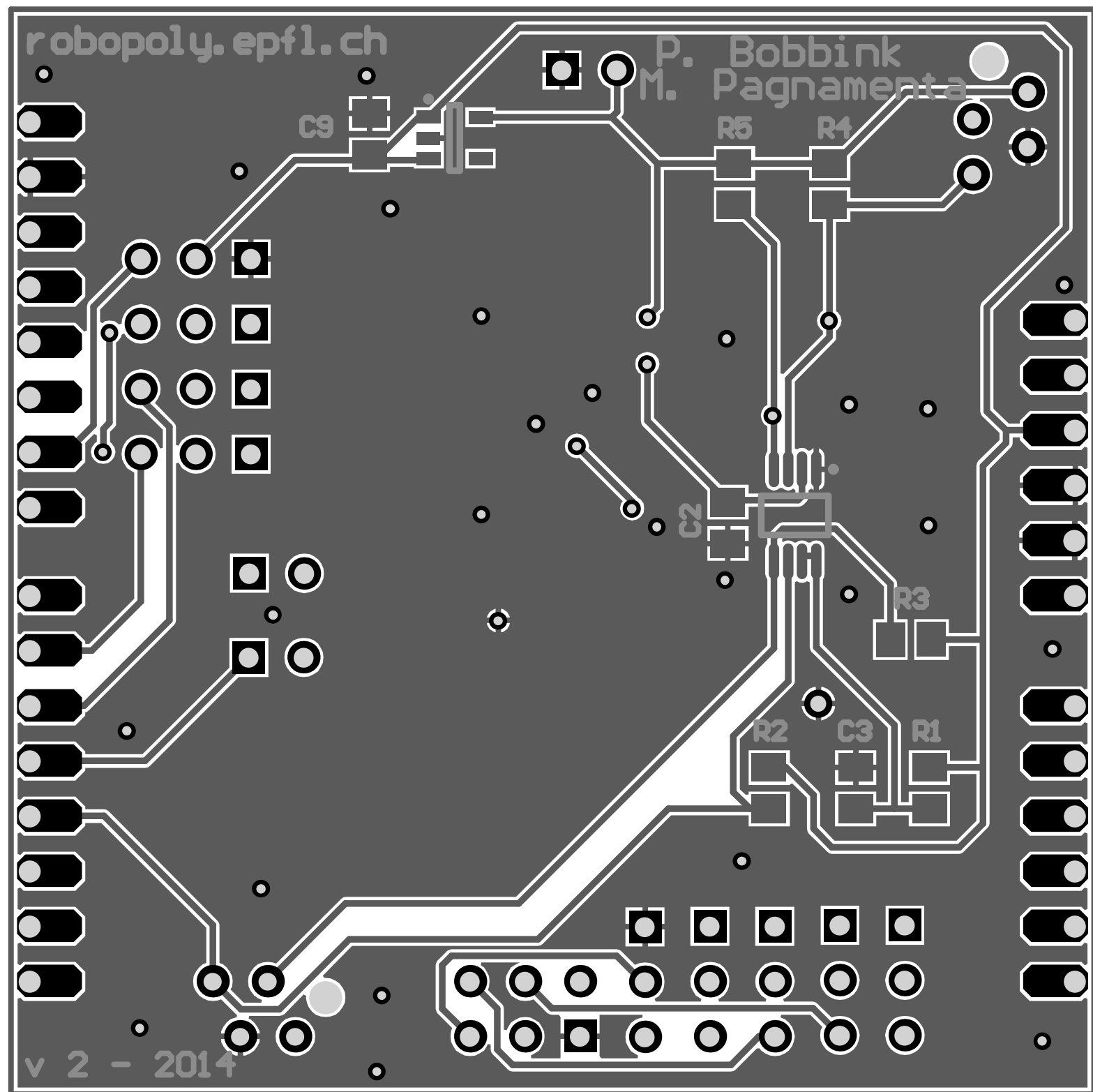
R3

R2

C3

R1

v 2 - 2014



Quantity	Comment	LibRef	Designator	Description	Footprint
2	I2C	Micromatch-I2C	1, 2	Micromatch I2C Connector	TYCO/215079-4
3	Header 2	Header 2	3, J1, J2	Header, 2-Pin	HEADER1x2
9	Header 3	Header 3	AUX1, ESC1, ESC2, ESC3, ESC4, PITCH1, ROLL1, THR1, YAW1	Header, 3-Pin	HDR1X3
7	C0805	C0805	C1, C2, C3, C4, C5, C6, C9	Ceramic Chip Capacitor - Standard	MELF-R2012-0805
2	C	C	C7, C8	Capacitor	C/0805
1	Header 3X2	Header 3X2	ISP1	Header, 3-Pin, Dual row	HDR2X3
2	resistor	resistor	J1, J2	Resistor	MELF-R2012-0805
1	9-axis	MPU-9150	MPU-1	9-axis sensor (gyroscope, accelerometer, magnétomètre)	MPU-9150
1	Header 2	Barometer LPS331AP	P1	Header, 2-Pin	HCLGA-16L
1	PCA9306	Component_1_1	PCA1	I ² C shifting voltage	TSOP65P490X110-8N
5	Res1	Res1	R1, R2, R3, R4, R5	Resistor	MELF-R2012-0805
1	Leonardo pins	Leonardo pins	shield1		Leonardo pins
1	TLV70033DDCR	TLV700xx	TLV1	Header, 2-Pin	TLV70033DDCR

