

The generation of the graph follows this main ideas:

- the generation is done concurrently by running MAX\_THREADS\_GRAPH number of threads
- at each iteration, each thread
  - $\circ$  reads x lines
  - o increment shared counter of read lines (see p\_curr\_iteration)
  - o allocates a single chunk of memory, big enough to store x Nodes (see node\_create\_multiple)
  - o parse those lines (e.g. find the node\_id of the current node and of its children)
  - $\circ$  save the address of each created Node at graph->nodes[<node\_id>] = p\_node;

repeat until end of file

• find the root nodes. In practice loops through the bitmap b\_incoming\_edge\_nodes in order to find nodes that do not have any incoming edges.

Node\_create\_multiple allocates and initialize x nodes at a time, having in mind to reduce the num of calls to malloc, which it is a slow operation.

Node\_add\_children is an ad-hoc parser, which fills the children array of a node with its children ids. It takes as input the address of a node and the string to parse.

## Interval Generation

- 1. Run *n* threads.
- 2. The i-th thread is tasked to generate the i-th interval
  - a. For each root node choosen randomly call "randomized\_label"

## Randomized\_label()

- 1. Return if the node has been already visited
- 2. Mark the node as visited
- 3. For each child of the node, call randomized label
- 4. Compute the label's left and right value
  - o Left value represents the smallest rank present in the subtree rooted at the current node
  - o Right value is the rank of the current node

## Query phase

- 1. Populate the struct "queries" from the file
- 2. Divide the queries in *n* blocks. Assign each block to a thread
- 3. For each query of its block, the i-th thread calls find\_path\_reachability:
  - a. If curr.source == dest the query is reachable, then return "query reachable"
  - b. Mark the curr.source as visited
  - c. For each child of the current source
    - i. If it has not been visited and the dest.labels[i-th] are contained in the curr.source node.labels[i-th]
      - 1. Calls find\_path\_reachability
  - d. The current source can't reach dest, then return "query non reachable"
- 4. Save the result in "queries->res"

