

Calibration results

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Camera-system parameters:

cam0 (/b1/b1_front_down_cam/infra1/image_rect_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.00694542 -0.00989615 0.00200095 -0.00063271] +- [0.00269143 0.00272851 0.00059056 0.00057303]

projection: [380.11666488 380.89336898 318.91733599 238.9209778] +- [0.76442169 0.7865116 0.78081296
0.79561361]

reprojection error: [-0.000002, -0.000001] +- [0.129487, 0.156782]

Target configuration

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Type: aprilgrid

Tags:

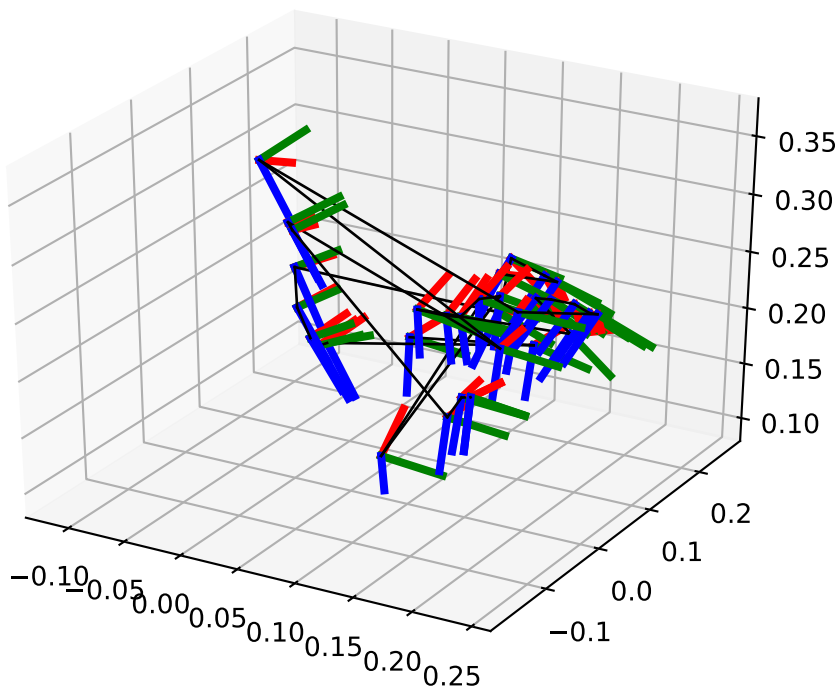
Rows: 6

Cols: 6

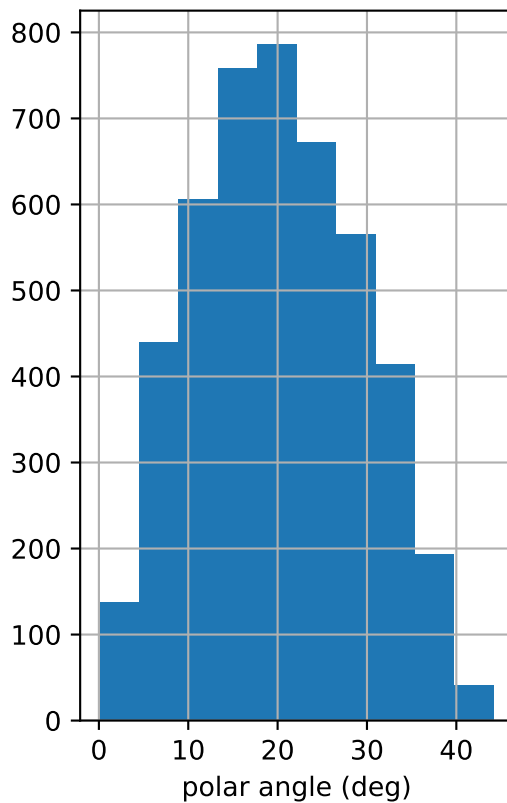
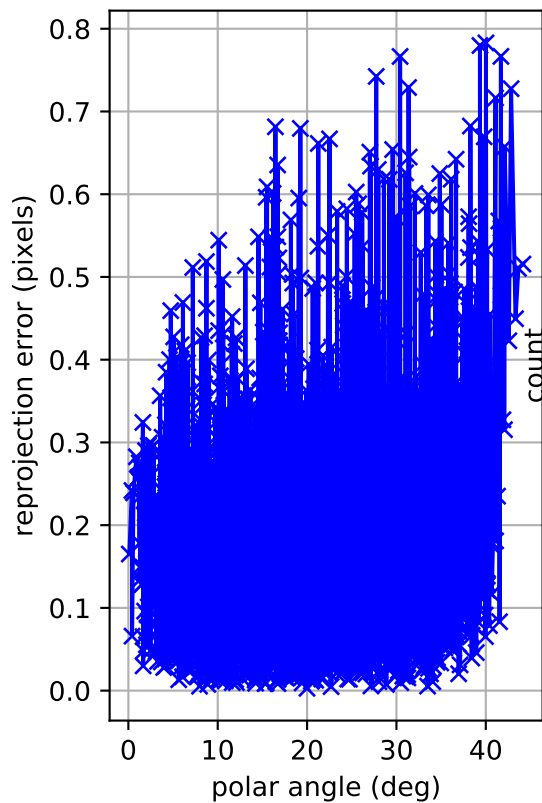
Size: 0.02 [m]

Spacing 0.006 [m]

