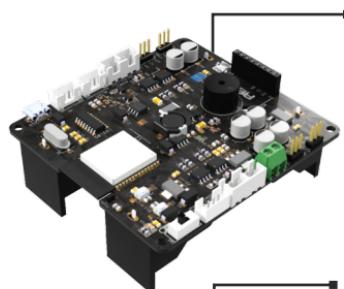


Required Components to build TrackerBot

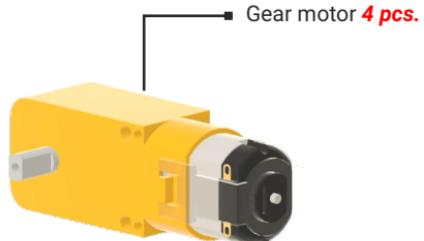


Rex 8in1 MainBoard

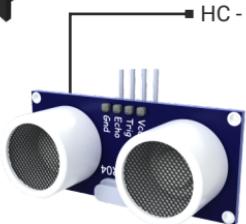


TCRT500 (Line Follower)

■ Converter Board



■ Gear motor **4 pcs.**



■ HC - SR04



■ M3 Nuts **16 pcs.**



■ M3 x 6mm screw **4 pcs.**



■ M3 x 8mm screw **16 pcs.**



■ M3 x 12mm screw **6 pcs.**



■ M3 x 30mm screw **8 pcs.**



■ Track pieces with pins **57pcs.**
(27 for each side)



■ M3 x 25mm female spacer **8 pcs.**



■ M3 x 20mm female spacer **12 pcs.**



■ DC Gear Motor Hub **4pcs.**

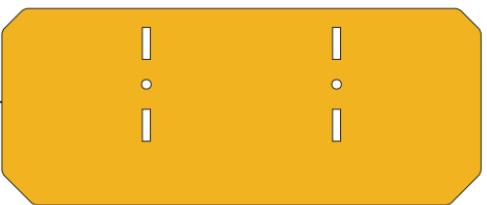
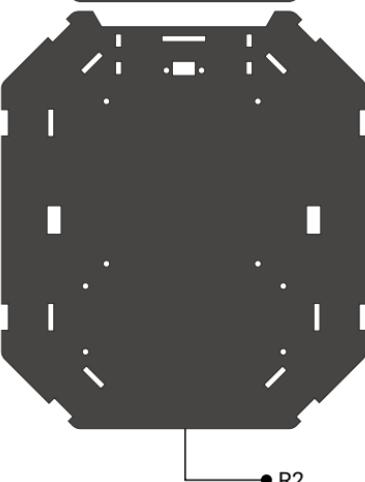
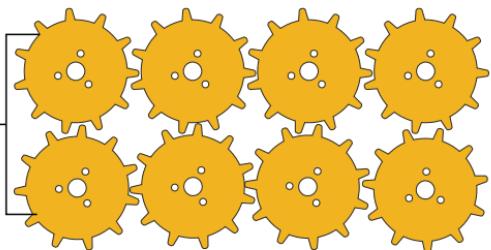
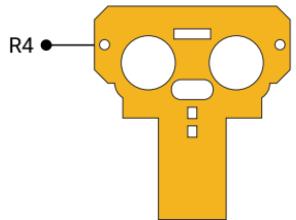
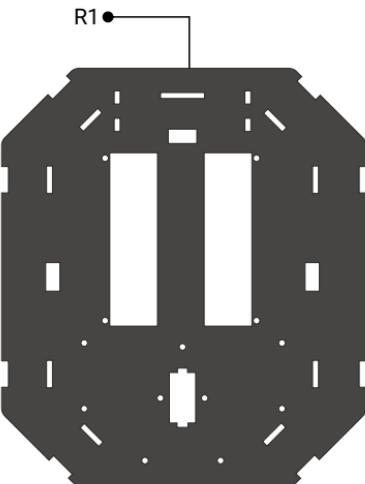
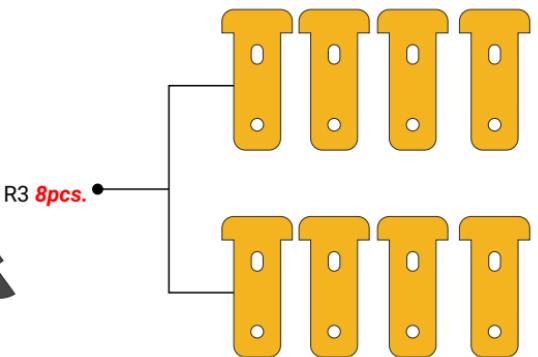
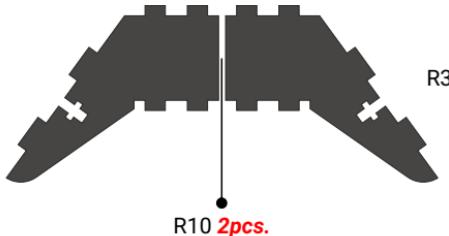


