

RobotArm JointLimits from fusion 360 drawing. Converted to radians
above pictures.

L1

$[-2.1817 \ 2.1817]\text{rad}$

EDIT JOINT LIMITS

Motion Rotate

Minimum ☒ -125.0 deg

Maximum ☒ 125.0 deg

Rest ☐

Flip

Animate

OK Cancel

L2

$[-3.4907 \ 1.1345]\text{rad}$

EDIT JOINT LIMITS

Motion Rotate

Minimum ☒ -200.0 deg

Maximum ☒ 65.0 deg

Rest ☐

Flip

Animate

OK Cancel

L3

$[-0.6109 \ 4.1015]\text{rad}$

EDIT JOINT LIMITS

Motion Rotate

Minimum ☒ -235.0 deg

Maximum ☒ 35.0 deg

Rest ☐

Flip

Animate

OK Cancel

L4

$[-\pi \ \pi]\text{rad}$

EDIT JOINT LIMITS

Motion Rotate

Minimum ☒ -180.0 deg

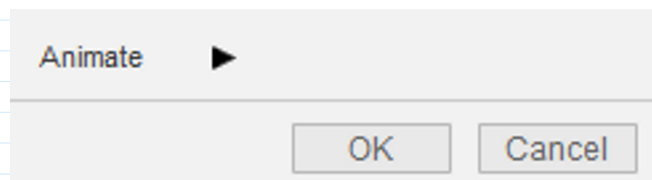
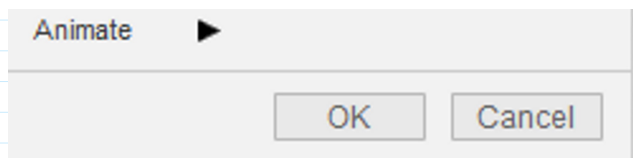
Maximum ☒ 180.0 deg

Rest ☐

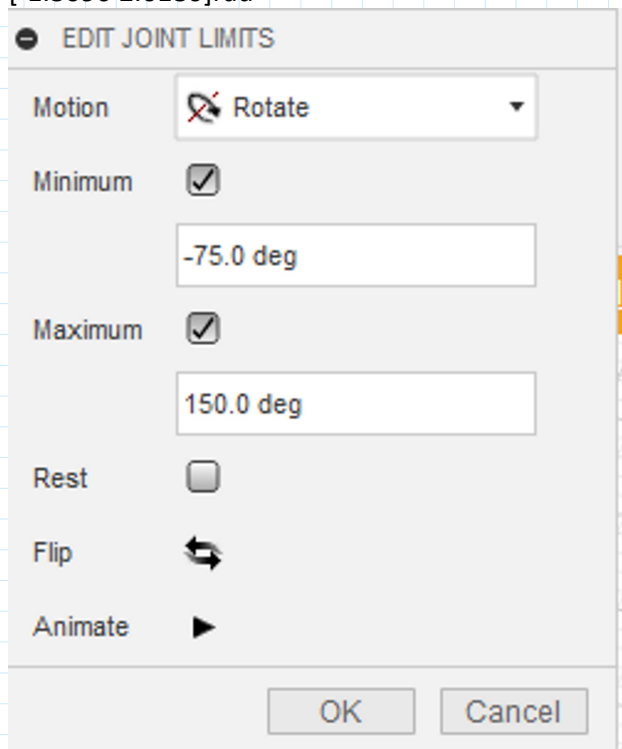
Flip

Animate

OK Cancel



L5
[-1.3090 2.6180]rad



L6
[-pi pi]rad

