Calibration results
====================
Camera-system parameters:
cam0 (/b1/b1_back_down_cam/infra1/image_rect_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [0.0037744 -0.00809666 -0.00125922 -0.00069535] +- [0.00208727 0.00259288 0.0004442 0.00043316]
projection: [380.41478084 381.35641386 319.29058829 235.89003599] +- [0.57575097 0.57264115 0.55408138
0.59509568]
reprojection error: [-0.000000, -0.000001] +- [0.114860, 0.141843]
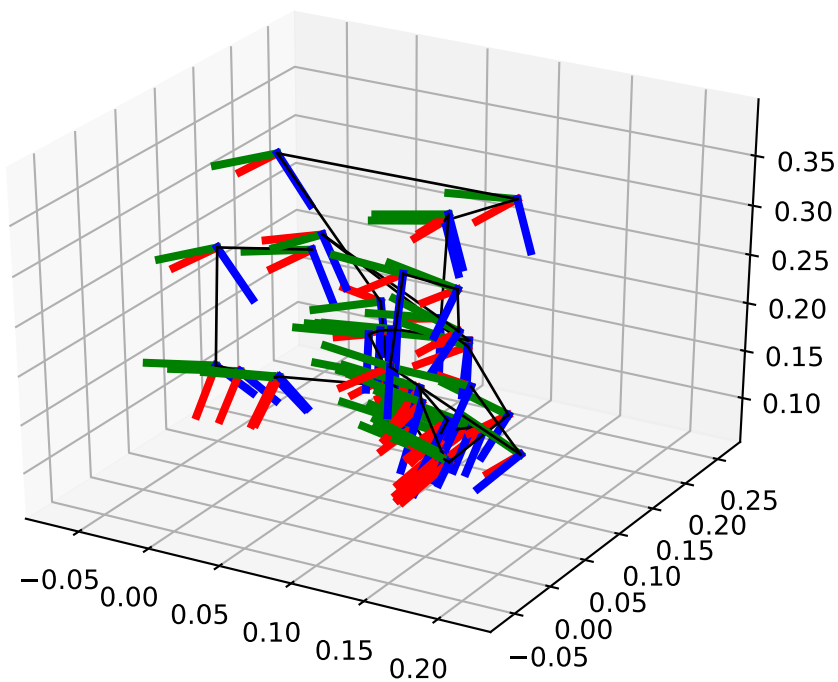

Target configuration
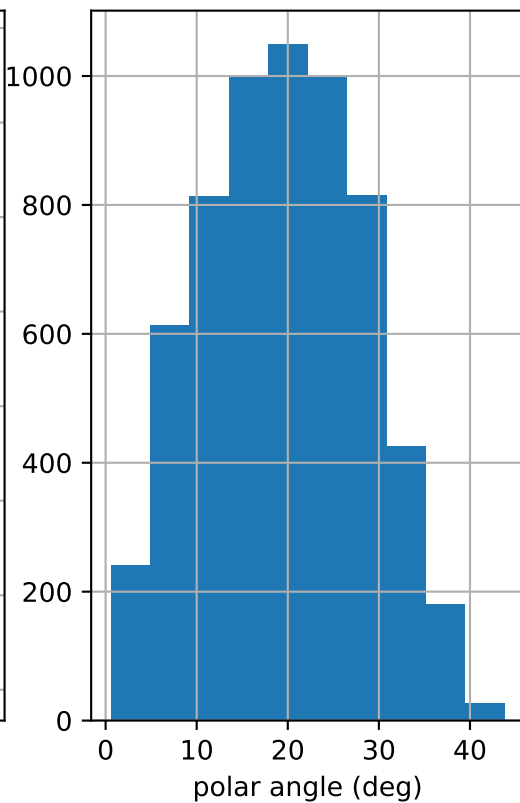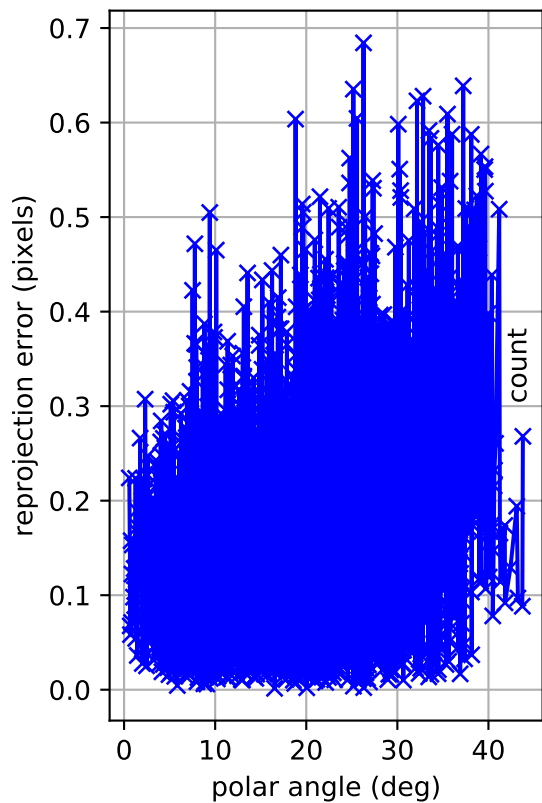====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
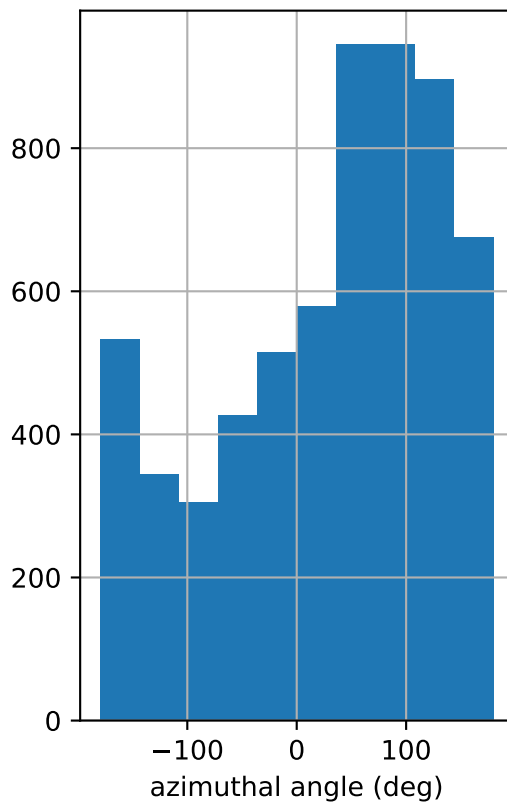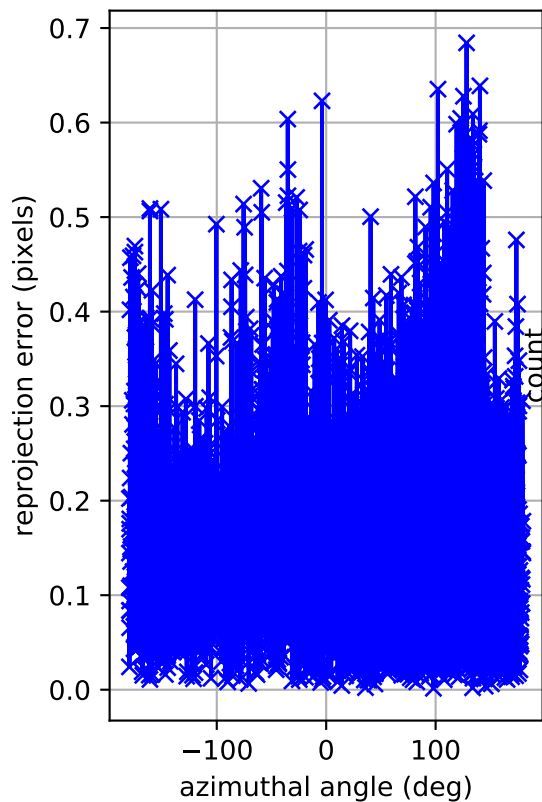Size: 0.02 [m]
Spacing 0.006 [m]
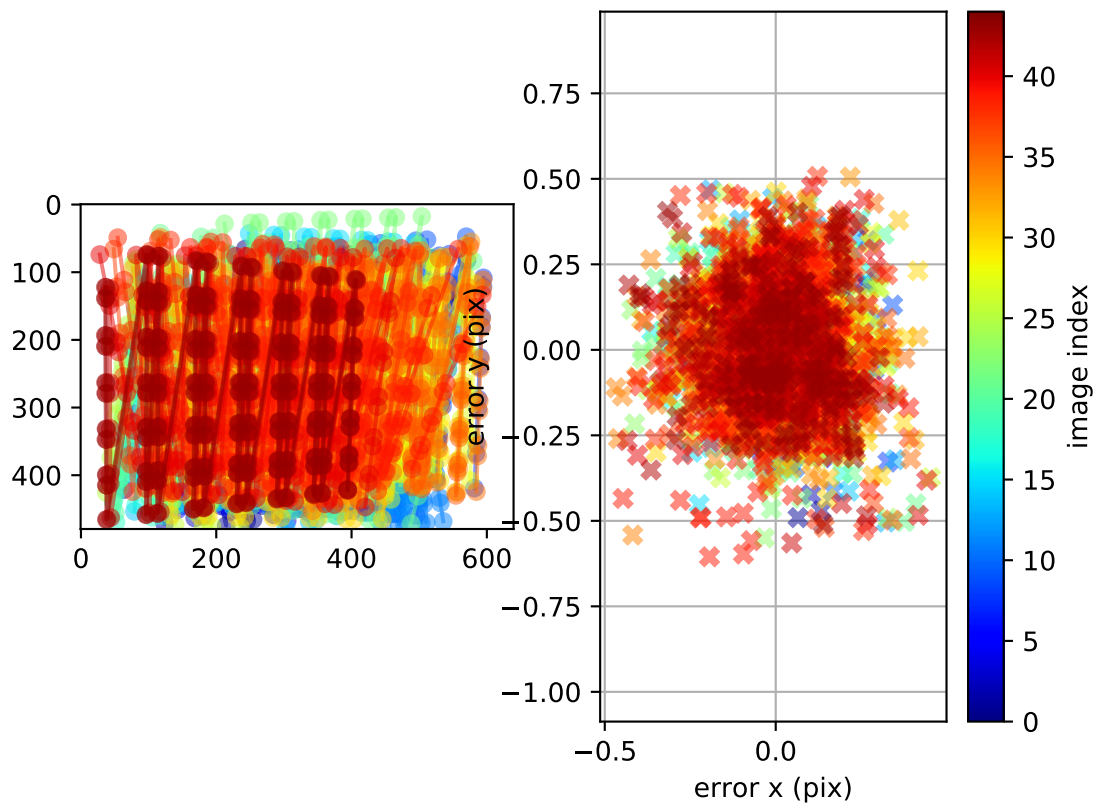
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0