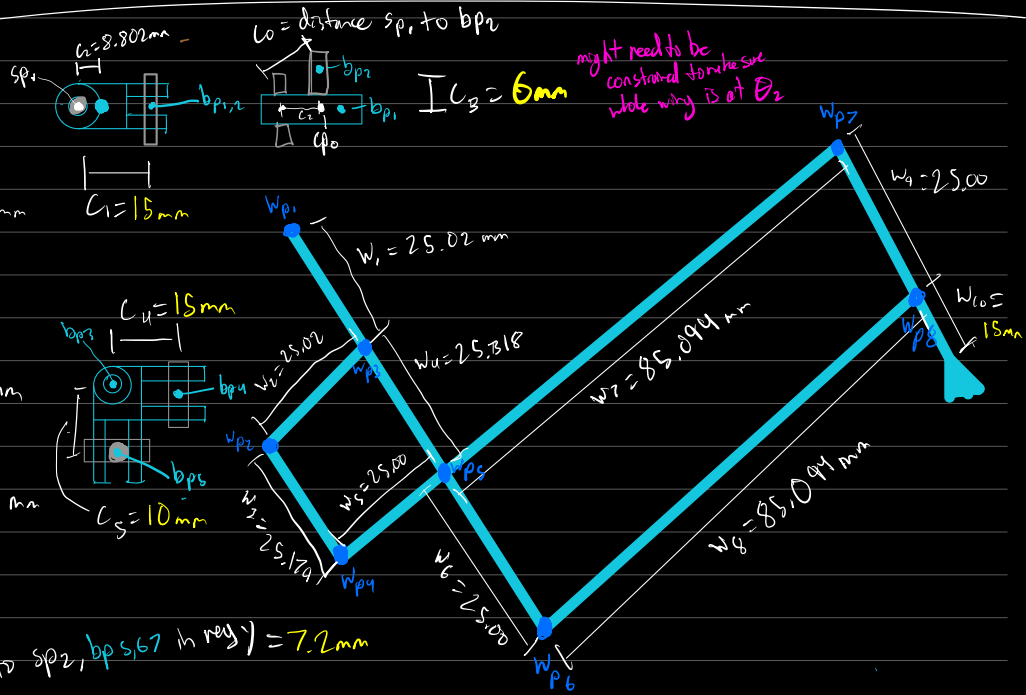
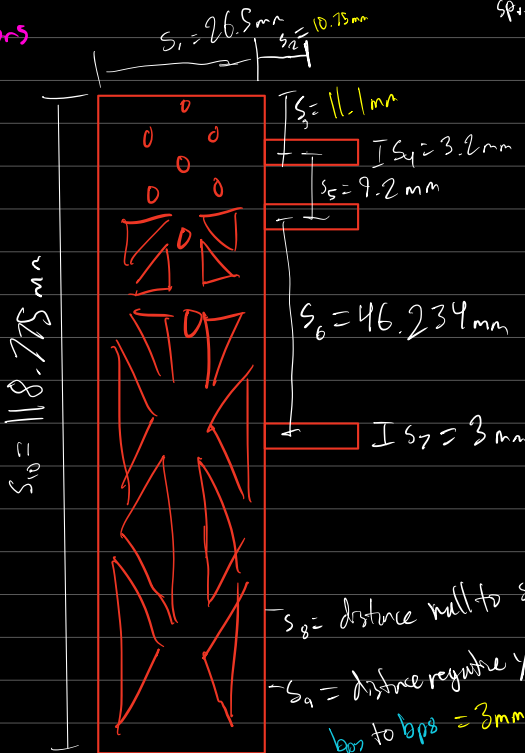


