Follow Color VI

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Sim Follow Color

1. Paquete ROS: launch, world
2. Plugin `GAZEBO_PLUGIN_PATH=$GAZEBO_PLUGIN_PATH:$PWD/build`
3. Modelo `GAZEBO_MODEL_PATH=$GAZEBO_MODEL_PATH:$PWD/models`
4. Python file

Sim Follow Color

- ## Yaw:

P=0.02, I=0, D=0.001

- ## Vz:

P=0.05, I=0, D=0.005

- ## Vx:

P=0.2, I=0, D=0.0002