pysimCoder

Step-by-step Installation in Ubuntu

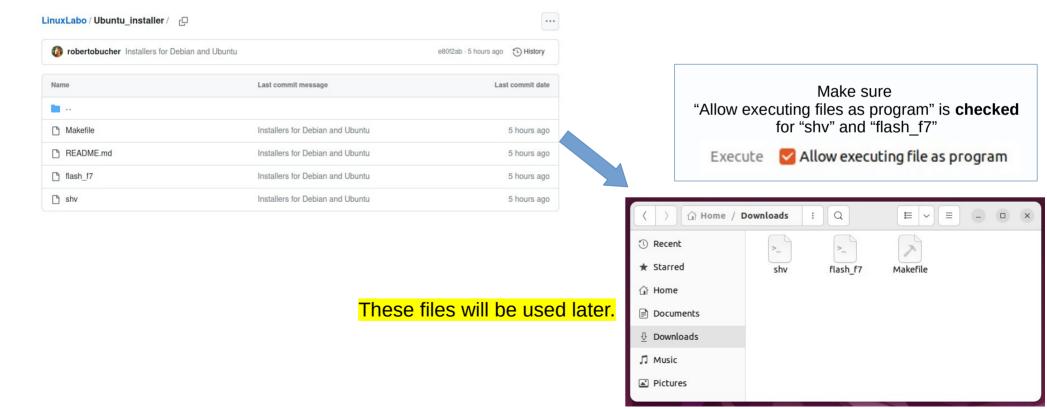
by

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Step 1: Download files from LinuxLabo

Link: https://github.com/robertobucher/LinuxLabo



Step 2: "Basic Installation"

- a) uname -r
- b) sudo su
- c) apt-get install linux-headers-6.5.0-41-generic
- d) apt-get install make

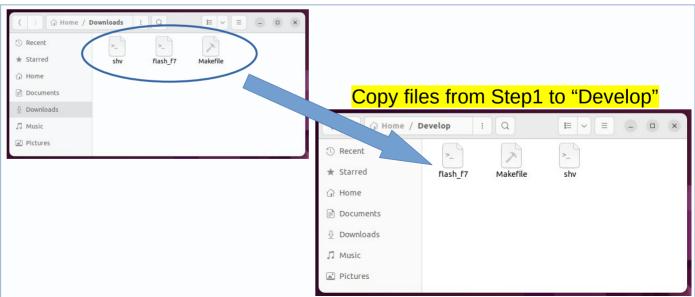
Step 2, part c:

```
emb@emb-iMac:~$ uname -r
6.5.0-41-generic
emb@emb-iMac:~$ sudo su
[sudo] password for emb:
root@emb-iMac:/home/emb# apt-get install linux-headers-6.5.0-41-generic
```

Step 3: "Additional files for Python and pysimCoder"

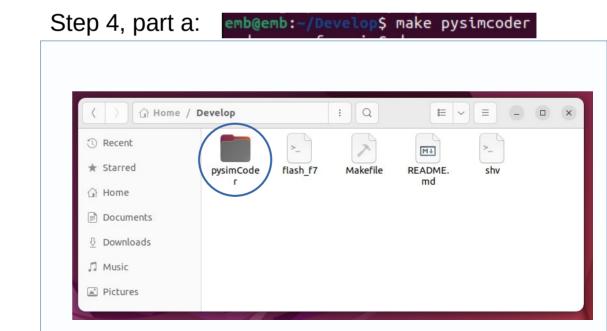
- a) mkdir Develop
- b) cd Develop
- c) Copy files to Develop
- d) make packages

Step 3, part c:



Step 4: "pysimCoder"

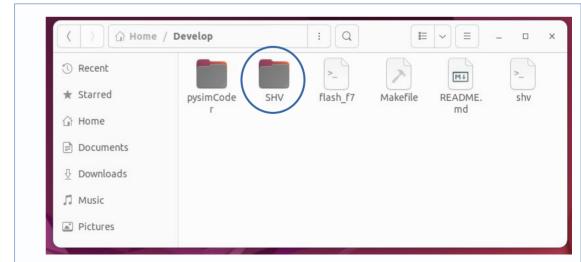
a) make pysimcoder



Step 5: "Install SHV"

- a) make Shv
- b) Start a new terminal as "normal user"
- c) cd pysimCoder/CodeGen/LinuxRT/devices
- d) make SHV=1

