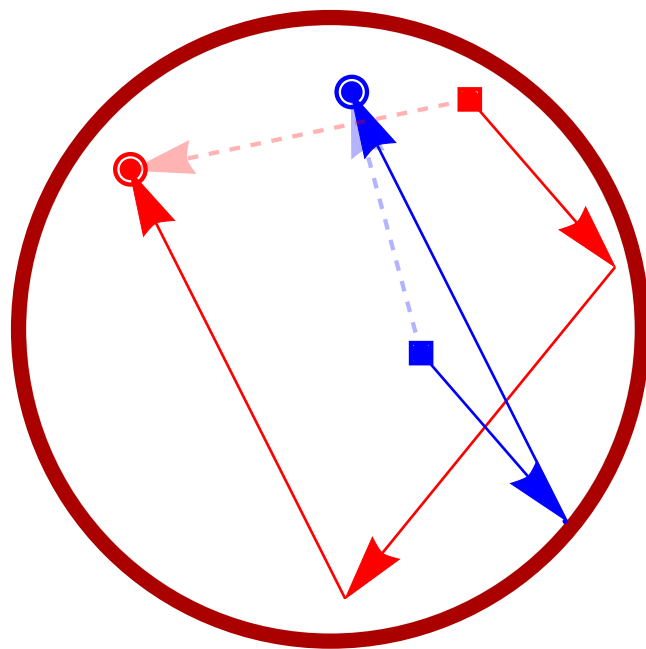


Distance 1.86 of 1.86

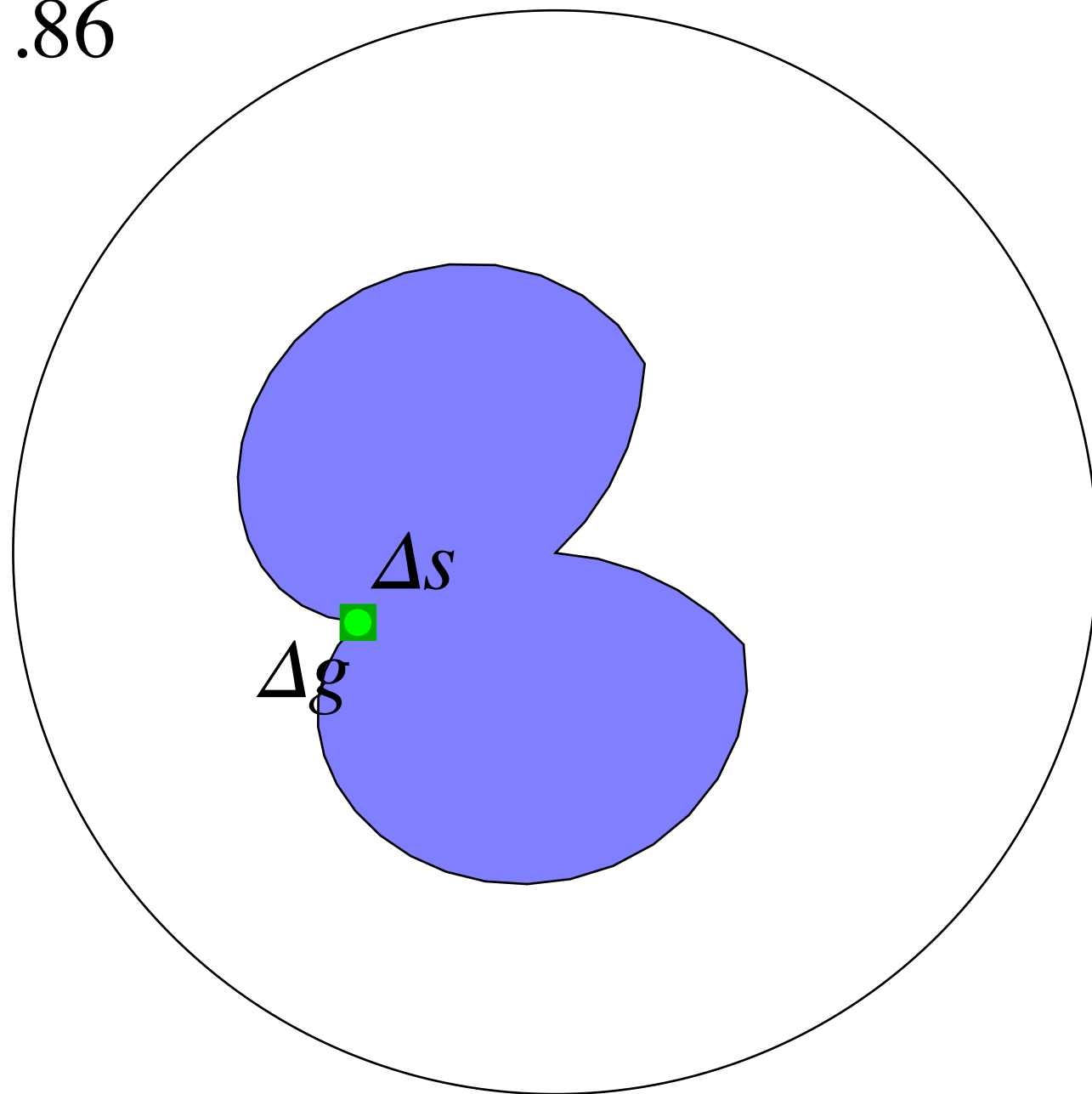
Move 3 of 3

Current ■=□—□

Goal ●=○—○



workspace



Δ configuration space