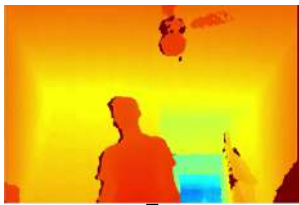
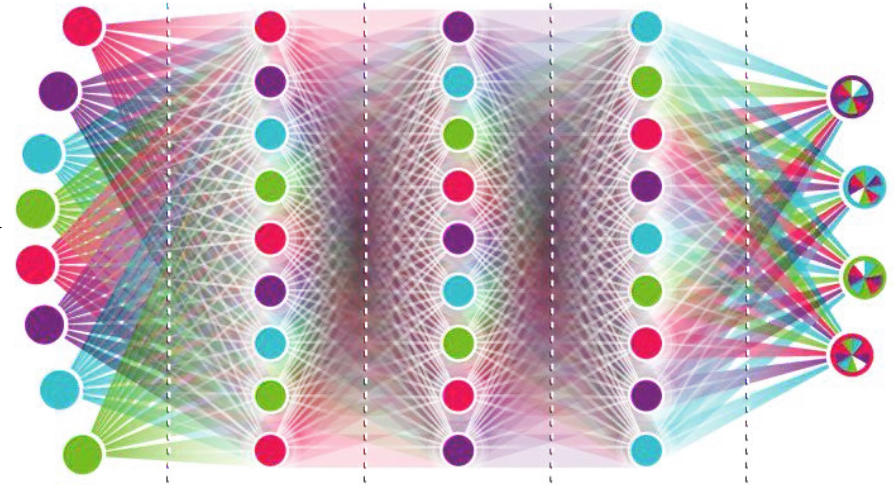


CAMERA



NETWORK



MOTORS

PID

Linear speed response

Angular speed response

TRACKERS