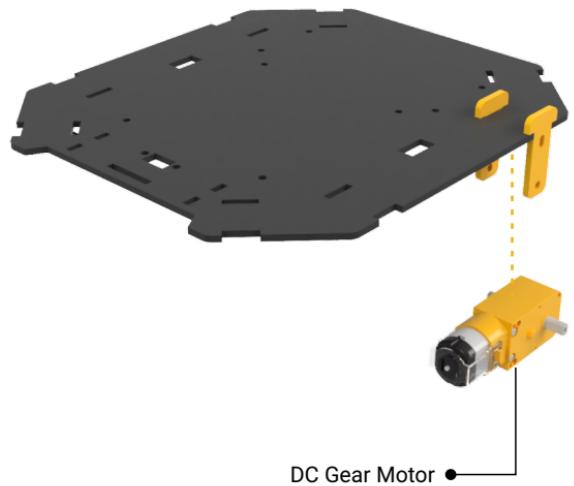
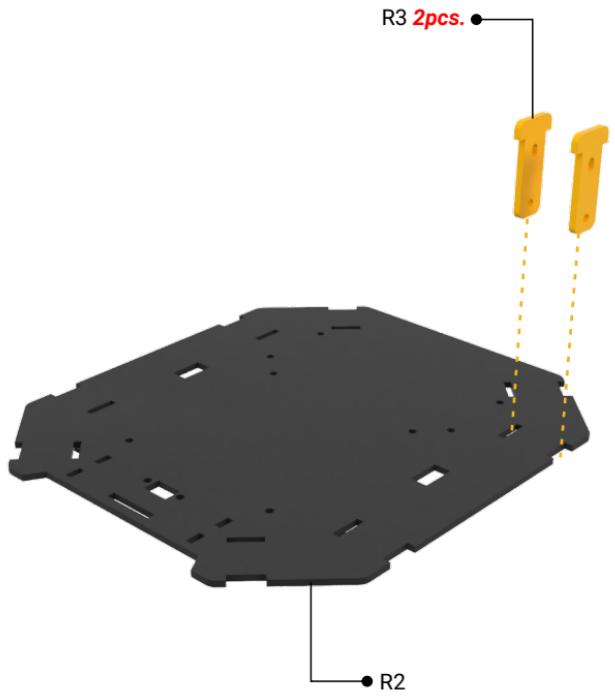
■ M3 x 6mm female - male spacer **4 pcs.**

