

view_frames Result
Recorded at time: 2530.562

world

Broadcaster: /world_link broadcaster
Average rate: 50.04
Buffer length: 4.976
Most recent transform: 2530.57
Oldest transform: 2525.594

map

Broadcaster: /ekf localization
Average rate: 30.242
Buffer length: 4.96
Most recent transform: 2530.522
Oldest transform: 2525.562

odom

Broadcaster: /odom_to_tf_pub
Average rate: 15.007
Buffer length: 4.931
Most recent transform: 2530.512
Oldest transform: 2525.581

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ZEDMini

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ZEDMini_imu_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

arm_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

magnetometer

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

teleop_camera_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

zed_Sensor_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

wheel_Left_Back_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2530.542
Oldest transform: 2525.642

wheel_Left_Front_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2530.542
Oldest transform: 2525.642

wheel_Left_Middle_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2530.542
Oldest transform: 2525.642

wheel_Right_Back_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2530.542
Oldest transform: 2525.642

wheel_Right_Front_link

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 2530.542
Oldest transform: 2525.642

wheel_Right_Middle_link