

CRICOS PROVIDER 00123M

Faculty of SET / School of Computer and Mathematical Sciences

COMP SCI 3007/7059/7659 Artificial Intelligence Exact Inference

adelaide.edu.au seek LIGHT



Exact Inference

AIMA C14.4

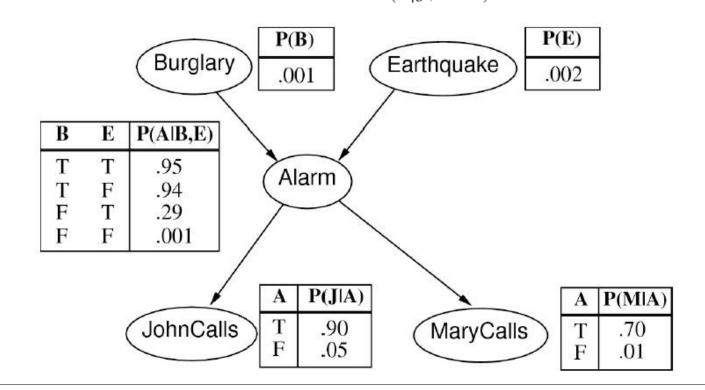
University of Adelaide

Outline

- Recap of Bayesian Networks
- Inference by enumeration
- Inference by variable elimination

Recap:Inference problem

I'm at work, neighbour John called to say my alarm is ringing, but neighbour Mary didn't call. Sometimes it's set off by minor earthquakes. Is there a burglar? $P(b|j, \neg m)$



Recap: Global semantic of Bayesian Networks

A Bayesian Network encodes our knowledge on how the variables interact. This is specified in terms of conditional independence assertions.

The global semantics of a network define a joint distribution of all variables as the product of local conditional distributions.

The joint distribution defined by a Bayesian Network with variables X_1, \ldots, X_n is:

$$P(X_1, ..., X_n) = P(X_1|Parents(X_1)) \times P(X_2|Parents(X_2)) \times ... \times P(X_n|Parents(X_n))$$

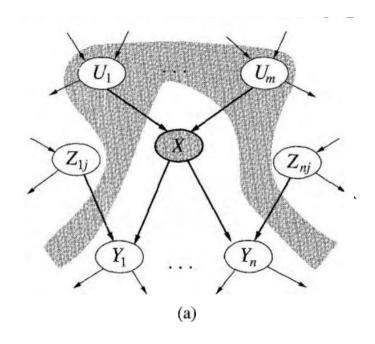
$$= \prod_{i=1}^{n} P(X_i|Parents(X_i))$$

where $Parents(X_i)$ are parents of X_i as specified by the particular Bayesian Network.

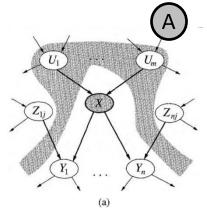
Local Semantics

Conditional independence assumptions can simply be "read off" the network topology.

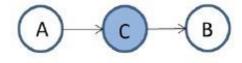
Local semantics: each node is conditionally independent of its nondescendants given its parents.



Case 2, Chain (Head-to-Tail)



Observed



$$P(A, B|C) = P(A, B, C)/P(C)$$

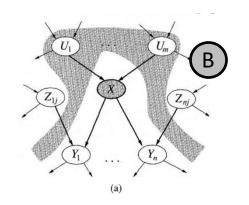
$$= P(B|C)P(C|A)P(A)/P(C)$$

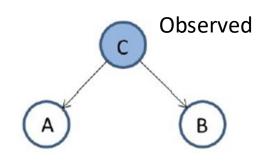
$$= P(B|C)P(A|C)$$

A and B are conditionally independent given C:

$$A \perp \!\!\!\perp B | C$$

Case 1, Fork (Tail-to-Tail)





$$P(A, B|C) = P(A, B, C)/P(C)$$

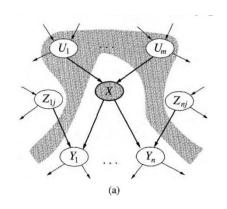
$$= P(A|C)P(B|C)P(C)/P(C)$$

$$= P(A|C)P(B|C)$$

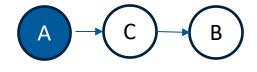
A and B are conditionally independent given C