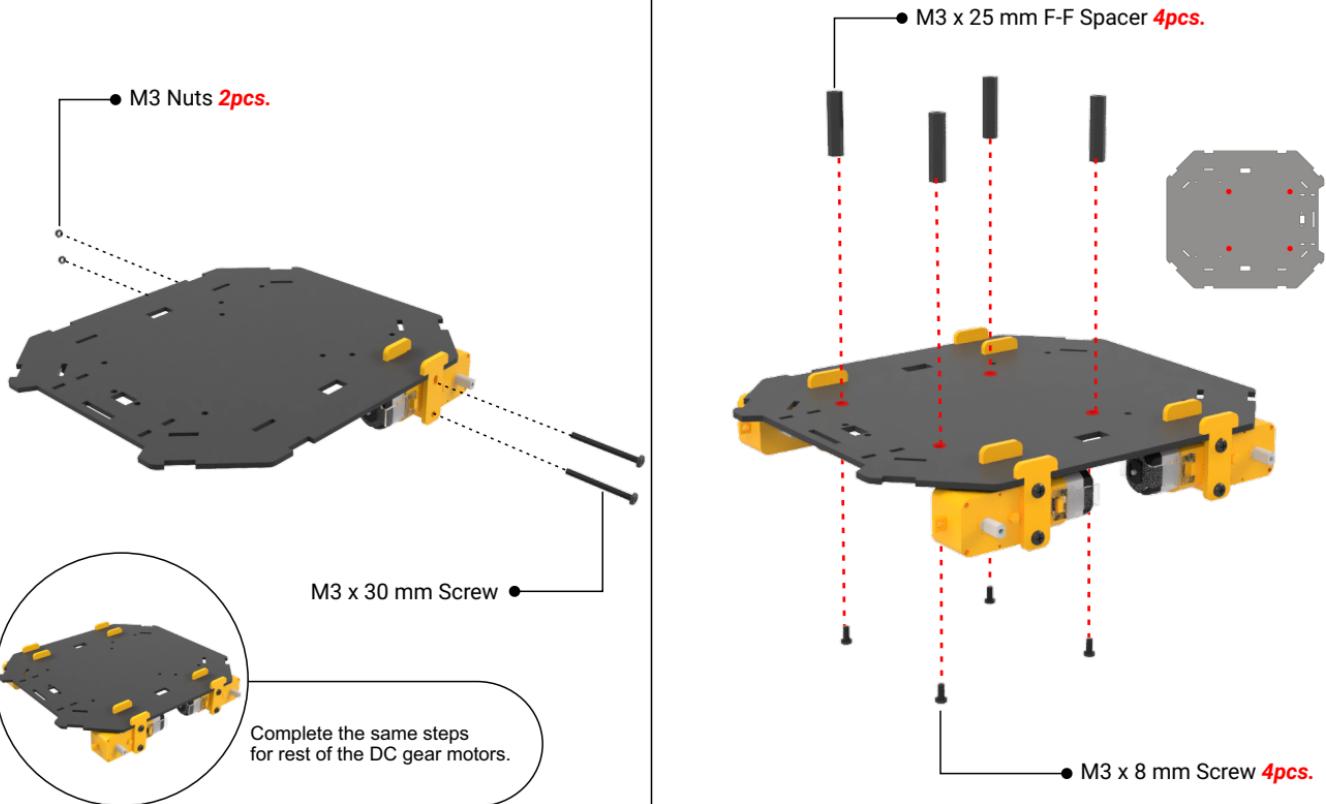


■ M2 x 8mm Wooden tip Screw **4pcs.**

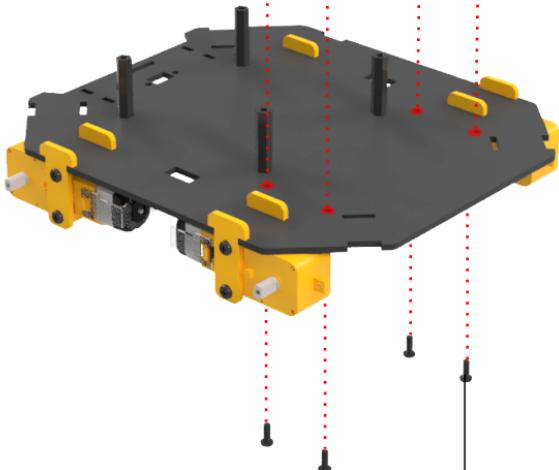
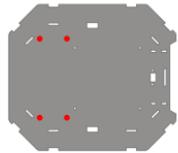
Required Parts







