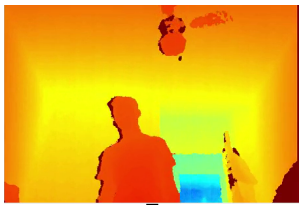
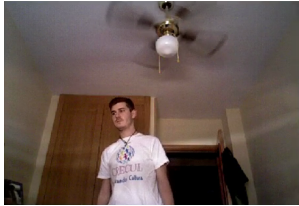
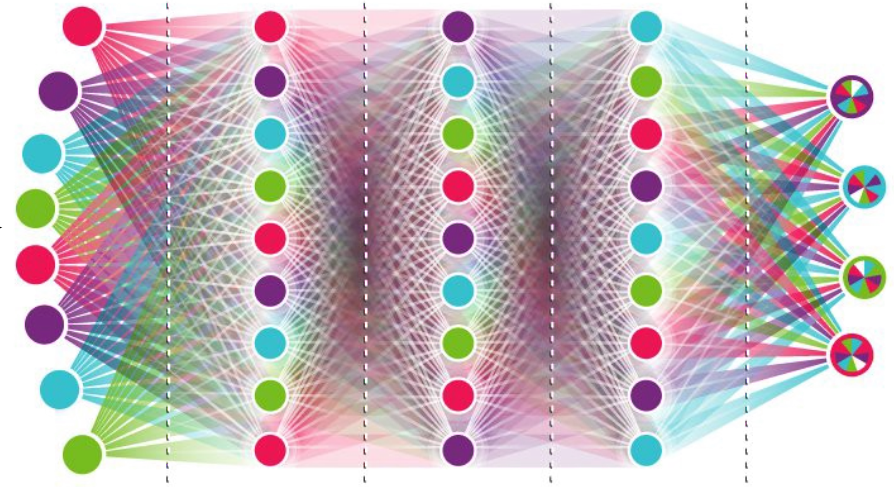


## CAMERA



## NETWORK



## MOTORS

### PID

Linear speed response

Angular speed response

## TRACKERS

