view_frames Result Recorded at time: 1601365716.978 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1601365716.978 sec old) Buffer length: 0.000 sec box_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1601365716.978 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /ur_hardware_interface Average rate: 10000.000 Hz Average rate: 125.208 Hz Average rate: 125.208 Hz Most recent transform: 0.000 (1601365716.978 sec old) Most recent transform: 1601365716.970 (0.008 sec old) Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec Buffer length: 0.000 sec Buffer length: 4.968 sec shoulder_link tool0_controller base Broadcaster: /robot_state_publisher Average rate: 125.208 Hz Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 125.208 Hz Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 125.208 Hz Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 125.208 Hz Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 125.208 Hz Most recent transform: 1601365716.946 (0.032 sec old) Buffer length: 4.944 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1601365716.978 sec old) Most recent transform: 0.000 (1601365716.978 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ee_link tool0