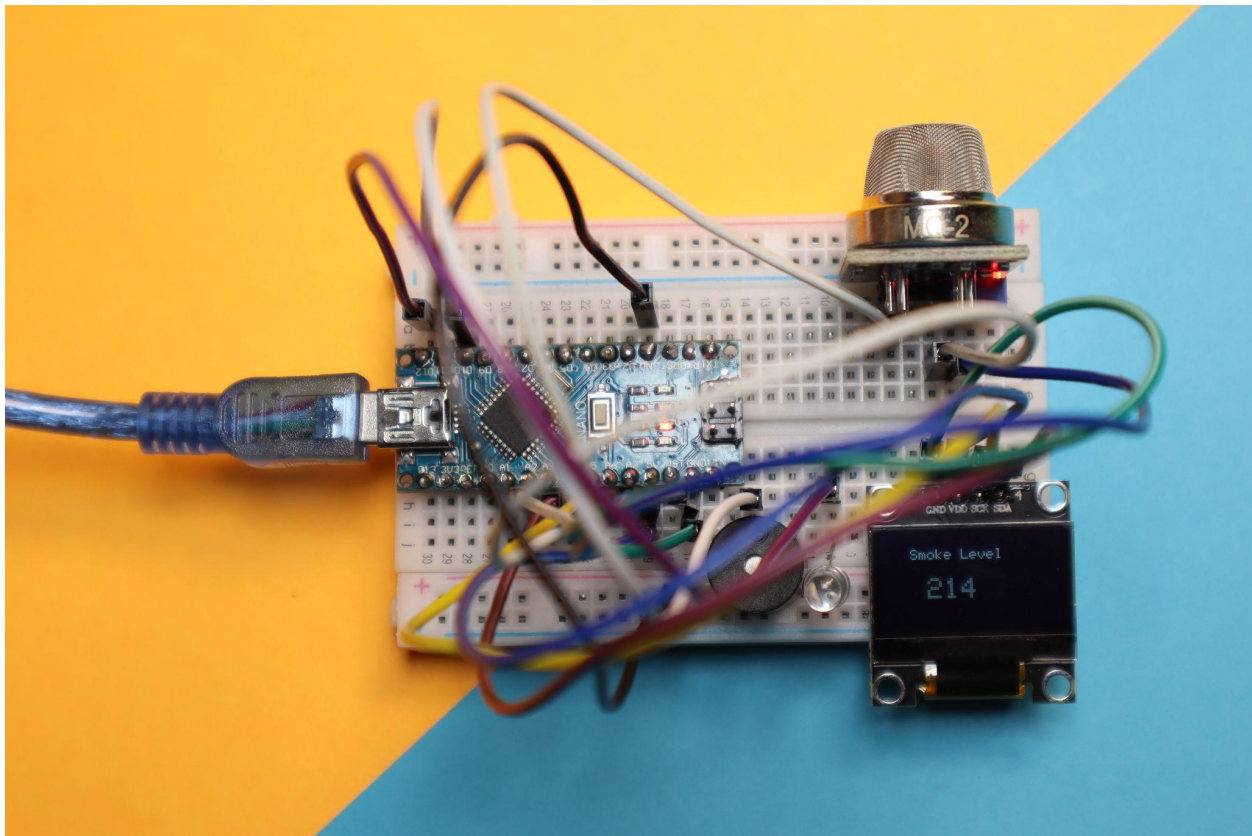


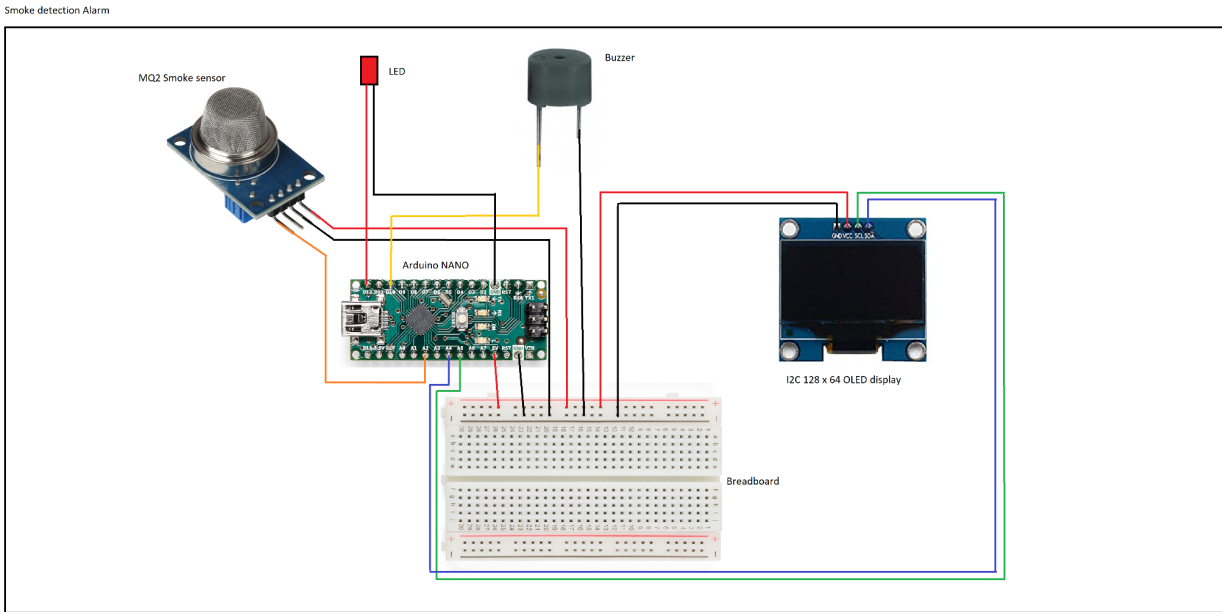
## Smoke Detection Alarm using Arduino Nano

### Material Required 🛒 :

S No.	Components	Link
1	Arduino Nano	<a href="https://amzn.to/3R5IQPT">https://amzn.to/3R5IQPT</a>
2	Breadboard Small	<a href="https://amzn.to/3QdsROy">https://amzn.to/3QdsROy</a>
3	I2C OLED display	<a href="https://amzn.to/3eg9Hdt">https://amzn.to/3eg9Hdt</a>
4	Buzzer	<a href="https://amzn.to/3rpQFos">https://amzn.to/3rpQFos</a>
5	LED	
6	Connecting Wires	<a href="https://amzn.to/3cl97EY">https://amzn.to/3cl97EY</a>
7	Arduino Nano Cable	<a href="https://amzn.to/3Cw7hRC">https://amzn.to/3Cw7hRC</a>
8	MQ2 Smoke sensor	<a href="https://amzn.to/3yeLlrU">https://amzn.to/3yeLlrU</a>



## Circuit Diagram ⚡ :



Robotix.io

## Code 💻 :

```
#include <Wire.h>
#include <Adafruit_GFX.h>
#include <Adafruit_SSD1306.h>

#define SCREEN_WIDTH 128 // OLED display width, in pixels
#define SCREEN_HEIGHT 64 // OLED display height, in pixels

// Declaration for an SSD1306 display connected to I2C (SDA, SCL pins)
Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &Wire, -1);

int redLed = 12;
int greenLed = 11;
