

Power

9V battery
5 V buck boost 2 A>
3V3 1 A
1V8 1 A
1V2 1 A
Power up sequence
5 V Current limiter
5V on/off
Current measurement on overall current
Voltage check on Batteries
5V BURN OUT

See page 11

USB Host Client

USB Client 1,5 , 12 and 480 MBit
USB Host 1,5, 12 Mbit
5 Volt +500 mA (1,2A MAX)
Current limiter
Apple Autentic IC + Decoding MCU

See page 2 and 3

Input

4 Input ports (see page 4):
Port 1: PixyCam (see page 5)
Port 2: Gyro sensor (see page 6)
Port 3: Color sensor (see page 7)
Port 4: Ultrasonic (see page 8)

TIAM1808

MCU

Buttons
Diodes
are on the KEYPAD PCB

Note:
PU = Pull Up
PD = Pull Down
SDA = Serial DATA
SCK = Serial Clock
ADC = Analog Digital Converter
USB = Universal Serial Bus
UART = Universal Asynchronous Receiver/Transmitter
PWM = Pulse Wide Modulation
GUI = Graphical User Interface
B&W = Black and White
mDDR = Mobile Double Data Rate synchronous DRAM
R = Red
G = Green
uSD = micro Secure Digital
I2C = Inter-Integrated Circuit
SPI = Serial Peripheral Interface Bus
PCB = Printed Circuit Board

Ram Flash uSD

mDDR 1,8V 64 Mbyte 16 bit Wide
uSD CARD HC version up to 32 Gbyte
I2C boot ROM for secure boot
SPI flash 3V3 16Mbyte

See page 2 and 3


Display Button GUI

Display, B&W, 178X128 Reflective
6 Buttons UP, DOWN, L, R, ACK/ON, BACK
R and G Diodes
Sound out

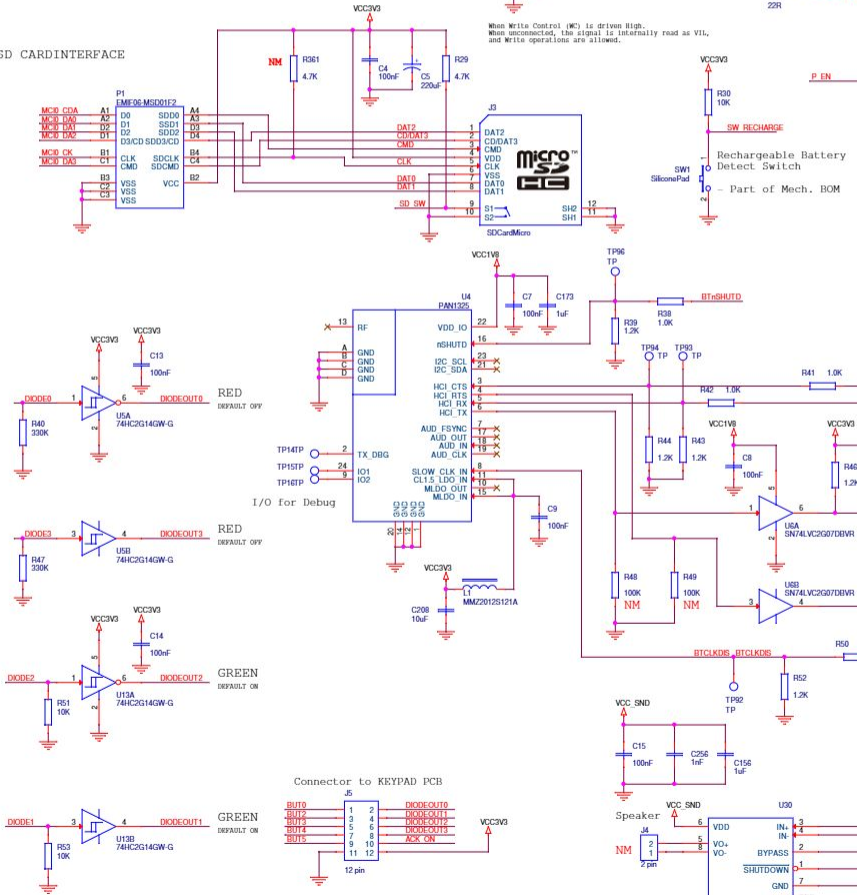
See page 2 and 3

Output

4 Output ports (see page 9):
Port A: Medium motor (Drive)
Port B: Medium motor (Drive)
Port C: Medium motor (Steering)
(Motors schemes are on page 10)

