Signals and systems lab sample codes:

NOTE: check for syntax/errors; do not replicate, try with your own logic of code

1. Calculation of Energy and power of signals

```
clc
x1 = @(t)(10*sin(10*pi*t));
f =@(x)exp(-2.*x);
x2 =@(t)((1+t).*(t>0 & t<2));
energy = integral(@(t)x1(t).^2,-pi,pi);

power = (integral(@(t)x1(t).^2,-pi,pi)/(2*pi));</pre>
```

2. Addition and multiplication of signals

```
응응
     multiplication and addition of signals
clc
t1 = linspace(-1, 5, 2000);
x1 = 0(t)(1.*(t>0 \& t<1) + 2.*(t>1 \& t<2) + (1.*(t>2 \& t<3)));
x2 = 0(t)((t).*(t>0 \& t<1)+(1.*(t>1 \& t<2))+((3-t).*(t>2 \& t<3)));
x3 = Q(t)(x1(t)+x2(t)); % addition of signals
x4 = Q(t)(x1(t).*x2(t)); % multiplication of signals
subplot(2,2,1);
plot(t1,x1(t1));
subplot(2,2,2);
plot(t1, x2(t1));
subplot(2,2,3);
plot(t1, x3(t1));
subplot(2,2,4);
plot(t1, x4(t1));
```

3. Sampling theorem verification

```
% y(t) = 1+4\cos(2000*pi*t) + \sin(1000*pi*t) is given to you & sampling it
using Nyquist criterion and reconstruct the original
                         % Number of Samples
t = linspace(-20, 20, 1000);
n=0:1000;
x1= @(t) ones(1, length(t));
x2 = @(t) 4*cos(2000*pi.*t);
x3 = @(t) sin(1000*pi.*t);
y= @(t) x1(t)+x2(t)+x3(t); % Total signal that has to be sampled
hold on
subplot(5,1,1);
plot(t, y(t));
title('Original Signal');
hold off
fm=1000; % Maximum frequency out of all the three signals.
% Case 1 : fs =2*fm (Nyquist Criterion)
fs1=2*fm;
ts1=1/fs1;
sample1=@(n) y(n.*(1/fs1));
```

```
subplot(5,1,2);
stem(n, sample1(n));
title('Sampled at fs =2*fm ');
hold off
% Case 2 : Sampling at fs>2*fm
fs2=6*fm;
sample2=@(n) y(n.*(1/fs2));
hold on
subplot(5,1,3);
stem(n, sample2(n));
title('Sampled at 6*fm');
hold off
% Case 3 : Sampling at fs< 2*fm
fs3=0.1*fm;
sample3=@(n) (y(n.*(1/fs3)));
hold on
subplot(5,1,4);
stem(n, sample3(n));
title('Sampled at 0.01*fm');
hold off
%Sample Reconstruction from Nquist Sampling Analysis
yrecnst=@(t)(0);
ynew = @(n) sample1(n).*(sinc(t-(n/fs1).*fs1));
for count=1:1000
    yrecnst= @(t) (yrecnst(t) + ynew(count));
end
hold on
subplot(5,1,5);
plot(t, yrecnst(t));
title('Reconstructed Signal y(t)');
hold off
   4. Obtaining Fourier series coefficients of given signal
Trigonometric Fourier series of a given signal
t=linspace(-5, 5, 101);
T=2;
                               %time period is 2 repeats after every 2sec
w0 = (2*pi)/T;
u t = @(t) (0*(t<0) + 1*(t>=0));
                                            % defining the func.
x t = Q(t) (u t(t+0.5) - u t(t-0.5));
y t = @(t) (x t(t).*((t >= -0.5) & (t <= 0.5)));
a o=(1/T) *integral(@(t)y t(t),0,2*pi);
```

hold on

sum = zeros(1,101);

f=@(t) y t(t).*cos(n*w0*t);

for n=1:200

```
a n= (2/T).*integral(@(t)f(t),0,2*pi); %writing fourier
coefficients
    g=0(t) y_t(t).*sin(n*w0*t);
    b n= (2/T).*integral(@(t)g(t),0,2*pi);
    sum = sum + a n .*cos(n*w0*t) + b n .*sin(n*w0*t);
    a n1=@(t) (2/T).*integral(@(t)f(t),0,2*pi);
    c n(n) = abs(a n);
    d n(n) = abs(b n);
    subplot(3,1,3)
    stem(c n);
    title('an');
    subplot(3,1,2)
    stem(d n);
    title('bn');
end
X = (a \circ) + sum;
subplot(3,1,1)
plot(X);
title('reconstructed signal');
```