- volume swept from top to bottom
- percentage of cycle that is down flap vs up again
- one DoF vs 2 DoF

process variable θ

Dimensions



s_g = distance null to sp_2 , bp 5,67 in reg 1 = 7.2mm

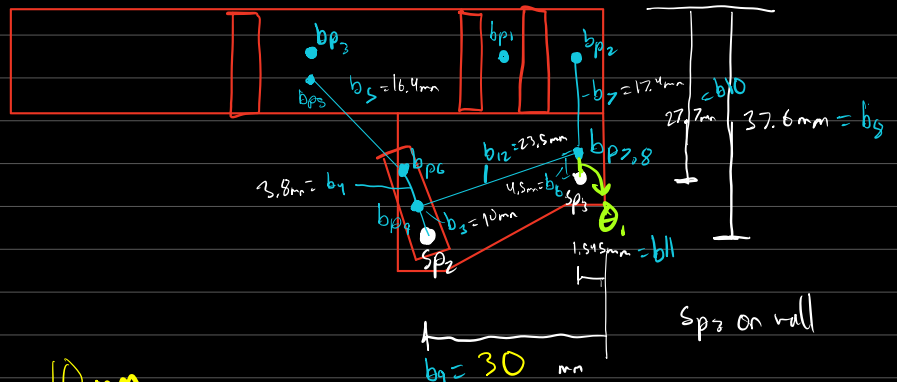
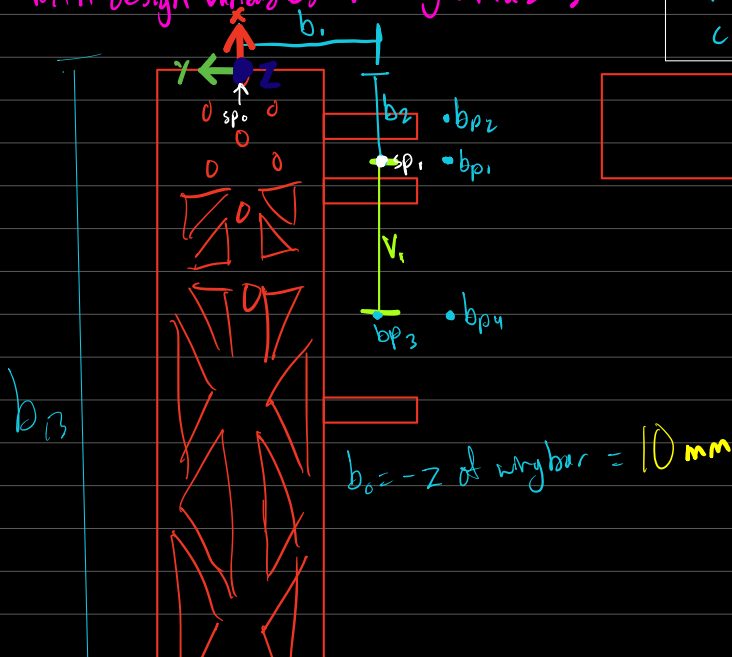
$-S_a = \text{distance regularity}$
bps to bps = 3mm

- s_p = stationary spine points
- b_p = moving body points
- w_p = moving wing points
- b = designable body dimensions
- w = designable wing dimensions
- c = designable connector dimensions

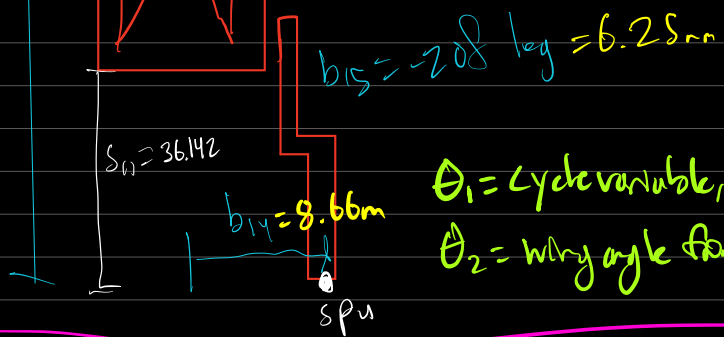
$$b_{p_1} = w_{p_1}$$
$$b_{p4} = W_{p2}$$

variables

with design variables + moving variables



yellow pears red, checked



$\theta_1 = \text{cycle variable, motor angle}$

$\theta_2 = \text{wing angle from horizontal} - \text{found through positions}$

Process: define spc points

define relations between points

draw all points

draw all lines

Results:

$\theta_{1,hor} = \text{cycle angle when } \theta_2 = 0$