	Title		Engineer/Constructor	Date (YYYYMMDD)
	95647_20		B&P	20120907
	Project Number		Checker	Date (YYYYMMDD)
	95647		B&P/UJ	20120907
Version		Sheet		Page Size
J		1 of 6		A2

SD/uSD CARDINTERFACE

SOUNDEN
INTERNAL PD

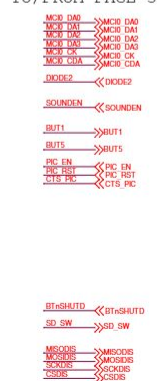
Short wire twisted to speaker



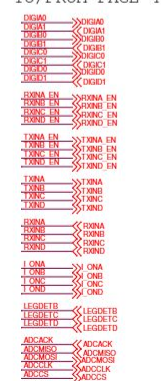
BOOT[7:0]	Boot Mode	AIS
0000 0010	NOR	Yes
0000 1110	NAND 8	Yes
0001 0000	NAND 16	Yes
0000 0000	I2C0	EEPROM Yes
0000 0110	I2C1	EEPROM Yes
0000 0001	I2C0	Slave Yes
0000 0111	I2C1	Slave Yes
0000 1000	SPI0	EEPROM Yes
0000 1001	SPI1	EEPROM Yes
0000 1010	SPI0	Flash Yes
0000 1100	SPI1	Flash Yes
0001 0010	SPI0	Slave Yes
0001 0011	SPI1	Slave Yes
xxx1 0110	UART0	Yes
xxx1 0111	UART1	Yes
0000 0100	UART2	Yes
0000 0101	HPI	No
0001 1110	Emulation Debug	No

SPI setup
SPI0 Flash and ADC
SPI1 Display
I2C0
EEPROM
UART
UART0 input RJ12
UART1 input RJ12
SW UART input PRU
SW UART input PRU