int buzzer = 10;
int smokeA0 = A2;
// Your threshold value
int sensorThres = 250;
```

## Robotix.io

```
void setup() {

if(!display.begin(SSD1306_SWITCHCAPVCC, 0x3C)) { // Address 0x3D for 128x64
  Serial.println(F("SSD1306 allocation failed"));
  for(;;);
}
delay(2000);
display.clearDisplay();

pinMode(redLed, OUTPUT);
pinMode(greenLed, OUTPUT);
pinMode(buzzer, OUTPUT);
pinMode(smokeA0, INPUT);
Serial.begin(9600);
}

void loop() {
  display.clearDisplay();
  int analogSensor = analogRead(smokeA0);

  Serial.print("Pin A0: ");
  Serial.println(analogSensor);
  display.setTextSize(1);
  display.setTextColor(WHITE);
  display.setCursor(20, 10);
  // Display static text
  display.println("Smoke Level");
  display.setTextSize(2);
  display.setTextColor(WHITE);
  display.setCursor(32,30);
  display.print(analogSensor);
  display.display();

  // Checks if it has reached the threshold value
  if (analogSensor > sensorThres)
  {
    digitalWrite(redLed, HIGH);
    digitalWrite(greenLed, LOW);
    tone(buzzer, 800, 200);
  }
  else
  {

```

## Robotix.io

```
digitalWrite(redLed, LOW);  
digitalWrite(greenLed, HIGH);  
noTone(buzzer);  
}  
delay(100);  
}
```