M3 x 25 mm F-F Spacer **4pcs.**



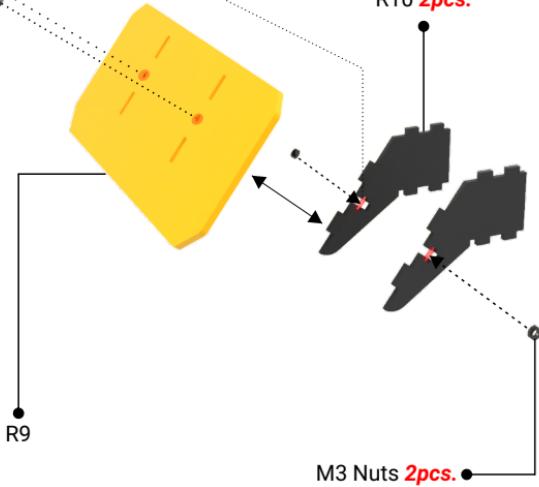
M3 x 8 mm Screw **4pcs.**

M3 x 12 mm Screw **2pcs.**

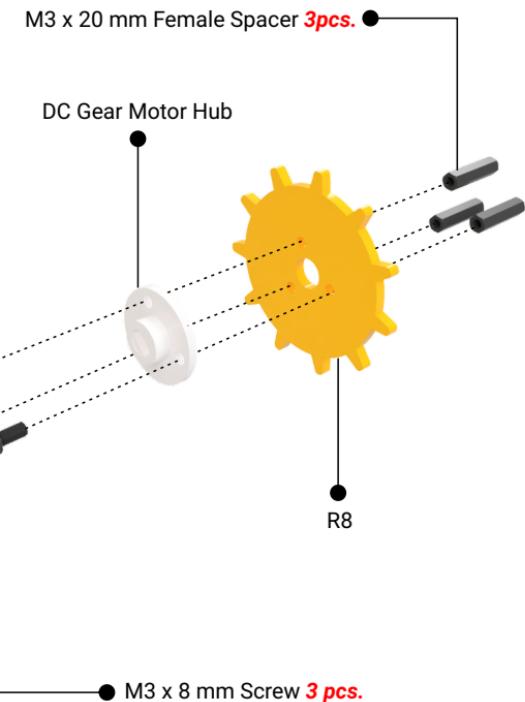
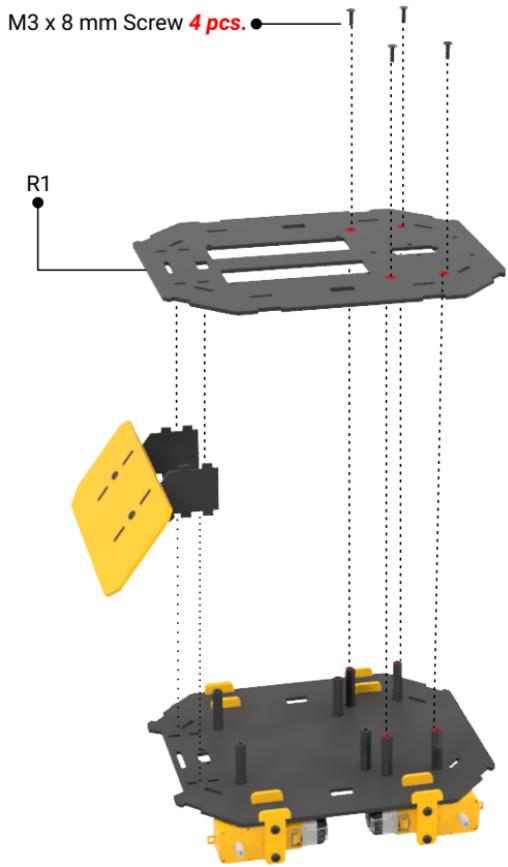


