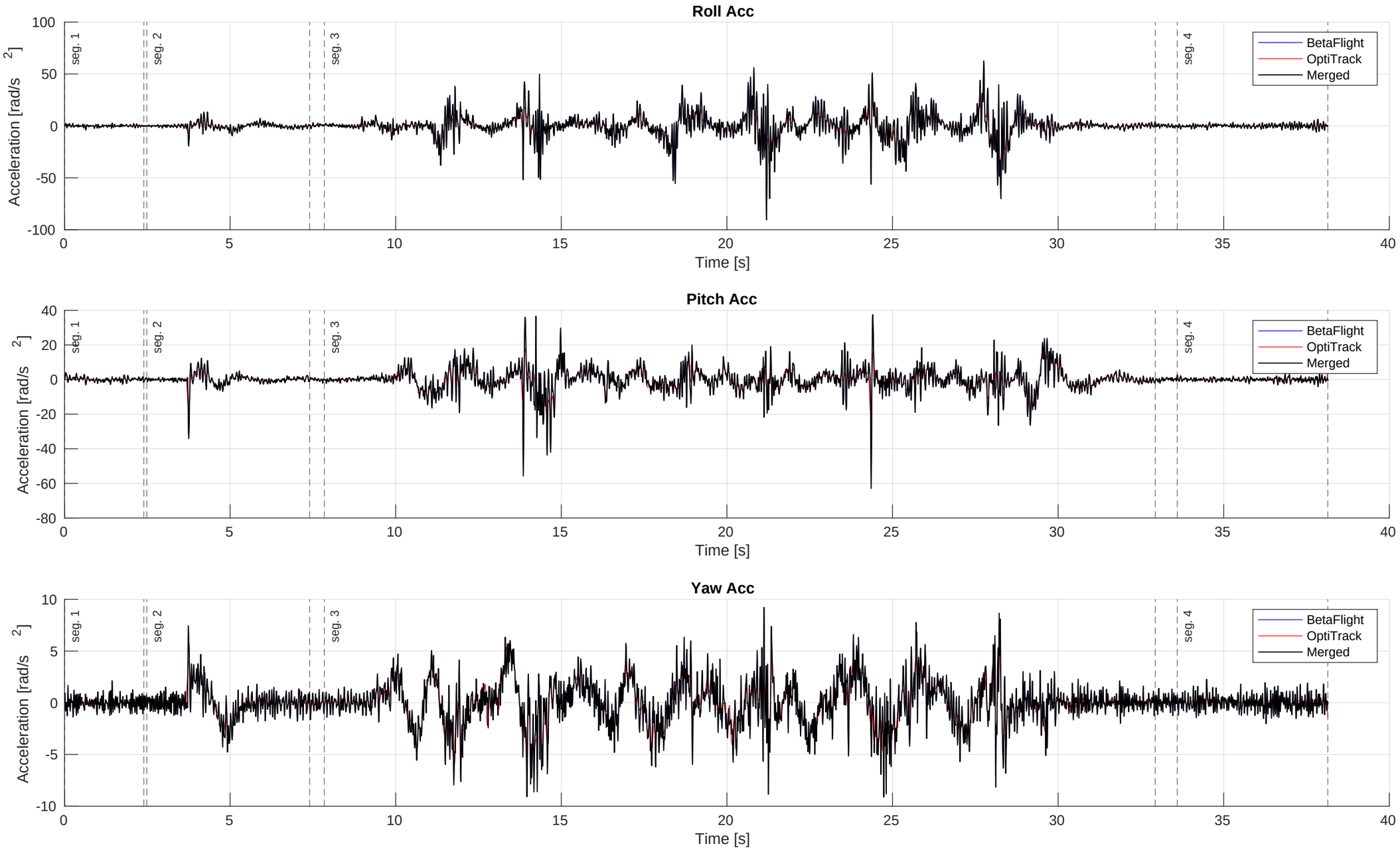
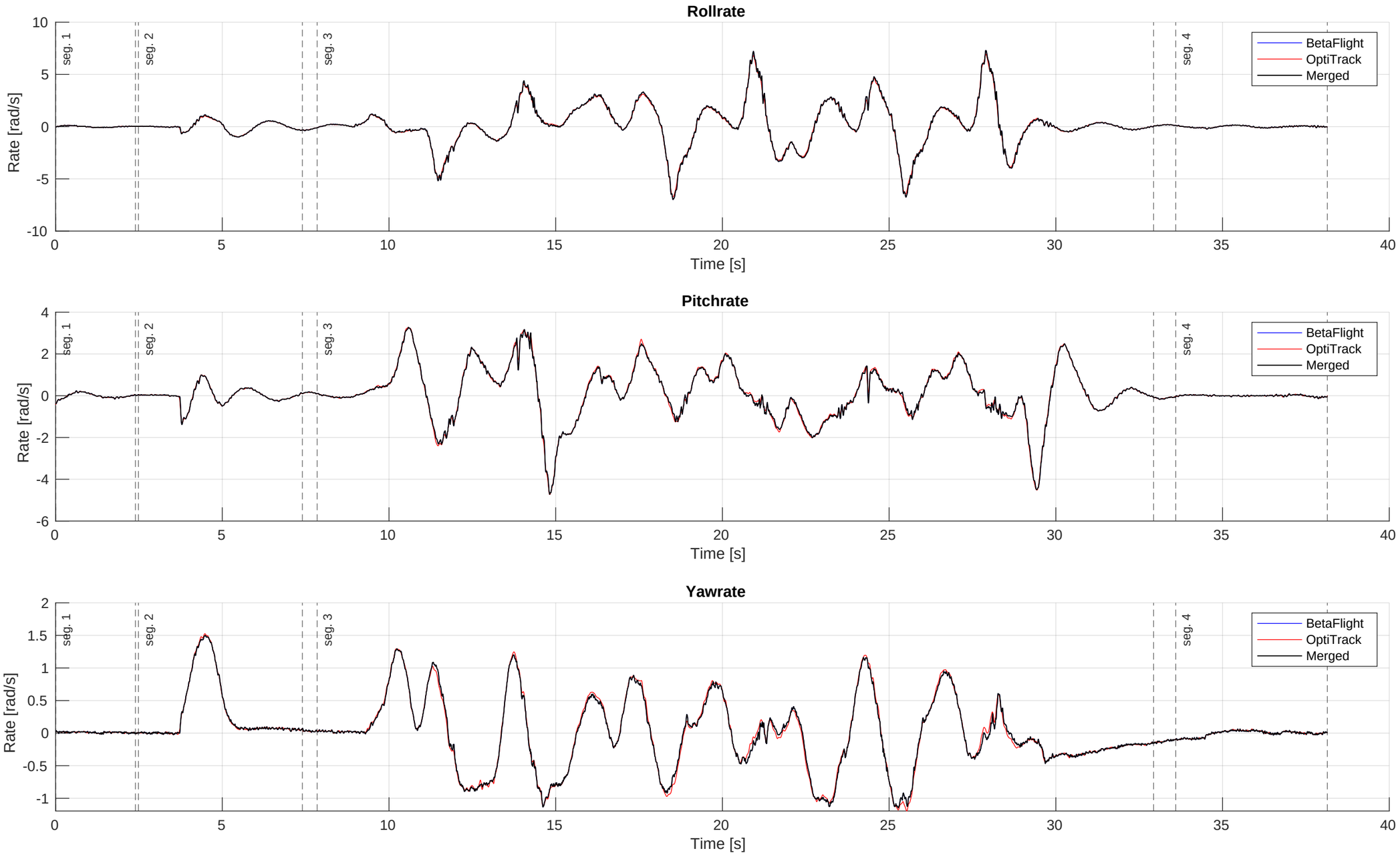
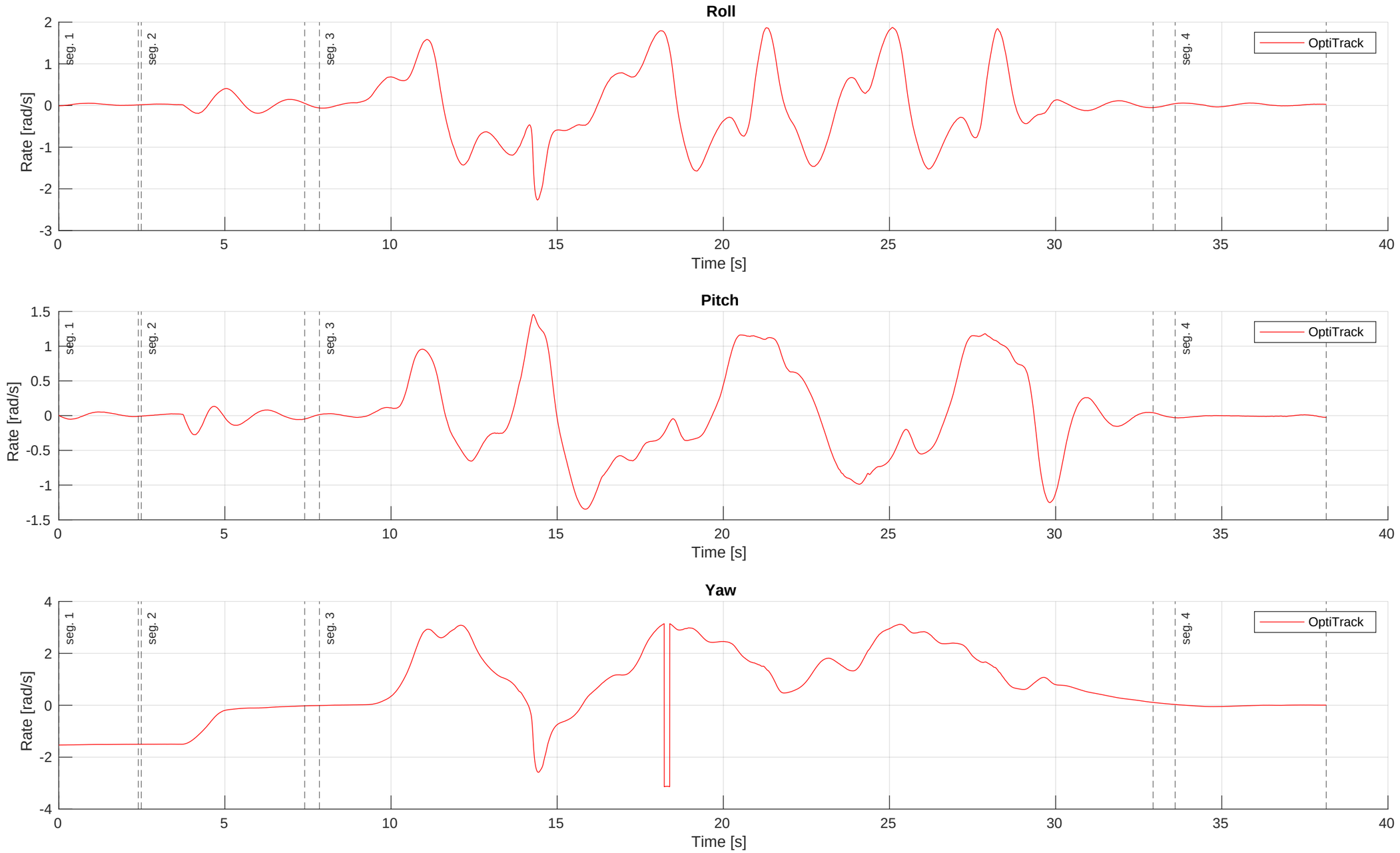
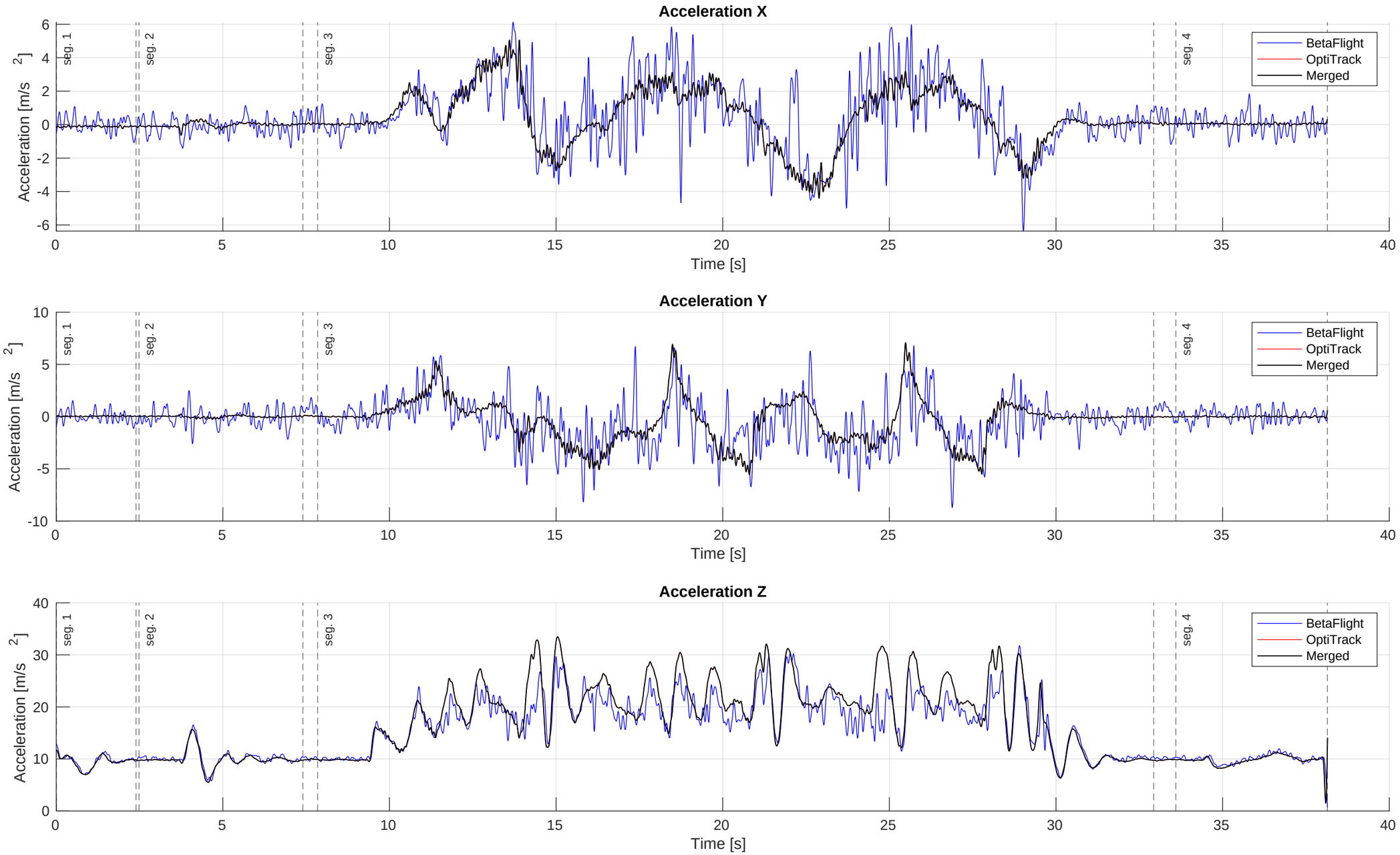