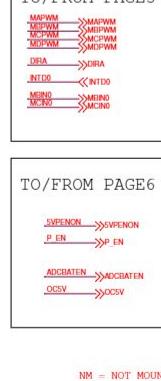
TO/FROM PAGE 3



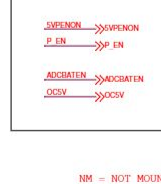
TO/FROM PAGE 4



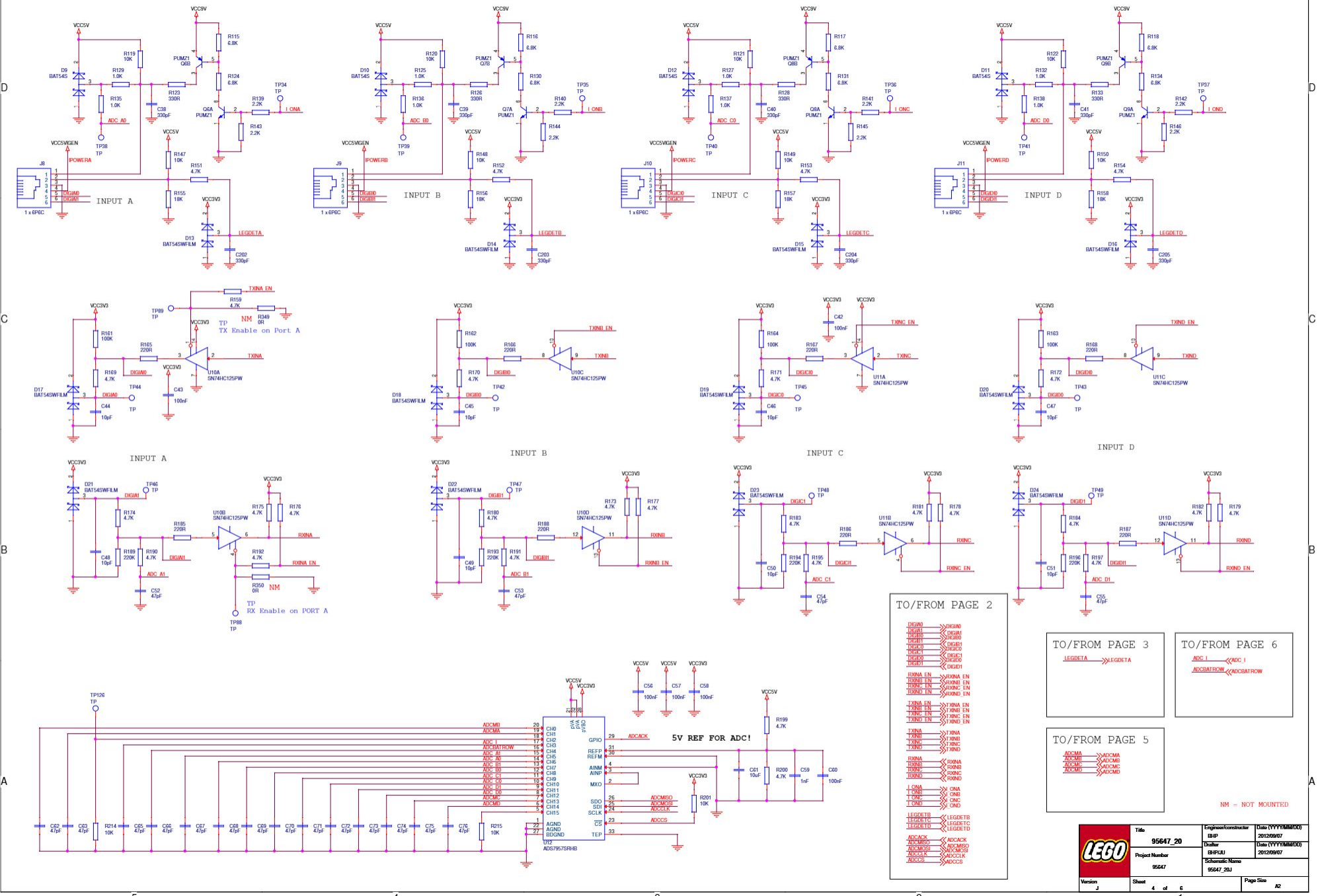
TO/FROM PAGE5

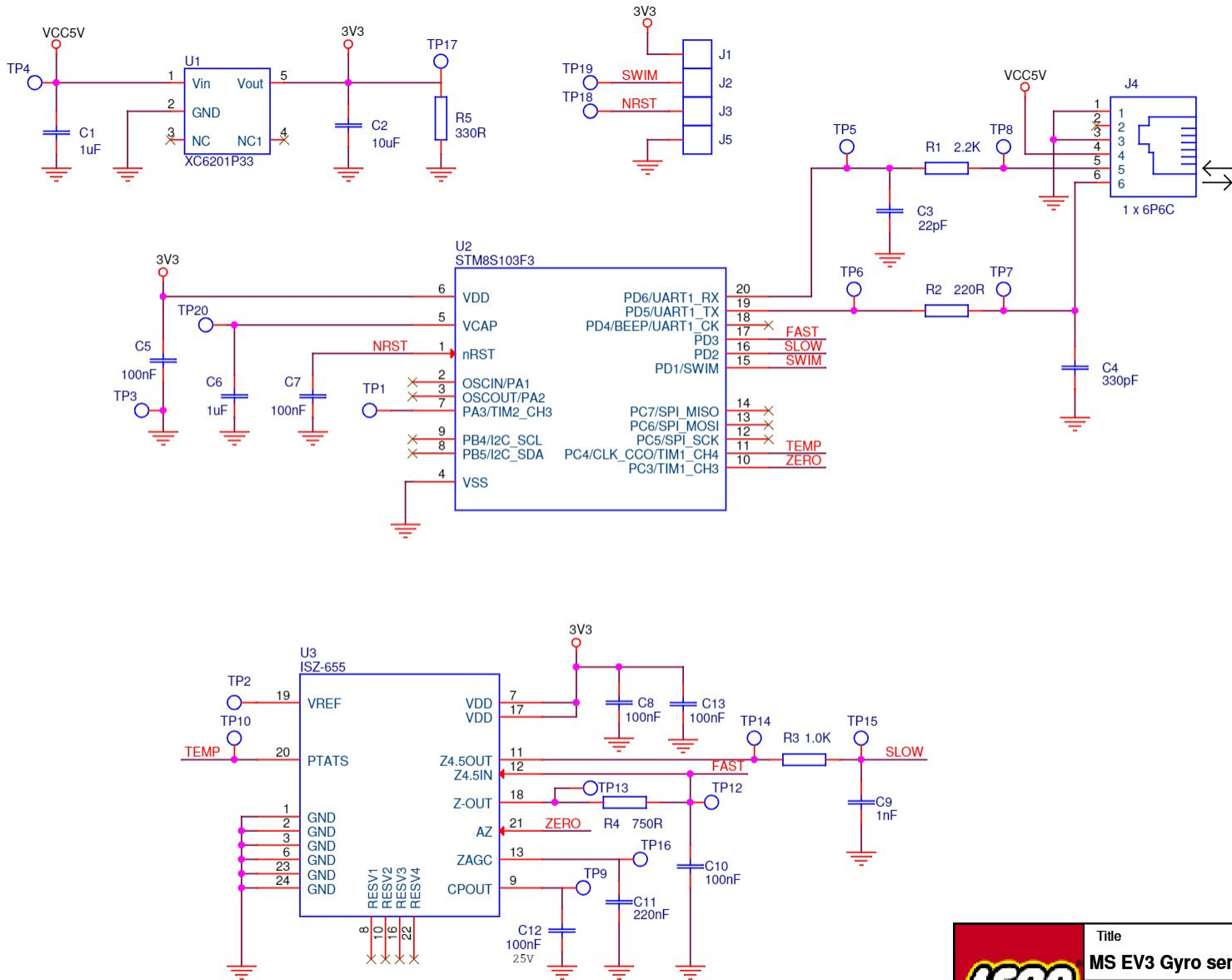



