

南方科技大学优秀本科毕业生申请表

姓名	赵锦秋		学号	12110430		性别	男		
民族	汉族		政治面貌	中国共产党党员		书院	致新书院		
学院	工学院		院系	生物医学工程系		专业	智能医学工程		
总GPA	3.64		专业排名	9 / 18		书院导师	杨招军		
学院导师	张明明		辅导员	付林浩		学生电话	15029502924		
称号类型	<input checked="" type="checkbox"/> 优秀毕业生 (书院通道) <input type="checkbox"/> 十佳毕业生 (书院通道) <input checked="" type="checkbox"/> 优秀毕业生 (学院通道) <input type="checkbox"/> 十佳毕业生 (学院通道) <input type="checkbox"/> 郭谢碧蓉奖学金 (书院通道) <input type="checkbox"/> 郭谢碧蓉奖学金 (学院通道)								
个人宣传口号	(如果勾选“十佳毕业生”则需要填写此项)								
申请类型	□ 就业创业类		去向单位						
			岗位						
	□ 升学类		去向学校	新加坡国立大学					
			去向专业	机器人					
			培养层次	<input checked="" type="checkbox"/> 硕士	<input type="checkbox"/> 博士				
			奖学金情况	<input type="checkbox"/> 全奖	<input type="checkbox"/> 半奖				
				<input checked="" type="checkbox"/> 其他 无					
在校期间所获荣誉	获奖年度	获奖名称				颁奖单位			
	2023-12	南方科技大学优秀学生干部				南方科技大学			
	2024-12	南方科技大学优秀学生				南方科技大学			
	2023-11	南方科技大学 实践之星				南方科技大学			
	2024-11	南方科技大学校级优秀学生奖学金一等奖				南方科技大学			
	2023-10	南方科技大学校级优秀学生奖学金三等奖				南方科技大学			
	2023-10	南方科技大学致新书院 致新之星				南方科技大学致新书院			
主要事迹	事迹类别	年度				事迹描述			
	学业科研	2024-07				M2vip会议论文			
	学业科研	2023-12				igem银奖			
	学业科研	2023-10				南方科技大学生物医学工程系学术交流日优秀奖			
	社会实践	2023-10				南方科技大学暑期社会实践团体优秀奖			
	社会实践	2023-10				南方科技大学暑期社会实践优秀个人			
	学生工作	2023-09				致新书院实践部部长			
	学业科研	2024-07				全国生医大赛二等奖			
	学业科研	2023-12				梧桐树"校园创业之星大赛优秀奖			
	社会实践	2023-03				南方科技大学寒假社会实践团体二等奖			
	文体艺术	2023-10				南方科技大学极限飞盘大赛二等奖			
	学生工作	2024-09				致新书院2104班优秀班委			
本人承诺以上所填信息真实、准确，并同意授权学校对所填资料进行查询、核对。如虚报资料，本人愿意承担相关责任。									
本人签名：  填表日期： 2025-04-25 22:37									



扫描全能王 创建

导师/辅导员意见：

同意

签名：

JbomJzr

院系/书院负责人意见：

签名：

备注：

1.符合评选条件的本科生填写报名表，通过学院报名的请导师和院系负责人签署意见，通过书院报名的请辅导员和书院负责人签署意见。2.申请人需提交科研成果、社会活动成果、文体艺术创作成果以及所获荣誉的佐证材料，学术论文的佐证材料为论文首页。所有佐证材料（提交后不予退回）上传到【附件】。

✓



扫描全能王 创建

Enhancing Movement Directions Decoding in EEG-BCI through Force Feedback

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Abstract—In advancing brain-computer interface (BCI), force feedback has demonstrated potential in enhancing neurophysiological interactions during motor tasks. This study investigated the impact of force feedback on brain activity and the accuracy of decoding movement direction. We developed an electroencephalogram (EEG)-based BCI paradigm with four levels of force feedback (i.e., 0 N, 8 N, 16 N, 24 N) applied during right-hand movements to left and right directions. Six participants were involved to ensure robust results. Three deep learning models—DeepConvNet, ShallowConvNet, and EEGNet—were used to decode movement directions. Findings from event-related desynchronization/event-related synchronization (ERD/ERS) and movement-related cortical potentials (MRCPs) indicated that increased force feedback significantly enhanced the brain's response to motor stimuli. The decoding results revealed that force feedback notably improved decoding accuracy of DeepConvNet and EEGNet, particularly under medium and high-intensity conditions. Specifically, three models demonstrated accuracy improvements of 11%, 4%, and 12% under high-intensity force feedback, respectively. These results suggest that specific force feedback enhances motor area responsiveness, improving movement intention decoding in BCI. Our study confirms the positive impact of force feedback on BCI performance, highlighting the potential of force feedback-based BCI systems.

Index Terms—Brain-computer interface (BCI); electroencephalogram (EEG); force feedback; movement direction decoding

I. INTRODUCTION

Electroencephalography (EEG) is a non-invasive electrophysiological monitoring method that records spontaneous electrical brain activity over a specific duration through electrodes positioned on the scalp [1]. Nowadays, EEG technology has become a pivotal tool in neuroscience,

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widely used in various domains such as diagnosing brain disorders like epilepsy, cognitive neuroscience, biometrics, and brain-computer interfaces (BCI) [2,3]. The non-invasive nature and excellent temporal resolution of EEG make it an ideal choice for monitoring brain activity during motor tasks. Extensive research indicates that EEG can reflect the kinematic and dynamic characteristics of limb movement [4]. Decoding hand movement directions from EEG signals is a particularly active area of BCI research [5-8]. For instance, Wang et al. achieved a classification accuracy of 70.29% for six types of movements, including individual and coordinated hand movements, using linear discriminant analysis and support vector machine [7]. Similarly, Zhang et al. proposed a deep learning model combining convolutional neural networks and bidirectional long short-term memory networks, which attained an average classification accuracy of 73.39% for three coordinated directions of hand movements [8].

Traditionally, visual and auditory feedback have been widely used in EEG research to enhance participant interactivity and engagement. Visual feedback often involves the use of visual cues like animations and videos to help participants focus and complete the tasks. Alimardani et al. had shown that visual feedback design can positively enhance the performance of participants in motor imagery tasks [9]. Auditory feedback, on the other hand, employs audio cues to direct participants to complete tasks, which is particularly beneficial for studies targeting visually impaired individuals. Nijboer et al. had demonstrated that auditory feedback-based BCIs can be as effective as visual BCIs [10]. Recently, force feedback has been introduced into EEG studies, providing a novel method to stimulate brain activity [11,12]. This shows promising potential in BCI, with evidence suggesting that force feedback can enhance upper limb rehabilitation in BCI applications [13].

Although extensive research has been conducted on visual and auditory feedback in EEG studies, the exploration of force feedback remains relatively limited. Current research predominantly focuses on cognitive responses to non-contact stimuli, with insufficient attention to how contact feedback



PARTICIPATION CERTIFICATE



The iGEM Foundation certifies that

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特发奖状，以资鼓励！
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指导老师：南方科技大学 张明明， 南方科技大学 陈义峰

证书编号: A20241208

中国生物医学工程学会

二〇二四年七月



Application Number: K473869212

Programme: Master of Science in Robotics

Dear Mr. Jinqiu Zhao,

Congratulations! We are delighted to inform you that you have been selected for admission to the Master of Science in Robotics programme for the term beginning August 2025 on a Full-Time basis.

At NUS, being the leading university in Asia, you will have great opportunities to work with outstanding faculty and you will also gain access to world-class research infrastructure and facilities.