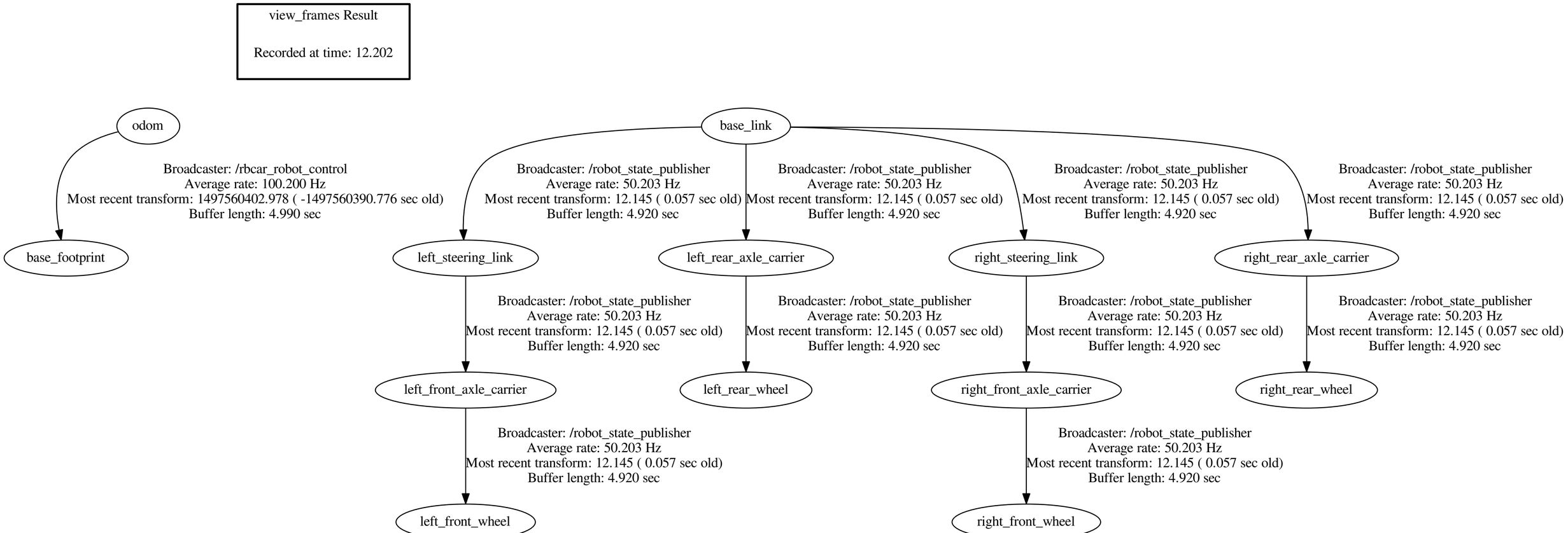
view_frames Result
Recorded at time: 12.202
odom
Broadcaster: /rbcar_robot_control
Average rate: 100.200 Hz
Most recent transform: 1497560402.978 (-1497560390.776 sec old)
Buffer length: 4.990 sec
base_footprint
base_link
Broadcaster: /robot_state_publisher
Average rate: 50.203 Hz
Most recent transform: 12.145 (0.057 sec old)
Buffer length: 4.920 sec
left_steering_link
left_rear_axle_carrier
right_steering_link
right_rear_axle_carrier
left_front_axle_carrier
left_rear_wheel
right_front_axle_carrier
right_rear_wheel
left_front_wheel
right_front_wheel