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### Session - 18



This session deals with

Numpy

**Numpy Operations** 

Matrix and its operations

Linear algebra

System of equations



## Accessing Elements DATA SCIENCE



#### **Multi-Dimensional Arrays**

```
In [38]: a=arange(27).reshape(3,3,3)
         print(a)
         print(a[1:3,1;3,1;3])
             6
            [16 17]]
          [[22 23]
            [25 26]]]
```



## Attributes of numpy DATA SCIENCE



#### Various attributes are defined in numpy.

```
In [68]: a=array([[1,2,3],[4,5,6]])
         print(a.shape)
         print(a.strides)
         print(a.ndim)
         print(a.data)
         print(a.size)
         print(a.itemsize)
         print(a.nbytes)
         print(a.flags)
         (2, 3)
         (12, 4)
         <memory at 0x00000199D73F28B8>
         6
         4
         24
           C CONTIGUOUS : True
           F CONTIGUOUS : False
           OWNDATA : True
           WRITEABLE : True
           ALIGNED : True
           UPDATEIFCOPY : False
```

```
In [70]: a=array([[1,2,3],[4,5,6]])
    print(a.T)
    print(a.dtype)

[[1 4]
      [2 5]
      [3 6]]
    int32
```



## Arithmetic Operations DATA SCIENCE



```
In [109]:
         a=array([[1,2],[4,5]])
          b=array([[1,0],[0,1]])
          print(a)
          print(b)
          print("....a+b....")
          c=a+b
          print(c)
          print("....a-b....")
          c=a-b
          print(c)
          print("....a*b....")
          c=a*b
          print(c)
          FF1 21
          [4 5]]
          [[1 0]
          [0 1]]
          ....a+b.....
          [[2 2]
          [4 6]]
          .....a-b.....
          FFO 21
          [4 4]]
          .....a*b.....
          rra ol
           ro 511
```



## SONET Methods on numpy



```
In [92]:
          a=array([[0,2,3],[4,5,6]])
          print(a)
          print(a.sum())
          print(a.sum(1))
          print(a.sum(0))
          print(a.max())
          print(a.max(1))
          print(a.min())
          print(a.mean())
          print(a.var())
          print(a.all())
          print(a.anv())
          [[O 2 3]
            [4 5 6]]
          20
          [ 5 15]
          [4 7 9]
          65
          [3 6]
          \mathbf{O}
          3.33333333333
          3.88888888889
          False
          True
```



## SONET Methods on numpy



Various methods defined on numpy.

```
[56]:
              a=arange (9)
              b=a.reshape(3,3)
              print(b)
              [[0 1 2]
                [3 4 5]
                [6 7 8]]
In [97]:
         a=array([[1,2],[4,5]])
         b=array([[1,0],[0,1]])
         print(a)
         print(b)
          c=a.dot(b)
         print(c)
          [[1 \ 2]]
           [4 5]]
          [[1 0]
           [0 1]]
          [[1 2]
           [4 5]]
In [100]:
          a=array([30,12,23,54,5,36])
          print(a)
          print(sort(a))
          [30 12 23 54 5 36]
          [ 5 12 23 30 36 54]
```

```
In [107]: a=array([[0,2,3],[4,5,6]])
           print(a)
           print(a.tolist())
           print(a.transpose())
           [[0 2 3]
            [4 5 6]]
           [[0, 2, 3], [4, 5, 6]]
           [[0 4]
            [2 5]
            [3 6]]
```



### Strides



#### Number of bytes to be skipped to get next element

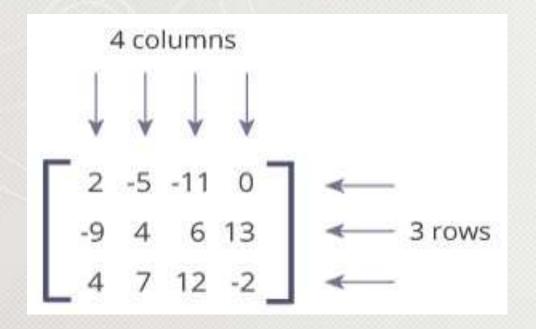
```
In [29]: a=arange(9)
      print(a)
      print(a.strides)
      [0 1 2 3 4 5 6 7 8]
      (4,)
              a=arange(9).reshape(3,3)
In [37]:
              print(a)
              print(a.dtype)
              print(a.strides)
                                                Total 12 bytes
                                             4 bytes each element
              int32
              (12, 4)
```



#### **Matrix**



A matrix is a two-dimensional data structure where numbers are arranged into rows and columns.



This matrix is a 3x4 (pronounced "three by four") matrix because it has 3 rows and 4 columns.



#### **Matrix**



A python matrix is a list of list with 3 rows and 4 columns.

```
import numpy as np
A = [[1, 4, 5, 12],
    [-5, 8, 9, 0],
    [-6, 7, 11, 19]]
m1=np.matrix(A)
print(m1)
```



## Accessing Elements DATA SCIENCE



A python matrix is a list of list with 3 rows and 4 columns.

```
import numpy as np
A = [[1, 4, 5, 12],
    [-5, 8, 9, 0],
    [-6, 7, 11, 19]
m1=np.matrix(A)
# first row
print("m1[0]=", m1[0])
# second row
print("m1[1] =", m1[1])
# Last row
print("m1[-1] =", m1[2])
```