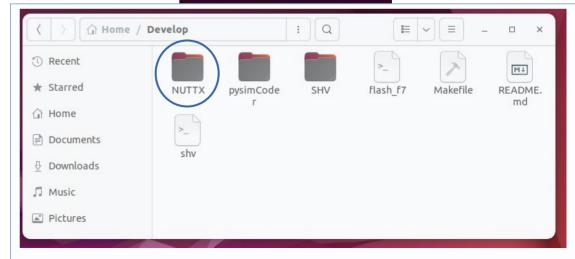
Step 5, part a: 2:~/Develop\$ make Shv



Step 6: "Install NuttX"

- a) make nuttx
- b) make f7
- c) Configure "make menuconfig" to match the target needs (next slides)

Step 6, part a: :~/Develop\$ make nuttx



Optional
Procedures
depending on
target needs.

```
emb@emb: ~/Develop/NUTTX/nuttx
                    NuttX/x86 64 Configuration
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty
submenus ----). Highlighted letters are hotkeys. Pressing <Y>
includes. <N> excludes. <M> modularizes features. Press <Esc> to
exit. <?> for Help. </> for Search. Legend: [*] built-in []
       License Setup --->
       Build Setup --->
       System Type --->
       Board Selection --->
       RTOS Features --->
       Device Drivers --->
       Networking Support --->
       Crypto API --->
       File Systems --->
       Graphics Support --->
     <Select>
                 < Exit >
                             < Help >
                                        < Save >
                                                    < Load >
```

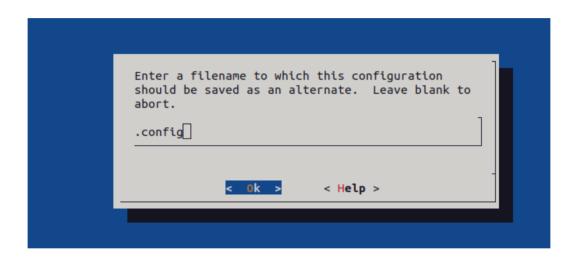
Go to "System Type", then "Timer Configuration"

Optional Procedures depending on target needs.

```
PWM low-level operations
[*] TIM1 PWM
     TIM1 Mode
    TIM1 Lock Level Configuration
    TIM1 t DTS Division
(10) TIM1 Initial Dead-time
     TIM1 Channel 1
     TIM1 Channel 1 Mode
     TIM1 Channel 1 Output
      TIM1 Channel 1 Complementary Output
     TIM1 Channel 2
     TIM1 Channel 2 Mode
     TIM1 Channel 2 Output
      TIM1 Channel 2 Complementary Output
     TIM1 Channel 3
     TIM1 Channel 4
     TIM1 Channel 5 (internal)
     TIM1 Channel 6 (internal)
   TIM2 PWM
 1 TIM3 PWM
1 TIM4 PWM
[*] PWM Multiple Output Channels
[ ] TIM PWM TRGO support
[ ] TIM1 ADC
[*] TIM2 ADC
     Select TIM2 ADC channel (TIM2 ADC channel 1) --->
[ ] TIM3 ADC
[ ] TIM4 ADC
(5000) ADC1 Sampling Frequency
(1) ADC1 Timer Trigger
[ ] TIM1 Capture
[ ] TIM2 Capture
[ ] TIM3 Capture
[ ] TIM4 Capture
   STM32 TIMx Outputs Configuration --->
```

```
PWM low-level operations
[*] TIM1 PWM
    TIM1 Mode
     TIM1 Lock Level Configuration
   TIM1 t DTS Division
(10) TIM1 Initial Dead-time
    TIM1 Channel 1
     TIM1 Channel 1 Mode
       TIM1 Channel 1 Output
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     TIM1 Channel 2 Mode
     TIM1 Channel 2 Output
       TIM1 Channel 2 Complementary Output
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     TIM1 Channel 4
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[ ] TIM4 ADC
(5000) ADC1 Sampling Frequency
(1) ADC1 Timer Trigger
[ ] TIM1 Capture
[ ] TIM2 Capture
[ ] TIM3 Capture
[ ] TIM4 Capture
   STM32 TIMx Outputs Configuration --->
```

Uncheck complementary outputs for TIM1



Save as .config and exit

- d) Start a new terminal as "normal user"
- e) cd pysimCoder/CodeGen/nuttx/devices
- f) make SHV=1

:~/Develop/pysimCoder/CodeGen/nuttx/devices\$ make SHV=1

Step 7: "Configure SHV Application"

- a) Set user and password in the shvspy window
- b) User: admin
- c) Password: admin!123

Step 8: "pyshv module"

a) pip install pyshv

Done, installation is complete!