Follow Person III

Pedro Arias

Soluciones

- Local:
 - Seguir en nuevo equipo
 - Darknet acabará compilando

- Jetson:
 - Buscar darknet con CUDA < 10.2
 - Otra implementación de YOLO
 - o Probær cconcabble og ig in alled & It k (it)



NVIDIA Jetson AGX Xavier

Actualizar Jetpack → SDK Manager ✓



- NVIDIA 1 Factory Setup
- NVIDIA 2 Custom Setup

- Darknet:
 - CUDA >= 10.2



```
🔞 🖨 🗊 jtop AGX Xavier [16GB] - JC: Inactive - 15W DESKTOP
NVIDIA Jetson AGX Xavier [16GB] - Jetpack 4.6 [L4T 32.6.1]
 - Up Time:
                   0 days 0:28:7
                                                  Version: 3.1.1
                   4.6 [L4T 32.6.1]
                                                  Author: Raffaello Bonghi
 - Jetpack:
                                                   e-mail: raffaello@rnext.it
 - Board:
                     AGX Xavier [16GB]
   * Type:
   * SOC Family:
                     tegra194
                                   ID: 25
   * Module:
                     P2888-0001
                                  Board: P2822-0000
   * Code Name:
                     galen
   * Cuda ARCH:
                     7.2
   * Serial Number: 0421419020930
 - Libraries:
                                              - Hostname:
                                                             jetson
   * CUDA:
                   10.2.300
                                              - Interfaces:
   * OpenCV:
                   4.1.1 compiled CUDA: NO
                                                * eth0:
                                                             10.117.150.93
   * TensorRT:
                   8.0.1.6
                                                * docker0:
                                                            172.17.0.1
   * VPI:
                   ii libnvvpi1 1.1.12 arm64 NVIDIA Vision Programming Interface
 li* VisionWorks: 1.6.0.501
   * Vulkan:
                   1.2.70
                   8.2.1.32
   * cuDNN:
                                                                 Raffaello Bonghi
1ALL 2GPU 3CPU 4MEM 5CTRL
                               6INFO Quit
```

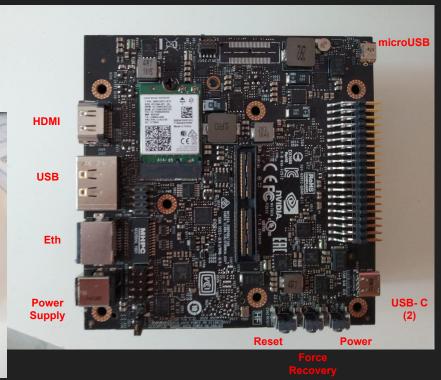
SDK Manager

- No detecta Nvidia Jetson
 - o Isusb
- USB-C (2) & Recovery Mode



Recovery Mode

(1. Off) Hold Force Recovery + Press Power(2. On) Hold Force Recovery + Hold Reset + Release



Setup I

1. ROS (base)

ROS_DISTRO=melodic
ROS_WORKSPACE=/home/nvidia/catkin_ws

2. catkin ws

\$ sudo apt-get install python3-catkin-tools

\$ cd && mkdir -p /catkin_ws/src

\$ cd /catkin ws && catkin init

\$ catkin build

3. drones

\$ sudo apt-get install ros-melodic-mavros ros-melodic-mavros-extras ros-melodic-cv-bridge

\$ cd repos && git clone https://github.com/JdeRobot/drones.git -b melodic-devel

\$ roscd && cd src && In -s ~/repos/drones/drone wrapper.

\$ roscd && catkin build 1

4. Darknet

export PATH="\$PATH:/usr/local/cuda-10.2/bin" export LD_LIBRARY_PATH="\$LD_LIBRARY_PATH:/usr/local/cuda-10.2/lib64"

\$ git clone https://github.com/AlexeyAB/darknet

\$ cd darknet

\$ wget https://github.com/AlexeyAB/darknet/releases/download/darknet_volo_v4/yolov4.weighttle

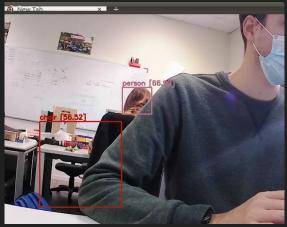
\$ make # after setting FLAGS in Makefile

Darknet sobre Jetson

- Darknet Wrapper
- YOLOv4 → demasiado pesada, tiny?

```
import numpy as np
import cv2
import yolo utils
# yolo4 = yolo utils.YOLOv4()
cap = cv2.VideoCapture("/dev/video0") # check this
    # Capture frame-by-frame
    ret, frame = cap.read()
    # Flip verticallly
    frame = cv2.flip(frame, 0)
    # Our operations on the frame come here
    yolo4 tiny.detect frame(frame)
    # Display the resulting frame
    cv2.imshow('frame', frame)
    if cv2.waitKey(1) & 0xFF == ord('q'):
# When everything done, release the capture
```



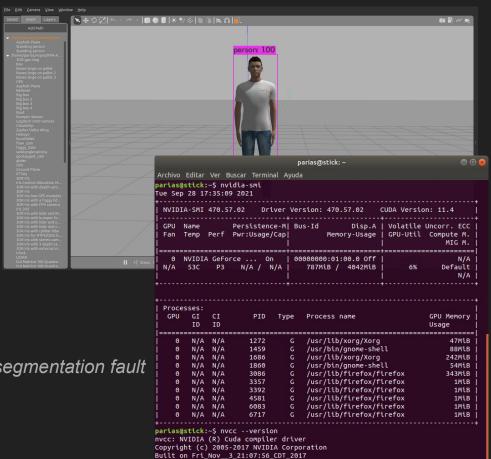


Darknet en local

- Muy lento
- Sin espacio para CUDA cuDNN

- Ubuntu -> USB 128Gb
 - Todavía en proceso de instalación
 - CUDA y cuDNN
 - Problema al compilar darknet -> segmentation fault

CUDA v11.4 nvcc v9.1 cuDNN v8.2.4



Cuda compilation tools, release 9.1, V9.1.85

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