## Accessing Elements DATA SCIENCE



A python matrix is a list of list with 3 rows and 4 columns.

```
import numpy as np
A = [[1, 4, 5, 12],
    [-5, 8, 9, 0],
    [-6, 7, 11, 19]]
m1=np.matrix(A)
print("m1[:,0] =",m1[:,0]) # First Column
print("m1[:,3] =", m1[:,3]) # Fourth Column
print("m1[:,-1] = ", m1[:,-1]) # Last Column (4th column in this case)
```

```
m1[:,0] = [[ 1]
 [-5]
 [-6]]
m1[:,3] = [[12]]
 [ 0]
 [19]]
m1[:,-1] = [[12]]
 [ 0]
 [19]]
```





It can perform addition, multiplication etc....

```
import numpy as np
A = np.matrix([[2, 4], [5, -6]])
B = np.matrix([[9, -3], [3, 6]])
C = A + B  # element wise addition
print(C)
```

```
[[11 1]
[ 8 0]]
```





#### Multiplication

```
import numpy as np
A = np.matrix([[2, 4], [5, -6]])
B = np.matrix([[9, -3], [3, 6]])
C = np.dot(A,B)
print(C)
```

```
[[ 30 18]
[ 27 -51]]
```





#### Transpose

```
import numpy as np
A = np.matrix([[2, 4], [5, -6]])
B = np.matrix([[9, -3], [3, 6]])
print(A.transpose())
```





Using numpy we can perform several matrix operations such as determinant, inverse, rank of matrix etc...

```
import numpy as np
A = np.matrix([[2, 4], [5, -6]])
print(np.linalg.det(A))
print(np.linalg.inv(A))
print(np.linalg.matrix_rank(A))
```



## Linear Algebra



More common problems in linear algebra is solving a matrix-vector equation.

Linear Algebra as one of the foundational blocks of Data Science.

Linear algebra is a sub-field of mathematics concerned with vectors, matrices, and linear transforms.



## Linear Algebra



$$A \mathbf{x} = \mathbf{b}$$

$$A = \begin{bmatrix} 2 & 1 & -2 \\ 3 & 0 & 1 \\ 1 & 1 & -1 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} -3 \\ 5 \\ -2 \end{bmatrix}$$

Will constructing the arrays for *A* and **b** for solving **x**.

To solve the system we do

$$x = np.linalg.solve(A,b)$$



## Why Linear Algebra



The use of linear algebra structures when working with data, such as tabular datasets and images.

Linear algebra concepts when working with data preparation, such as one hot encoding and dimensionality reduction.

The ingrained use of linear algebra notation and methods in sub-fields such as deep learning, natural language processing, and recommender systems.

In a multiple regression problem we seek a function that can map input data points to outcome values..

Each data point is a *feature vector*  $(x_1, x_2, ..., x_m)$  composed of two or more data values that capture various features of the input.

To represent all of the input data along with the vector of output values we set up a input matrix X and an output vector y:



$$X = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \cdots & x_{1,m} \\ 1 & x_{2,1} & x_{2,2} & \cdots & x_{2,m} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n,1} & x_{n,2} & \cdots & x_{n,m} \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

we can compute a predicted outcome value

$$\hat{\mathbf{y}} = \mathbf{x} \cdot \mathbf{\beta} = \beta_0 + \beta_1 \ x_1 + \beta_2 \ x_2 + \dots + \beta_m \ x_m$$



To compute the  $\beta$  vector as follows:

$$\beta = (X^T X)^{-1} X^T y$$

will use numpy to construct the appropriate matrices and vectors and solve for the \beta vector.

Once we have solved for \( \beta \) we will use it to make predictions for some test data points that we initially left out of our input data set.

constructed the input matrix X and the outcomes vector y in numpy, the following code will compute the β vector:

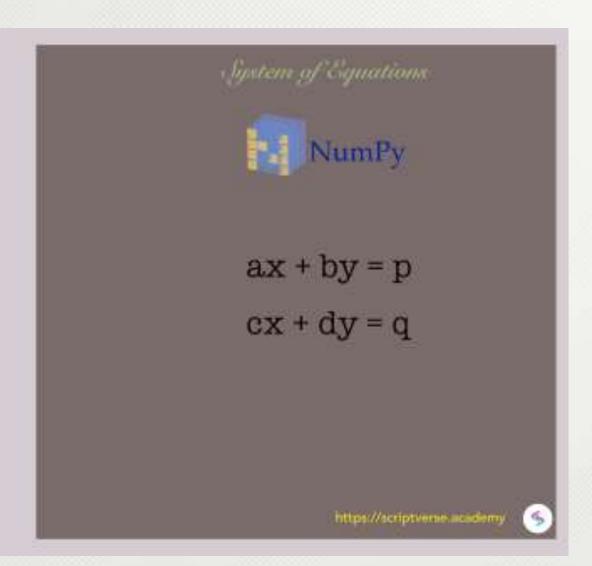
```
Xt = np.transpose(X)
XtX = np.dot(Xt,X)
Xty = np.dot(Xt,y)
beta = np.linalg.solve(XtX,Xty)
```



### **SONET Solving System equations**









## SONET Solving System equations DATA SCIENCE



$$3x + 7y = 27$$
$$5x + 2y = 16$$

This can be put in the matrix dot product form as

$$\left[ egin{array}{cc} 3 & 7 \ 5 & 2 \end{array} 
ight] \cdot \left[ egin{array}{c} x \ y \end{array} 
ight] = \left[ egin{array}{c} 27 \ 16 \end{array} 
ight]$$

If A represents the matrix of coefficients, x the column vector of variables and B the column vector of solutions, the above equation can be shortened to

$$Ax = B$$





```
import numpy as np
a = np.array([[3,7], [5,2]])
b = np.array([27,16])
x = np.linalg.solve(a, b)
print(x)
```

**Output** 

[2. 3.]





#### Conclusion

You are aware of

**Dictionary Data Structures** 

Numpy

We will proceed with

More on Numpy