TO/FROM PAGE6

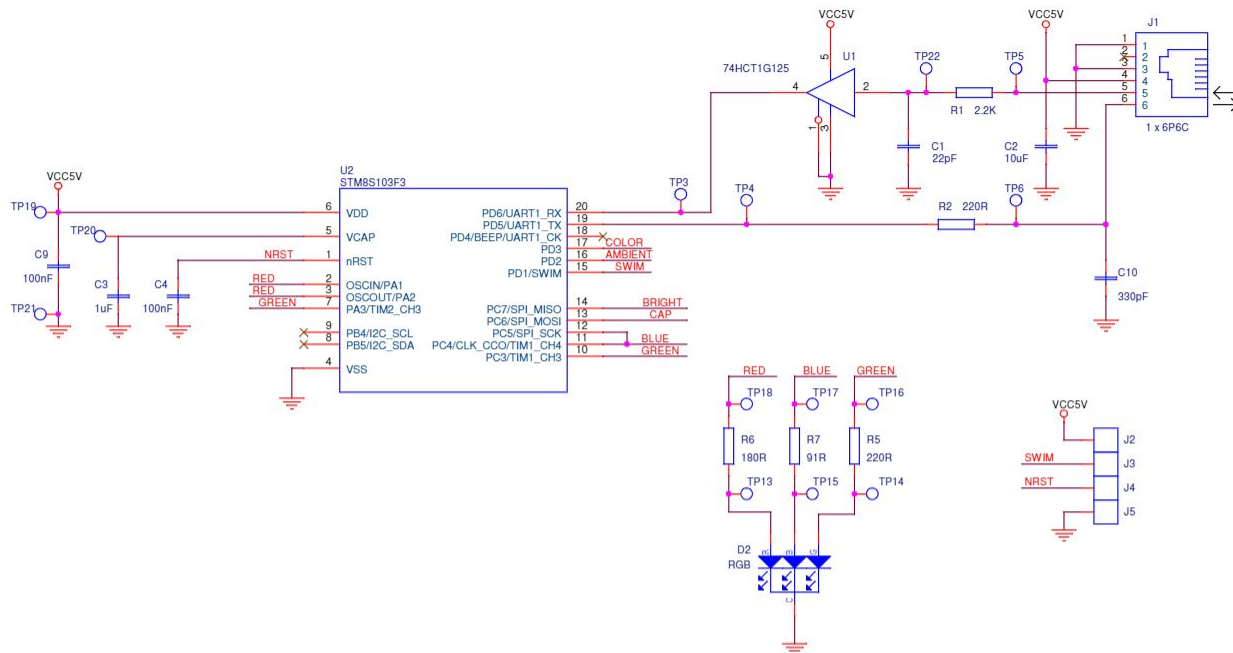


TO BE REDRAWN

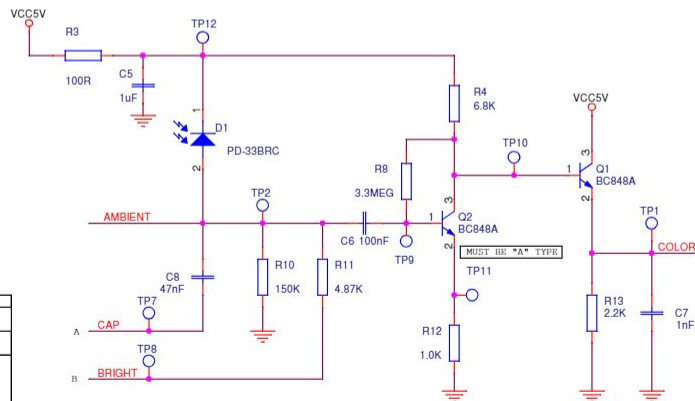


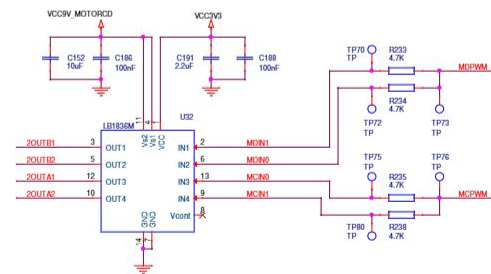
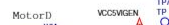
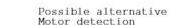


	Title	Engineer/constructor	Date (YYYY/MM/DD)
	MS EV3 Gyro sensor	PP	2012 / 05 / 03
	Project Number	Drafter	Date (YYYY/MM/DD)
	99383_20E		
Version	Sheet	Schematic Name	
	1 of 1	SCHEMATIC1	
		Page Size	A4