 $A \perp \!\!\! \perp B|C$

Case 2.5, Chain (Head-to-Tail)



Observed



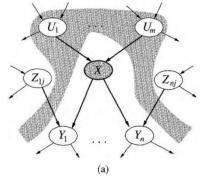
$$P(C,B|A) = P(A,B,C)/P(A)$$
$$= P(B|C)P(C|A)P(A)/P(A)$$
$$= P(B|C)P(C|A)$$

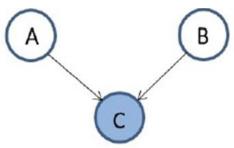
C and B are not conditionally independent given A

CAIB | A

Case 3, Inverted Fork

(Head-to-Head, Collider, or V-structure)





Not observed

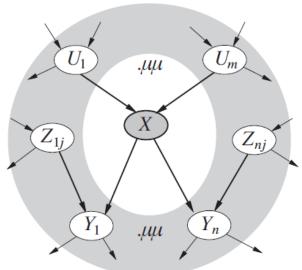
$$P(A, B, C) = P(A)P(B)P(C|A, B)$$

$$P(A,B) = \sum_{C} P(A)P(B)P(C|A,B) = P(A)P(B)$$

so $A \perp \!\!\! \perp B$

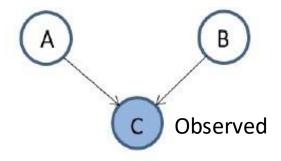
Markov blanket

A more specific way to state the local semantics: A node is conditionally independent of all others given its parents, children, and children's <u>other</u> parents -- i.e., given the Markov blanket of the node.



Why do we need to consider the children's parents?

Case 3, Inverted Fork (Head-to-Head)



$$P(A,B|C) = P(A,B,C)/P(C)$$
$$= P(C|A,B)P(A)P(B)/P(C)$$

so $A \not\perp \!\!\! \perp B|C$

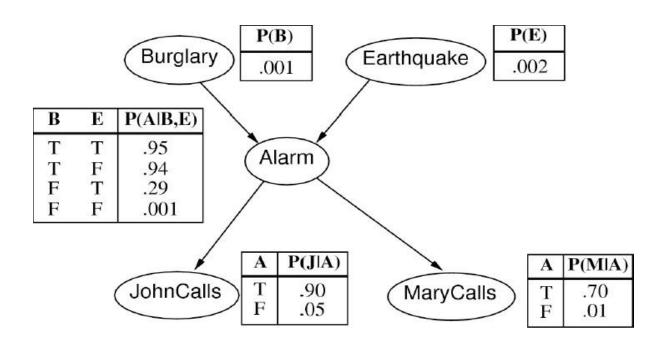
Recap: Inference

Recall the general rule of statistical inference:

$$P(X|e) = \alpha \sum_{\forall Y} P(X, e, Y)$$

where X is the query variable, e the observed values for the evidence variables, and Y the unobserved variables. As usual α is a normalisation constant that we solve for at the end.

Performing inference



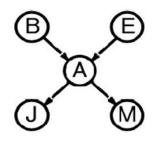
$$P(B, E, A, J, M)? \qquad P(b|j, \neg m)?$$

$$P(J, M, A, B, E) = P(J|A)P(M|A)P(A|B, E)P(B)P(E)$$

Performing inference on Bayesian Networks

A direct application of the general rule yields

$$P(b|j, \neg m) = \alpha \sum_{E} \sum_{A} P(b, j, \neg m, E, A)$$



Observe that the summands are joint probabilities of all the variables. Hence, we introduce the global semantics of the network:

