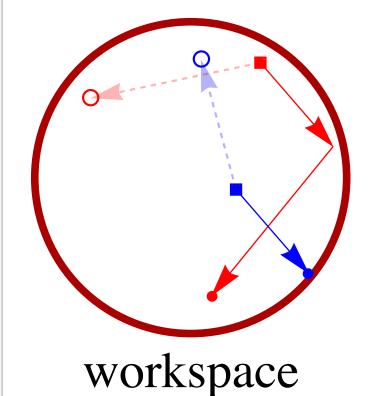
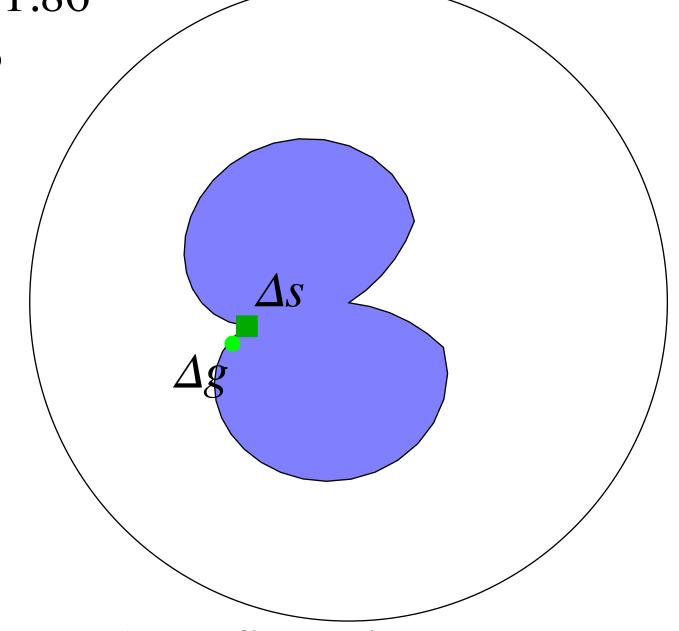
Distance 1.02 of 1.86 Move 2 of 3

Current == --

Goal •=o-o





 Δ configuration space