5. Exponential Fourier series

Question 1:

```
clc
x = 0(t)((1-abs(t)/0.5).*(t>=-0.5 & t<=0.5)+0.*(t<=-0.5 & t>=0.5));
C = zeros(1,50);
f = zeros(1,50);
phase = zeros(1,50);
Cn = @(n) (integral(@(t)(x(t).*exp(-1j*n*t)),0,2*pi));
z = Cn(0);
for count = 1:500
    C(count) = abs(Cn(count));
    phase(count) = angle(Cn(count));
   f(count) = count*1;
    z = @(t)(z(t) + (Cn(count).*exp(1j*1*count*t)));
end
subplot(3,1,1);
stem(f,C);
title('Magnitude spectrum');
subplot(3,1,2);
stem(f,phase);
title('Phase spectrum');
```

Exponential Fourier series: Question 2

```
clc x = @(t)(1-abs(t)/0.5.*(abs(t) \le 0.5) + 0.*(abs(t) > 0.5)); C = zeros(1,50);
```

6. Discrete convolution of a given signals

```
n = -10:50;
x1 = (1).*(n>=0).*n + (0).*(n<0).*n;
x2 = (1).*(n>=0).*exp(3*n) + (0).*(n<0).*exp(3*n);
X = x1;
Y = x2;
z = zeros(1, length(X) + length(Y) - 1);
X = [X, zeros(1, length(Y) - 1)];
Y = [Y, zeros(1, length(X) - 1)];
z(1) = X(1) *Y(1);
for i = 2: (length(x1)+length(x2)-1)
    for j = 1:i
        z(i) = z(i) + X(j) *Y(i+1-j);
    end
end
subplot(3,1,1)
stem(x1)
subplot(3,1,2)
stem(x2)
subplot(3,1,3)
stem(z)
title('Convolution of discrete signals')
```

Also do discrete convolution of given discrete sequences, example, {-1, 2, 3, 4} and {2, 3, 4, 1}

7. Continuous convolution of given signals

```
t = linspace(-1,1,100);

x1 = @(t) 1.*exp(3.*t).*(t>=0);
subplot(2,2,1)
plot(x1(t))
title('x1(t)');

x2 = @(t) 1*t(t>=0);
subplot(2,2,2)
plot(x2(t))
```

```
title('x2(t)');
x3 = conv(x1(t), x2(t));
subplot(2,2,3)
plot(x3);
title('convolution using inbuilt function');
X = x1(t);
Y = x2(t);
z = zeros(1, length(X) + length(Y) - 1);
X = [X, zeros(1, length(Y) - 1)];
Y = [Y, zeros(1, length(X) - 1)];
z(1) = X(1) *Y(1);
for i = 2: (length(x1(t))+length(x2(t))-1)
    for j = 1:i
        z(i) = z(i) + X(j)*Y(i+1-j);
end
subplot(2,2,4)
plot(z)
title('convolution using definition')
```

- 8. Find the DFT X(k) of the given discrete time sequence $x(n) = \{-1, 3, 2, 1\}$ Perform IDFT to get back the given discrete Fourier series x(n).
- 9. Perform time scaling, shifting, amplitude scaling operation on given signal
- 10. Determine the *natural response* (zero input response, it is due to the initial values of output alone) of the system described by the given equation
- 11. Determine the forced response or zero state response (it is due to the given input with zero initial output, but initial values of the input should be considered) of the system described by the given equation
- 12. Perform N point FFT for the given discrete time sequence of length 4, {-1, 2, 3, 2}