$$P(b|j, \neg m) = \alpha \sum_{E} \sum_{A} P(b)P(E)P(A|b, E)P(j|A)P(\neg m|A)$$

Inference by enumeration

Expanding by enumerating the summands we obtain

$$\begin{array}{lcl} P(b|j, \neg m) & = & \alpha \sum_E \sum_A P(b) P(E) P(A|b, E) P(j|A) P(\neg m|A) \\ \\ & = & \alpha \left[P(b) P(e) P(a|b, e) P(j|a) P(\neg m|a) \\ \\ & + P(b) P(e) P(\neg a|b, e) P(j|\neg a) P(\neg m|\neg a) \\ \\ & + P(b) P(\neg e) P(a|b, \neg e) P(j|a) P(\neg m|a) \\ \\ & + P(b) P(\neg e) P(\neg a|b, \neg e) P(j|\neg a) P(\neg m|\neg a) \right] \quad \neg \text{e, -a} \end{array}$$

For each of the components on the RHS, we read its value from the appropriate CPT, yielding $P(b|j, \neg m) = \alpha 0.00025677$.

Note that the result does not yet amount to a probability value as we haven't solved for α .

Inference by enumeration

Calculate the scaling factor

To compute $\alpha = \frac{1}{P(j, \neg m)}$ we obtain the marginal probability

$$P(j, \neg m) = \sum_{B} \sum_{E} \sum_{A} P(B, E, A, j, \neg m)$$

Inference by enumeration

An alternative is to realise that $\langle P(b|j, \neg m), P(\neg b|j, \neg m) \rangle$ is a probability distribution and that α is a normalisation constant that ensures that the probability distribution sums to 1.

Hence, compute $P(\neg b|j, \neg m) = \alpha 0.0498$, using the global semantics and enumerating the summands as before, yielding

$$\langle P(b|j, \neg m), P(\neg b|j, \neg m) \rangle = \alpha \langle 0.00025677, 0.0498 \rangle = \langle 0.0051, 0.9949 \rangle$$

where α is solved as $\frac{1}{0.00025677+0.0498}$.

Complexity of inference by enumeration

In the burglar-alarm example, we evaluate the expression

$$\begin{split} P(b|j,\neg m) &= \alpha \sum_E \sum_A P(b)P(E)P(A|b,E)P(j|A)P(\neg m|A) \\ &= \alpha \left[P(b)P(e)P(a|b,e)P(j|a)P(\neg m|a) \right. \\ &+ P(b)P(e)P(\neg a|b,e)P(j|\neg a)P(\neg m|\neg a) \\ &+ P(b)P(\neg e)P(a|b,\neg e)P(j|a)P(\neg m|a) \\ &+ P(b)P(\neg e)P(\neg a|b,\neg e)P(j|\neg a)P(\neg m|\neg a) \right] \end{split}$$

by adding up 4 terms, each obtained by multiplying 5 numbers—In total we need 16 multiplications and 3 additions (excludes the contribution due to term α).

Complexity of inference by enumeration

In the burglar-alarm example, we evaluate the expression

$$P(b|j, \neg m) = \alpha \sum_{E} \sum_{A} P(b)P(E)P(A|b, E)P(j|A)P(\neg m|A)$$

In the worst case, where we have to sum out almost all of the n variables (where we assume they are all Boolean), the complexity of inference by enumeration is $\mathcal{O}(n2^n)$.

This means we will not be able to perform inference by enumeration except for the smallest networks!

Depth-first Evaluation

An improvement can be achieved by observing that P(b) is a constant that can be moved outside the summations over E and A, while P(e) can be moved outside the summation over A:

$$P(b|j,\neg m) = \alpha P(b) \sum_{E} P(E) \sum_{A} P(A|b,E) P(j|A) P(\neg m|A)$$

Thus we evaluate by looping through the variables in order, multiplying CPT entries as we go.

