



IEEE Robotics and Automation Letters Best Paper Award

*For the paper by Ruiqing Luo, Zhengtao Hu, Menghui Liu, Liang Du,
Sheng Bao, and Jianjun Yuan*

***"Adaptive Neural Computed Torque Control for
Robot Joints With Asymmetric Friction Model"***

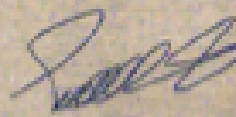
*IEEE Robotics and Automation Letters;
vol. 10, no. 1, pp. 732-739, Jan. 2025*



May 2025



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