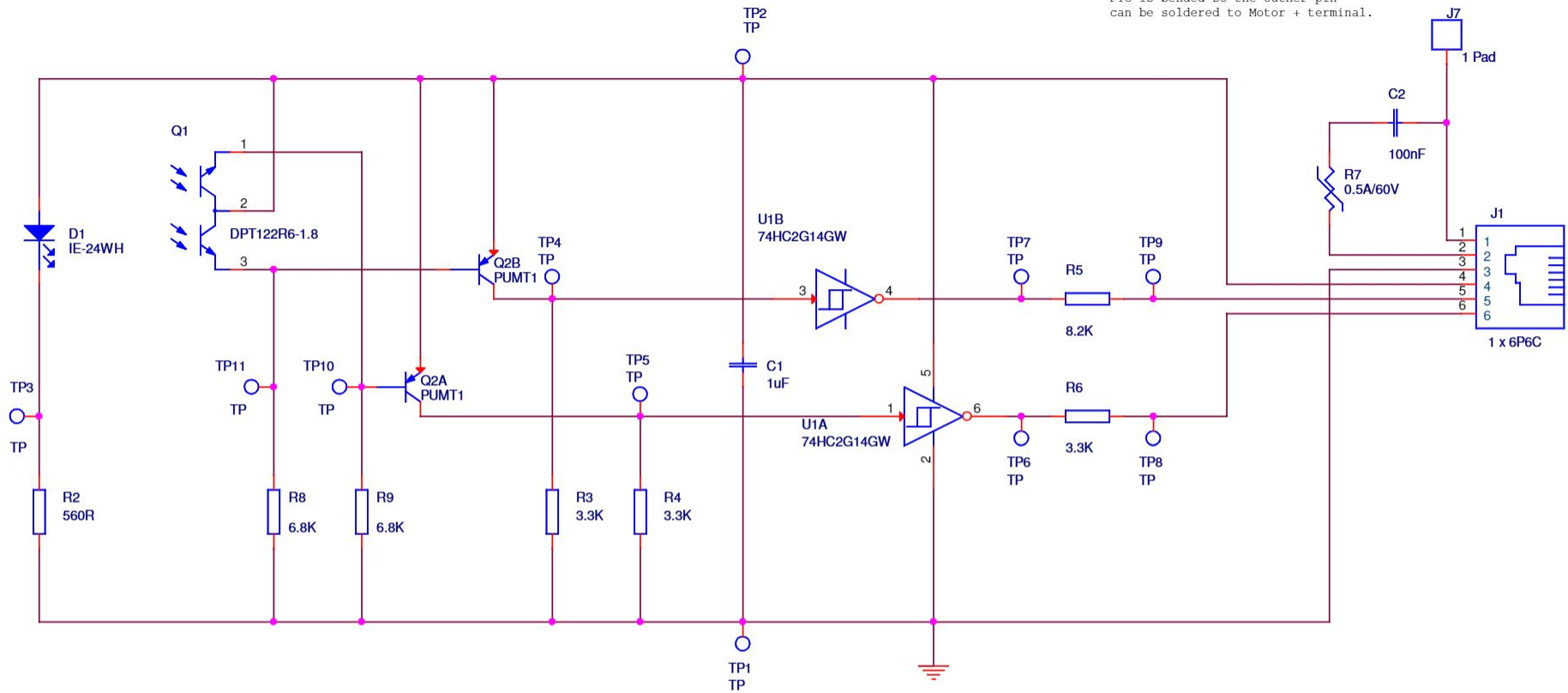



	A	B
	CAP	BRIGHT
COLOR MODE	FLOAT	FLOAT
AMBIENT DARK	LOW	FLOAT
AMBIENT BRIGHT	LOW	LOW

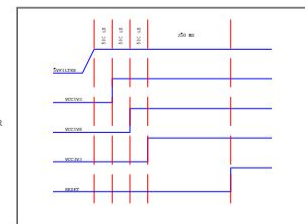
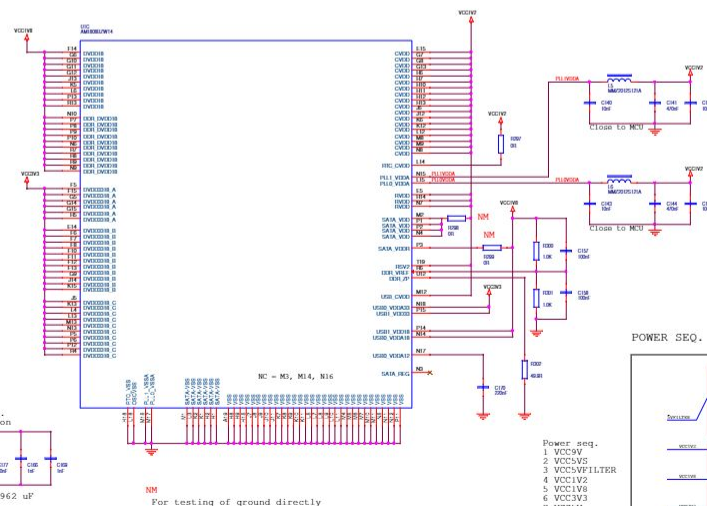
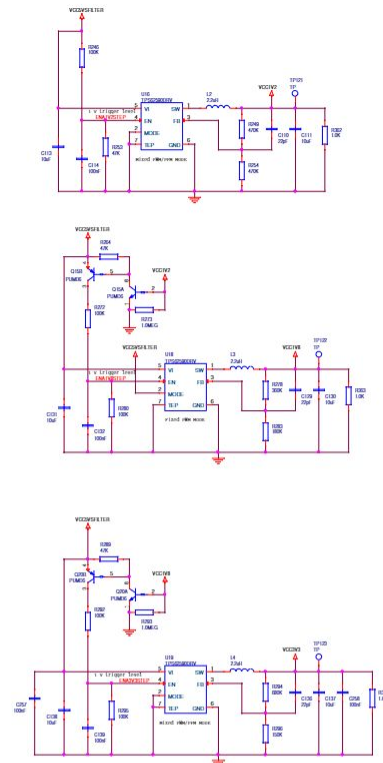





NM = NOT MOUNTED



	Title	Engineer/constructor	Date (YYYY/MM/DD)
	MS-EV3, Medium motor, PCBA	JS	2012.08.29
	Project Number	Drafter	Date (YYYY/MM/DD)
	99450_20	JS	2012.08.29
		Schematic Name	
		SCHEMATIC1	
Version	Sheet	Page Size	
E	1 of 1	A4	



NM
For testing of ground directly

	Title	Legion's controller		File (YYYYMMDD)
	95847_20	101P	20120809	
Project Number	101P41	Schematic Name		
	8547	8547_201		
Version	Sheet	Page Size		
1	C, rd, C	A3		