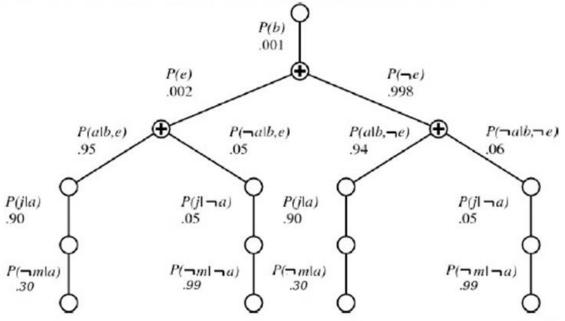
Now evaluating the expression involves 11 multiplications and 3 additions (again excluding the contribution due to term α).

$$= \alpha P(b) \sum_{E} P(E) [P(a|b,E)P(j|a)P(\neg m|a) + P(\neg a|b,E)P(j|\neg a)P(\neg m|\neg a)]$$

Depth-first Evaluation

$$P(b|j,\neg m) = \alpha P(b) \sum_{E} P(E) \sum_{A} P(A|b,E) P(j|A) P(\neg m|A)$$

The process can be illustrated as an evaluation tree.



The evaluation proceeds top-down, multiplying values along each path and summing at the "+" nodes

Complexity of Depth-first Evaluation

$$P(b|j,\neg m) = \alpha \sum_{E} \sum_{A} P(b)P(E)P(A|b,E)P(j|A)P(\neg m|A)$$

$$= \alpha \left[P(b)P(e)P(a|b,e)P(j|a)P(\neg m|a) + P(b)P(e)P(\neg a|b,e)P(j|\neg a)P(\neg m|\neg a) + P(b)P(\neg e)P(a|b,\neg e)P(j|a)P(\neg m|a) + P(b)P(\neg e)P(\neg a|b,\neg e)P(j|\neg a)P(\neg m|\neg a)\right]$$

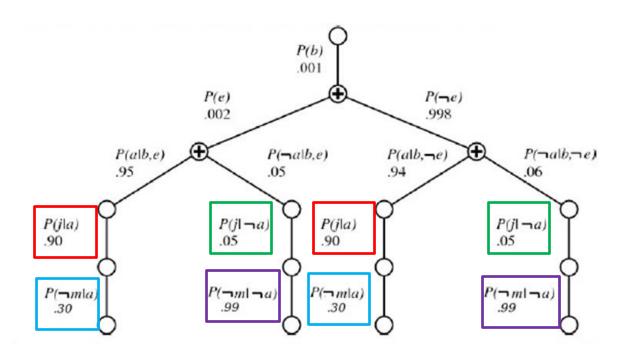
$$O(n 2^n)$$

$$P(b|j, \neg m) = \alpha P(b) \sum_{E} P(E) \sum_{A} P(A|b, E) P(j|A) P(\neg m|A)$$

$$O(2^{n})$$

Problem of Depth-First Evaluation

$$P(b|j, \neg m) = \alpha P(b) \sum_{E} P(E) \sum_{A} P(A|b, E) P(j|A) P(\neg m|A)$$



Repeat computation!

Problem with DF evaluation

We need to do this sum both for E = true and E = false. For the first case:

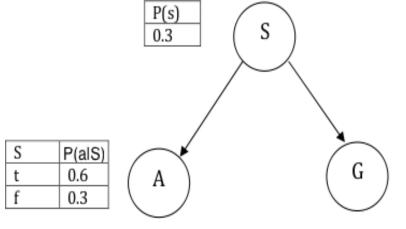
$$P(e) \left(\begin{array}{c} P(b) \left(P(a|b,e) P(j|a) P(m|a) + P(\neg a|b,e) P(j|\neg a) P(m|\neg a) \right) + \\ P(\neg b) \left(P(a|\neg b,e) P(j|a) P(m|a) + P(\neg a|\neg b,e) P(j\neg a) P(m|\neg a) \right) \end{array} \right)$$

Repeat computation!