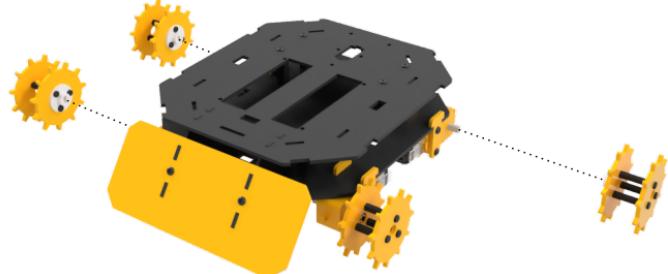
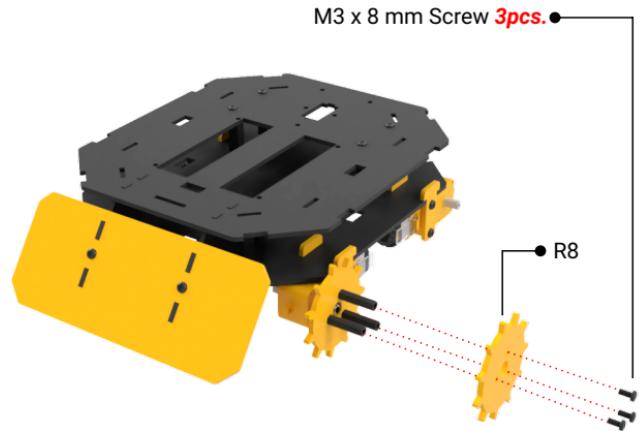
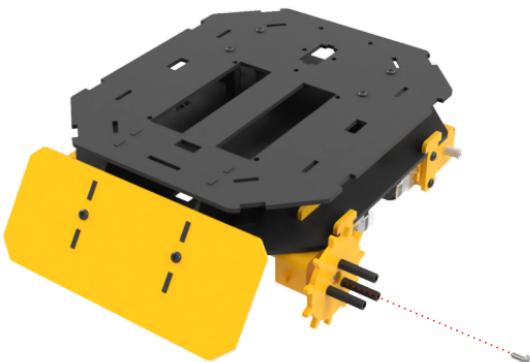
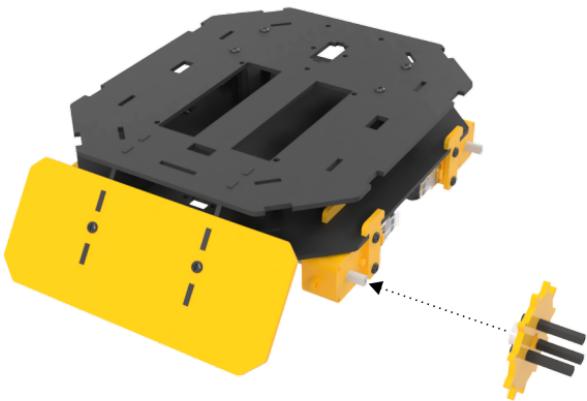
For T slot joint setup first, place the **M3 Nut** into the **Nest** then tighten the joint with using **M3 x 12mm screw**.

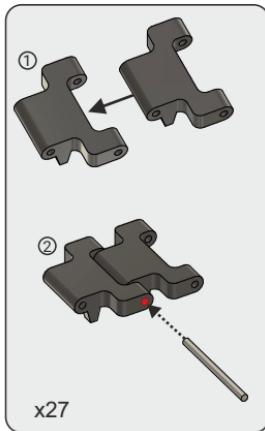
R10 **2pcs.**



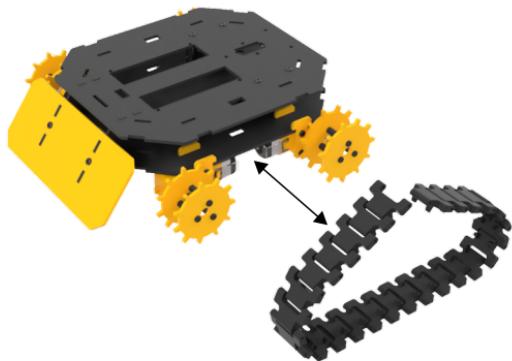
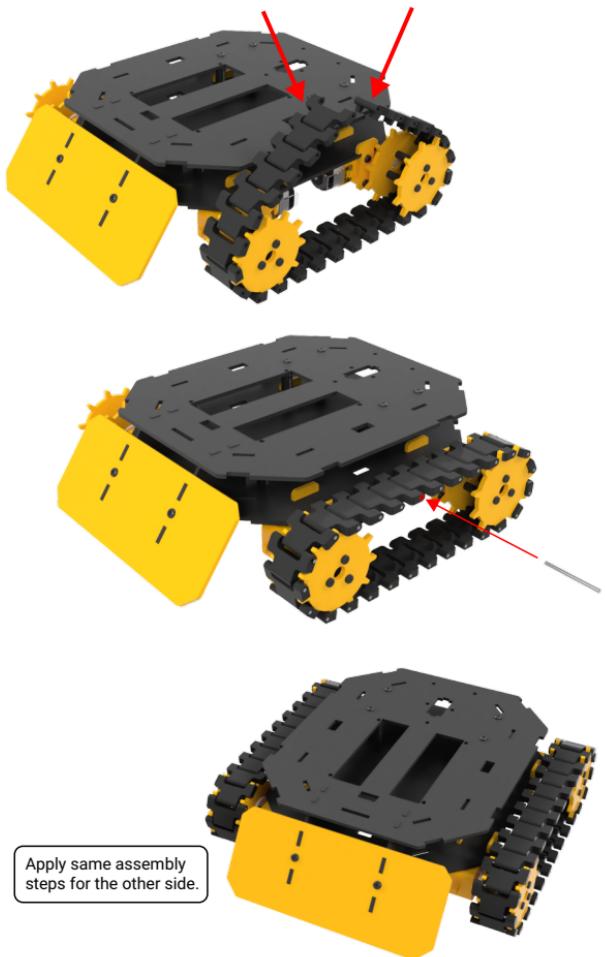
M3 Nuts **2pcs.**