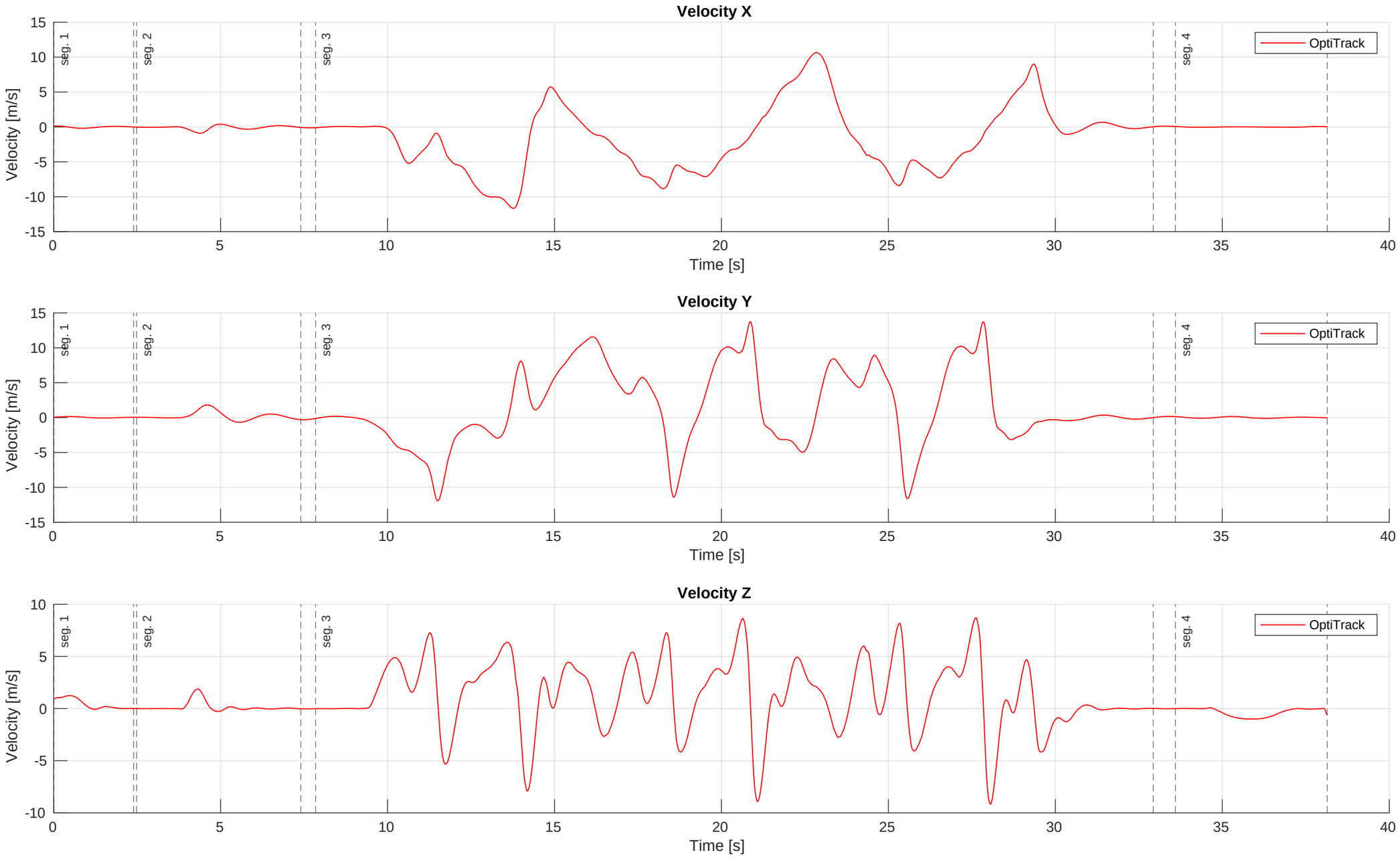
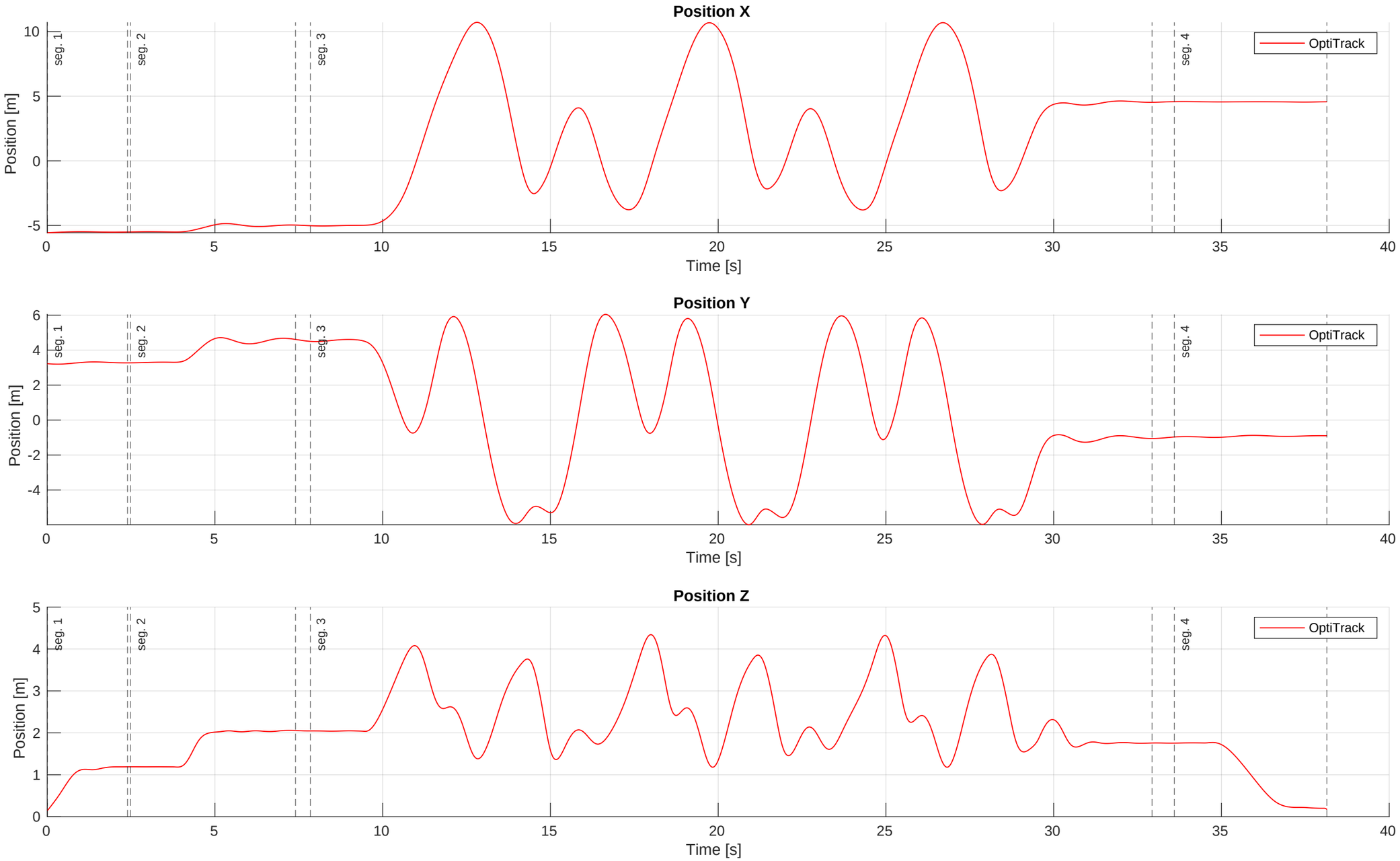

Roll Acc
Pitch Acc
Yaw Acc
Acceleration [rad/s 2]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