Recursively eliminate variables and merge terms into factors

Store factors to avoid repeating computations

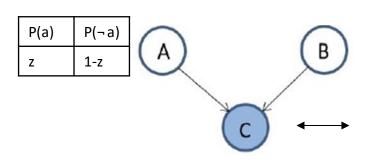
Variable Elimination (Fork)



S	P(gIS)	P(¬ g S)
t	0.7	0.3
f	0.2	0.8

$$\begin{split} P(A) &= \sum_{S} \sum_{G} P(A,S,G) \\ &= \sum_{S} \sum_{G} P(S)P(A|S)P(G|S) \\ &= \sum_{S} \left(P(S)P(A|S) \sum_{G} P(G|S) \right) \\ &= \sum_{S} \left(P(S)P(A|S) \sum_{G} P(G|S) \right) \\ &= \sum_{S} P(S)P(A|S) \end{split}$$

Variable Elimination (Inverted Fork)



Α	В	P(c)	P(¬c)
t	t	х	1-x
t	f	У	1-y
f	t	m	1-m
f	f	n	1-n

$$f1(B,C) = z*((B==t)*(C==c)*x + (B==t)*(C==-c)*(1-x) + (B==f)*(C==c)*y + (B==f)*(C==-c)*(1-y)) + (1-z)*(...)$$

$$P(C) = \sum_{A} \sum_{B} P(A, B, C)$$

$$= \sum_{A} \sum_{B} P(A)P(B)P(C|A, B)$$

$$= \sum_{B} P(B) \sum_{A} P(A)P(C|A, B)$$

	В	С	f1(B, C)
	t	С	z*x+(1-z)*m
	t	¬ C	z*(1-x)+ (1-z)*(1-m)
2)	f	С	z*y+(1-z)*n
)	f	¬ С	z*(1-y)+ (1-z)*(1-n)
Elimin	ate A	F1(E	3,C) is a factor

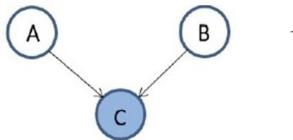
 $= \sum_{B} P(B) f_1(B, C)$

 $=f_2(C)$

Eliminate B

Variable Elimination-Factor

- A factor associates a real value to each setting of its arguments.
- Factors in Bayesian Networks correspond to conditional probability distributions.
- The joint distribution is a product of factors.



$$P(A, B, C) = P(A)P(B)P(C|A, B)$$

Variable Elimination -Factor Operation

• Let X, Y and Z are three random variables, and $\phi_1(X,Y)$ and $\phi_2(Y,Z)$ are two factors, their product is a new factor:

$$\psi(X, Y, Z) = \phi_1(X, Y)\phi_2(Y, Z)$$

X Y Z

si as in si-fi

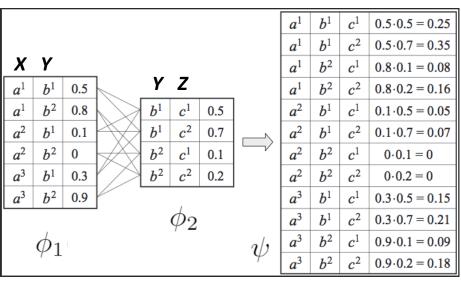
fi as in si-fi

An Example:

$$\phi_1$$
 has $3*2 = 6$ entries

 ϕ_2 has 2*2 = 4 entries yields:

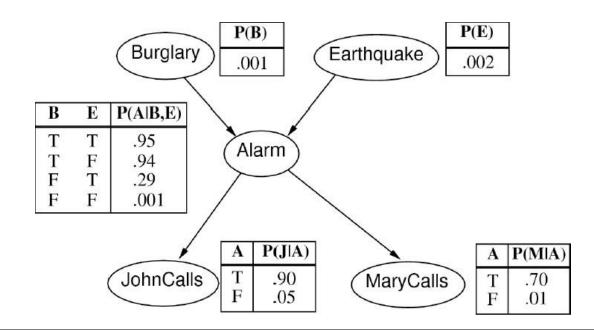
 ψ has 3*2*2 = 12 entries



$$P(E|j,m) = \alpha P(E,j,m)$$

$$= \alpha \underbrace{P(E)}_{E} \underbrace{\sum_{b} P(b)}_{B} \underbrace{\sum_{a} P(a|b,E)}_{A} \underbrace{P(j|a)}_{J} \underbrace{P(m|a)}_{M}$$