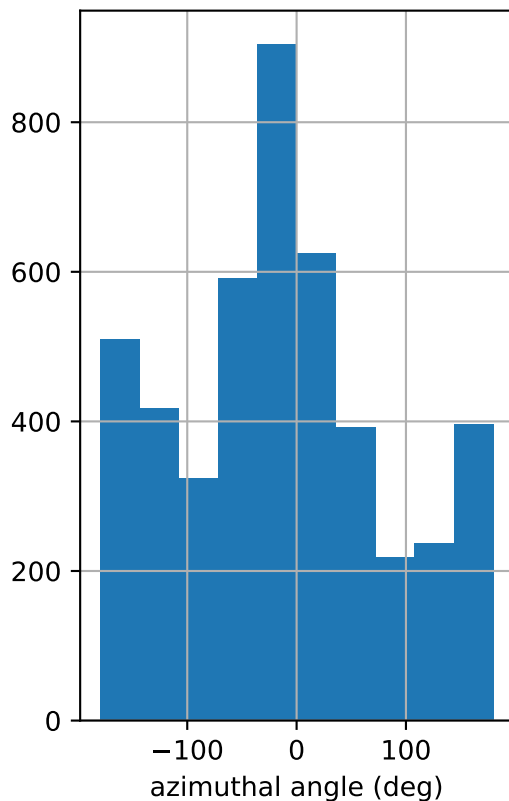
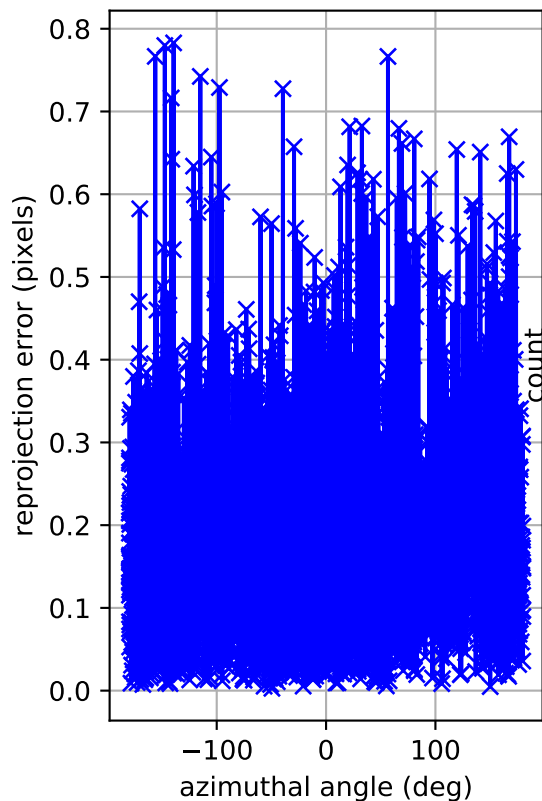
cam0: estimated poses



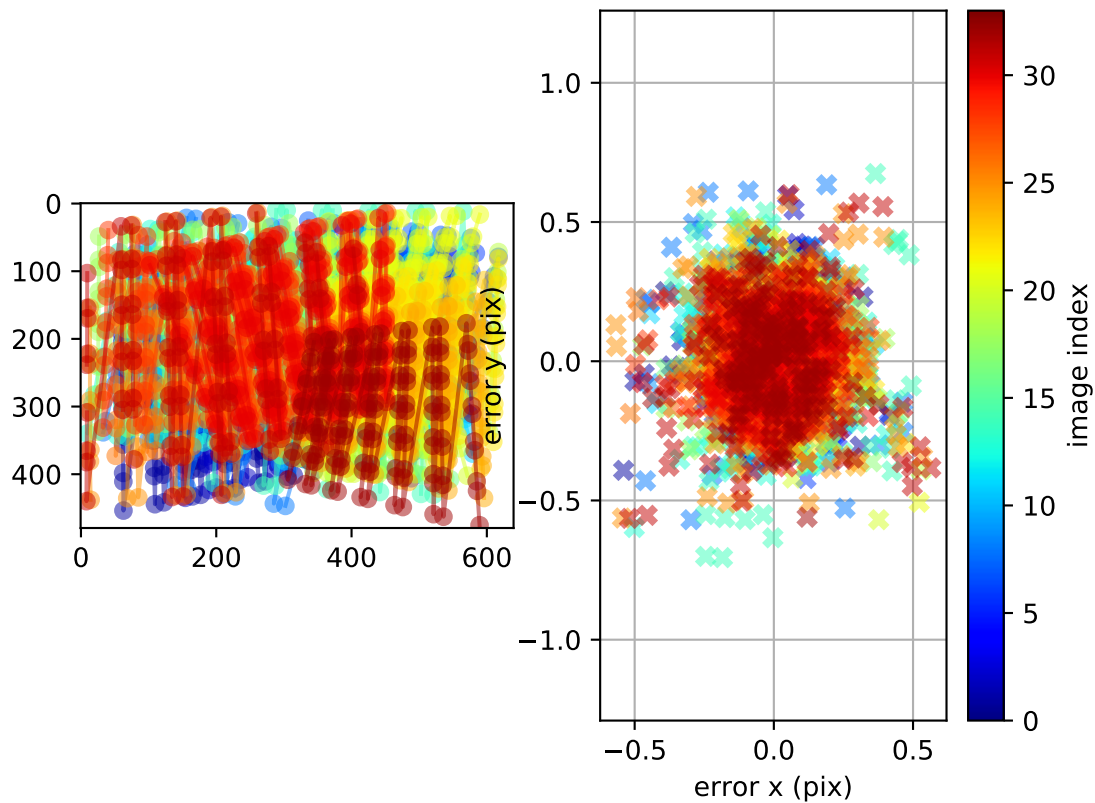
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