BetaFlight
OptiTrack
Merged

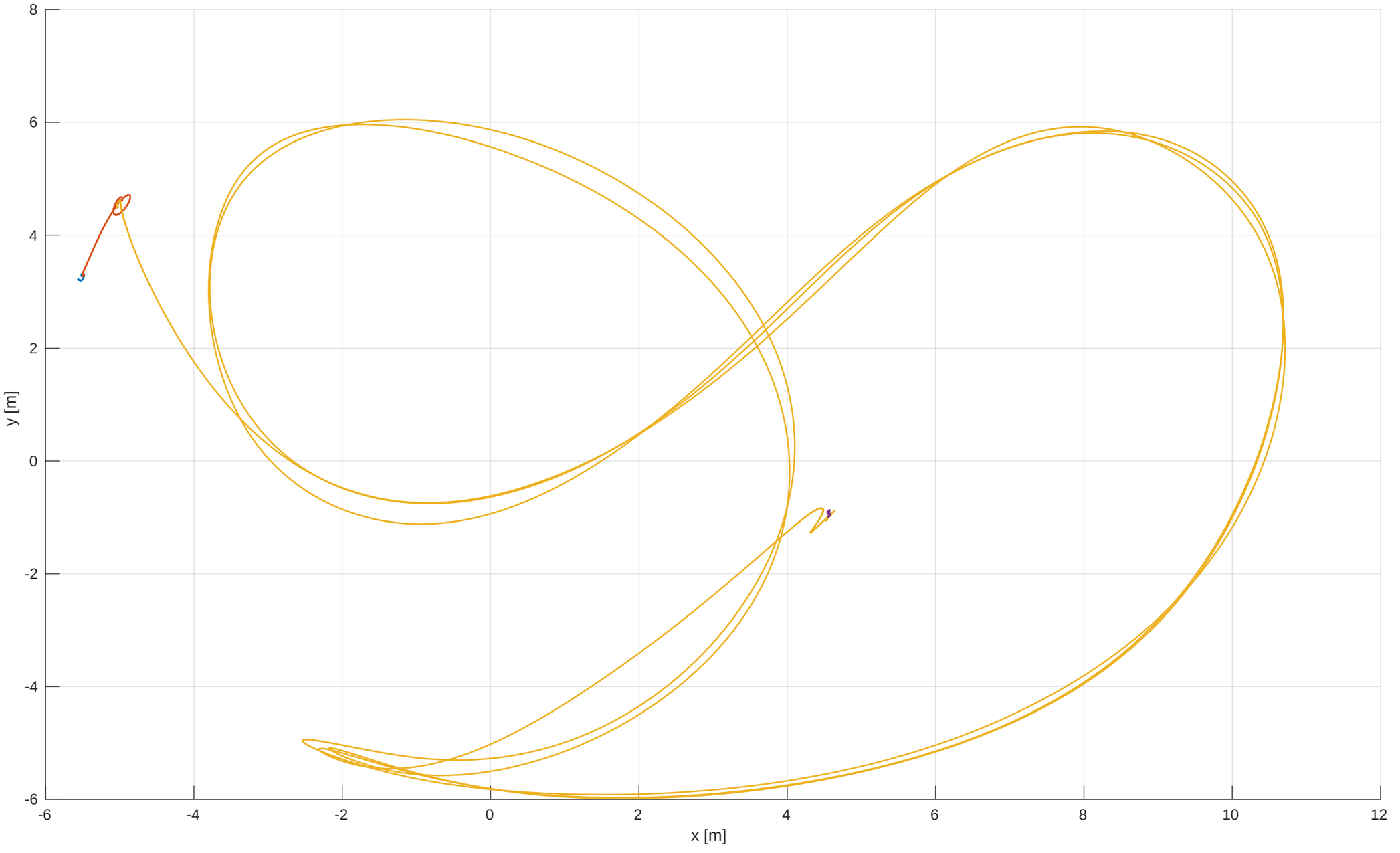

Rollrate
Pitchrate
Yawrate
Rate [rad/s]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