$$f_{E}(E) \quad f_{B}(B) \quad f_{A}(A,B,E) \quad f_{J}(A) \quad f_{M}(A)$$



Α	J	f _J (A)
Т	Т	0.9
Т	F	0.1
F	Т	0.05
F	F	0.95

$$P(E|j,m) = \alpha P(E,j,m)$$

$$= \alpha \underbrace{P(E)}_{E} \underbrace{\sum_{b} \underbrace{P(b)}_{B} \sum_{a} \underbrace{P(a|b,E)}_{A} \underbrace{P(j|a)}_{J} \underbrace{P(m|a)}_{M}}_{J}$$

$$f_{E}(E) \quad f_{B}(B) \quad f_{A}(A,B,E) \quad f_{J}(A) \quad f_{M}(A)$$

А	М	f _M (A)
Т	Т	0.7
Т	F	0.3
F	Т	0.01
F	F	0.99

E	$f_E(E)$
T	.002
F	.998

В	$f_B(B)$
T	.001
F	.999

A	В	\mathbf{E}	$f_A(A,B,E)$
T	T	T	.95
T	T	F	.94
T	F	T	.29
T	F	F	.001
F	T	T	.05
F	T	F	.06
F	F	T	.71
F	F	F	.999

A	$f_J(A)$
T	.9
F	.05

A	$f_M(A)$
T	.7
F	.01

$$\begin{split} P(E|j,m) &= \alpha P(E,j,m) \\ &= \alpha P(E) \sum_b P(b) \sum_a P(a|b,E) P(j|a) P(m|a) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_J(A) f_M(A) \quad \text{factorize} \end{split}$$

$$\mathbf{P}(E \mid j, m) = \alpha \mathbf{f}_E(E) \times \sum_b (\mathbf{f}_B(B) \times \sum_a (\mathbf{f}_A(A, B, E) \times \mathbf{f}_J(A) \times \mathbf{f}_M(A)))$$

0.9

0.1

0.05

0.95

F

F

F

F

Т

F

Т

F

Т

F

F

0.7

0.3

0.01

0.99

$$\begin{split} P(E|j,m) &= \alpha P(E,j,m) \\ &= \alpha P(E) \sum_b P(b) \sum_a P(a|b,E) P(j|a) P(m|a) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_J(A) f_M(A) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_{JM}(A) \end{split} \qquad \text{factorize} \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_{JM}(A) \\ &= \alpha f_B(E) \sum_b f_B(B) \sum_a f_A(B,E) f_{JM}(A) \\ &= \alpha f_B(E) \sum_b f_B(B) \sum_a f_A(B,E) f_{JM}(A) \\ &= \alpha f_B(E) \sum_b f_{JM}(A) \\ &= \alpha f_B(E) \sum_b$$

$$\begin{split} P(E|j,m) &= \alpha P(E,j,m) \\ &= \alpha P(E) \sum_b P(b) \sum_a P(a|b,E) P(j|a) P(m|a) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_J(A) f_M(A) \quad \text{factorize} \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_{JM}(A) \quad \text{factor product} \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_{AJM}(A,B,E) \quad \text{factor product} \end{split}$$

A	В	E	$f_A(A,B,E)$
T	Т	T	.95
T	T	F	.94
T	F	T	.29
Τ	F	F	.001
F	Т	T	.05
F	Т	F	.06
F	F	T	.71
F	F	F	.999

A	$f_{JM}(A)$
T	.63
F	.0005

A	В	Е	$f_{AJM}(A, B, E)$
T	T	Т	.95 * .63
\mathbf{T}	T	F	.94 * .63
T	F	Т	.29 * .63
T	F	F	.001 * .63
F	T	T	.05 * .0005
F	Т	F	.06 * .0005
F	F	T	.71 * .0005
F	F	F	.999 * .0005

