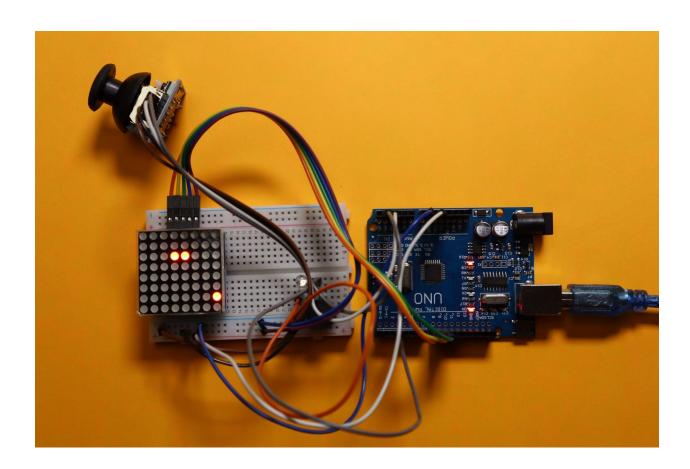
Joystick controlled snake game using Arduino UNO

Material Required **a**:

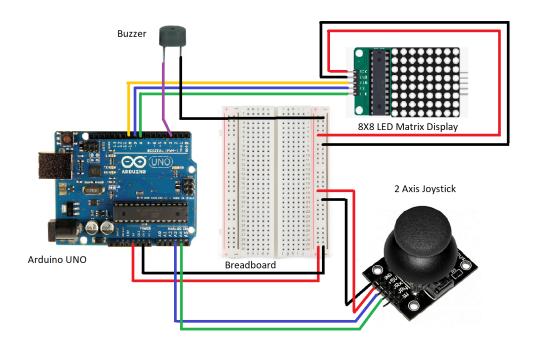
S No.	Components	Link
1	Arduino UNO	https://amzn.to/3R5IQPT
2	Breadboard Small	https://amzn.to/3QdsROy
3	8X8 LED Dot matrix display	https://amzn.to/3RnVYPG
4	2 Axis Joystick	https://amzn.to/3roN7CI
5	Buzzer	https://amzn.to/3rpQFos
6	LED	
7	Connecting Wires	https://amzn.to/3cl97EY
8	Arduino UNO Cable	https://amzn.to/3Cqxn8z



Robotix.io: https://linktr.ee/robotixio

Circuit Diagram ≠ :

Snake Game Circuit Diagram



Code ::

Robotix.io: https://linktr.ee/robotixio

```
int rPos; //The row index of the apple
 int cPos; //The column index of the apple
};
//MAX72XX led Matrix
const int DIN =10;
const int CS =9;
const int CLK = 8:
LedControl Ic = LedControl(DIN, CLK, CS,1);
const int varXPin = A3;//X Value from Joystick
const int varYPin = A4;//Y Value from Joystick
byte pic[8] = \{0,0,0,0,0,0,0,0,0\};//The 8 rows of the LED Matrix
Snake snake = \{\{1,5\},\{\{0,5\},\{1,5\}\}, 2,\{1,0\}\}\};//Initialize a snake object
Apple apple = \{(int)random(0.8),(int)random(0.8)\};//Initialize an apple object
//Variables To Handle The Game Time
float oldTime = 0:
float timer = 0:
float updateRate = 3;
int i,j;//Counters
void setup() {
 // put your setup code here, to run once:
  The MAX72XX is in power-saving mode on startup,
  we have to do a wakeup call
  */
 pinMode(buzzer,OUTPUT);
 lc.shutdown(0,false);
 /* Set the brightness to a medium values */
 lc.setIntensity(0,8);
 /* and clear the display */
 lc.clearDisplay(0);
 //Set Joystick Pins as INPUTs
 pinMode(varXPin, INPUT);
 pinMode(varYPin, INPUT);
void loop() {
 // put your main code here, to run repeatedly:
 float deltaTime = calculateDeltaTime();
 timer += deltaTime;
 //Check For Inputs
 int xVal = analogRead(varXPin);
 int yVal = analogRead(varYPin);
```

```
if(xVal<100 && snake.dir[1]==0){
  snake.dir[0] = 0;
  snake.dir[1] = -1;
 }else if(xVal >920 && snake.dir[1]==0){
  snake.dir[0] = 0;
  snake.dir[1] = 1;
 }else if(yVal<100 && snake.dir[0]==0){
  snake.dir[0] = -1;
  snake.dir[1] = 0;
 }else if(yVal >920 && snake.dir[0]==0){
  snake.dir[0] = 1;
  snake.dir[1] = 0;
 //Update
 if(timer > 1000/updateRate){
  timer = 0;
  Update();
 //Render
 Render();
float calculateDeltaTime(){
 float currentTime = millis();
 float dt = currentTime - oldTime;
 oldTime = currentTime;
 return dt;
void reset(){
for(int j=0;j<8;j++){
  pic[j] = 0;
void Update(){
 reset();//Reset (Clear) the 8x8 LED matrix
 int newHead[2] = {snake.head[0]+snake.dir[0], snake.head[1]+snake.dir[1]};
 //Handle Borders
 if(newHead[0]==8){
  newHead[0]=0;
 }else if(newHead[0]==-1){
  newHead[0] = 7;
 }else if(newHead[1]==8){
  newHead[1]=0;
```

```
}else if(newHead[1]==-1){
  newHead[1]=7;
//Check If The Snake hits itself
 for(j=0;j<snake.len;j++){
  if(snake.body[i][0] == newHead[0] && snake.body[i][1] == newHead[1]){
   //Pause the game for 1 sec then Reset it
    digitalWrite(buzzer,HIGH);
   delay(1000);
   digitalWrite(buzzer,LOW);
   snake = \{\{1,5\},\{\{0,5\},\{1,5\}\}\}, 2,\{1,0\}\};//Reinitialize the snake object
   apple = \{(int)random(0,8),(int)random(0,8)\};//Reinitialize an apple object
   return;
  }
}
//Check if The snake ate the apple
if(newHead[0] == apple.rPos && newHead[1] ==apple.cPos){
  snake.len = snake.len+1;
  apple.rPos = (int)random(0,8);
  apple.cPos = (int)random(0,8);
  digitalWrite(buzzer,1);
  delay(100);
  digitalWrite(buzzer,0);
  removeFirst();//Shifting the array to the left
snake.body[snake.len-1][0]= newHead[0];
 snake.body[snake.len-1][1]= newHead[1];
 snake.head[0] = newHead[0];
 snake.head[1] = newHead[1];
//Update the pic Array to Display(snake and apple)
for(j=0;j<snake.len;j++){
  pic[snake.body[j][0]] |= 128 >> snake.body[j][1];
pic[apple.rPos] |= 128 >> apple.cPos;
void Render(){
 for(i=0;i<8;i++)
  lc.setRow(0,i,pic[i]);
```

```
void removeFirst(){
  for(j=1;j<snake.len;j++){
    snake.body[j-1][0] = snake.body[j][0];
    snake.body[j-1][1] = snake.body[j][1];
  }
}</pre>
```

Robotix.io: https://linktr.ee/robotixio