BetaFlight
OptiTrack
Merged

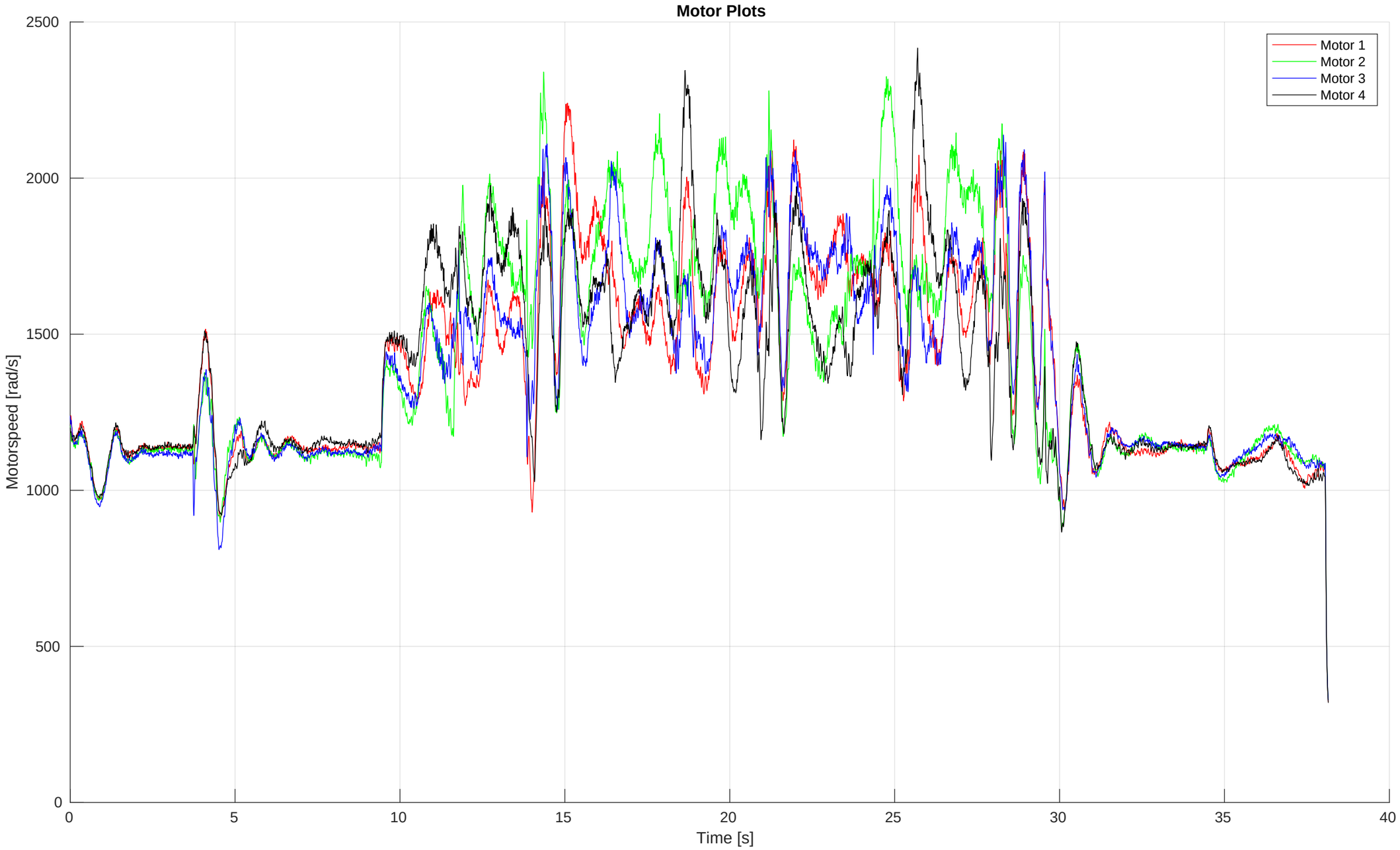

Roll
Pitch
Yaw
OptiTrack
seg. 1
seg. 2
seg. 3
seg. 4
Rate [rad/s]
Time [s]


Acceleration X
Acceleration Y
Acceleration Z
Acceleration [m/s 2]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
BetaFlight
OptiTrack
Merged


Velocity X
Velocity Y
Velocity Z
Velocity [m/s]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
OptiTrack


Position X
Position [m]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
OptiTrack
Position Y
Position [m]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
OptiTrack
Position Z
Position [m]
Time [s]
seg. 1
seg. 2
seg. 3
seg. 4
OptiTrack


8
6
4
2
0
-2
-4
-6
y [m]
-6
-4
-2
0
2
4
6
8
10
12
x [m]


Motor Plots
Motor 1
Motor 2
Motor 3
Motor 4
Motorspeed [rad/s]
Time [s]
0
500
1000
1500
2000
2500
0
5
10
15
20
25
30
35
40