$$f_{AJM}(A, B, E) = f_A(A, B, E) f_{JM}(A)$$

T

.29 * .63 .001 * .63

.05 * .0005

.06 * .0005 .71 * .0005

.999 * .0005

F

$$\begin{split} P(E|j,m) &= \alpha P(E,j,m) \\ &= \alpha P(E) \sum_b P(b) \sum_a P(a|b,E) P(j|a) P(m|a) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_J(A) f_M(A) \quad \text{factorize} \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_{JM}(A) \quad \text{factor product} \\ &= \alpha f_E(E) \sum_b f_B(B) \underbrace{\sum_a f_{AJM}(A,B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{f_{\bar{A}JM}(B,E)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{\beta f_B(B)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{\beta f_B(B)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{\beta f_B(B)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{\beta f_B(B)}_{\text{factor marginalization, and eliminate A}} \\ &= \underbrace{\alpha f_E(E) \sum_b f_B(B) \underbrace{\alpha f_B(B)}_{\text$$

.94 * .63

.001 * .63 +

 $f_{\bar{A}JM}(B,E) = \sum f_{AJM}(A,B,E)$

.06 * .0005

.71*.0005

999 * .0005 = .001129

= .5922

.1830

$$\begin{split} P(E|j,m) &= \alpha P(E,j,m) \\ &= \alpha P(E) \sum_b P(b) \sum_a P(a|b,E) P(j|a) P(m|a) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_J(A) f_M(A) \quad \text{factorize} \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_A(A,B,E) f_{JM}(A) \\ &= \alpha f_E(E) \sum_b f_B(B) \sum_a f_{AJM}(A,B,E) \\ &= \alpha f_E(E) \sum_b f_B(B) f_{\bar{A}JM}(B,E) \quad \text{Eliminate A} \\ &= \alpha f_E(E) \sum_b f_{B\bar{A}JM}(B,E) \\ &= \alpha f_E(E) f_{\bar{B}\bar{A}JM}(E) \quad \text{Eliminate B} \\ &= \alpha f_{E\bar{B}\bar{A}JM}(E) \end{split}$$

The process of evaluation is a process of summing out variables (right to left) from pointwise products of factors to produce new factors, eventually yielding a factor that is the solution, i.e., the posterior distribution over the query variable.

It is bottom-up in the evaluation tree.

- Recursively eliminate variables and merge terms into factors
- Store factors to avoid repeating computations

Tree-structured (Polytree)

- Complexity for Bayesian networks that are <u>single-connected</u> and with n <u>Boolean variables</u> are
 - linear to the size (number of CPT entries) of the network

2^k CPT entries, assuming maximum k parents

O(n2k) CPT entries

Also useful for doing inference multiple times

e.g.

$$P(B|J, M) = \alpha P(B, J, M)$$
$$P(B|J) = \alpha P(B, J)$$
$$P(B|M) = \alpha P(B, M)$$

$$\begin{split} P(B|J,M) &= \alpha P(B,J,M) \\ &= \sum_{a} \sum_{e} P(B)P(e)P(a|B,e)P(J|A)P(M|a) \\ &= \alpha P(B) \sum_{e} P(e) \sum_{a} P(a|B,e)P(J|a)P(M|a) \\ &= \alpha P(B)f(J,M) \end{split}$$

J	М	F(J,M)
Т	Т	
F	F	

We only need to calculate f once

$$P(B|J) = \alpha P(B, J)$$

$$= \sum_{m} \sum_{a} \sum_{e} P(B)P(e)P(a|B, e)P(J|A)P(m|a)$$

$$= \alpha P(B) \sum_{m} \sum_{e} P(e) \sum_{a} P(a|B, e)P(J|a)P(m|a)$$

$$= \alpha P(B) \sum_{m} f(J, m)$$

$$P(B|M) = \alpha P(B, M)$$

$$= \sum_{j} \sum_{a} \sum_{e} P(B)P(e)P(a|B, e)P(j|A)P(M|a)$$

$$= \alpha P(B) \sum_{j} \sum_{e} P(e) \sum_{a} P(a|B, e)P(j|a)P(M|a)$$

$$= \alpha P(B) \sum_{j} f(j, M)$$