

view_frames Result

Recorded at time: 2915.535

world

Broadcaster: /world_link broadcaster
Average rate: 49.94
Buffer length: 4.986
Most recent transform: 2915.542
Oldest transform: 2910.556

map

Broadcaster: /ekf localization
Average rate: 30.218
Buffer length: 4.964
Most recent transform: 2915.496
Oldest transform: 2910.532

odom

Broadcaster: /odom to tf pub
Average rate: 9.927
Buffer length: 4.936
Most recent transform: 2915.483
Oldest transform: 2910.547

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

arm_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_bottom_screw_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

magnetometer

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_odom_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

teleop_camera_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

zed_Sensor_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Left_Back_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Left_Front_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Left_Middle_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Right_Back_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Right_Front_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2915.442
Oldest transform: 2910.542

wheel_Right_Middle_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_depth_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_pose_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_color_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_depth_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_left_ir_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_right_ir_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_accel_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_fisheye1_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_fisheye2_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_gyro_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_color_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_left_ir_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

d435i_right_ir_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_fisheye1_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

t265_fisheye2_optical_frame