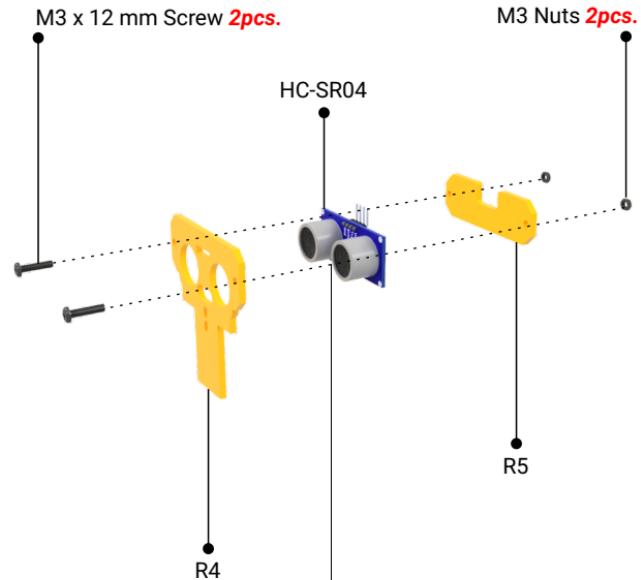
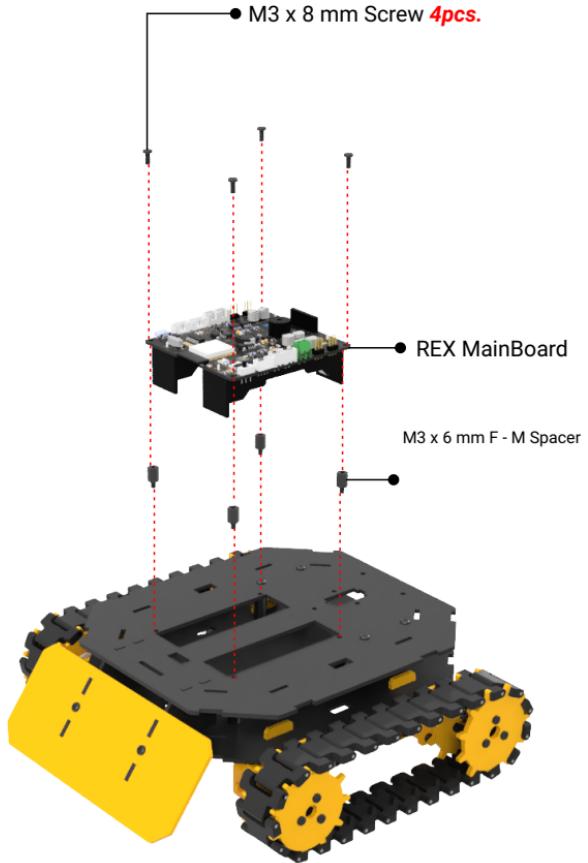






x27





Make sure HC-SR04 pins are facing upward as in the image.

