



CSE251

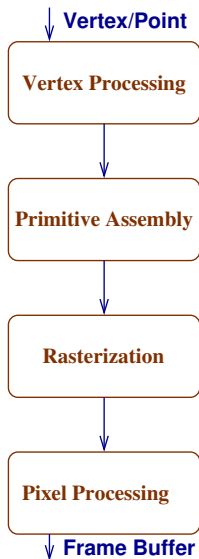
Basics of Computer Graphics

Module: Rasterization Module

Avinash Sharma

Spring 2017

Primitive Pipeline



- ▶ From points, lines, triangles/polygons
- ▶ **Vertex** stage: process vertices independently
- ▶ Primitive stage: triangle assembly
- ▶ Rasterization: Clip & Determine the pixels inside the primitive
- ▶ **Pixel** stage: process each pixel independently

Patterned Line

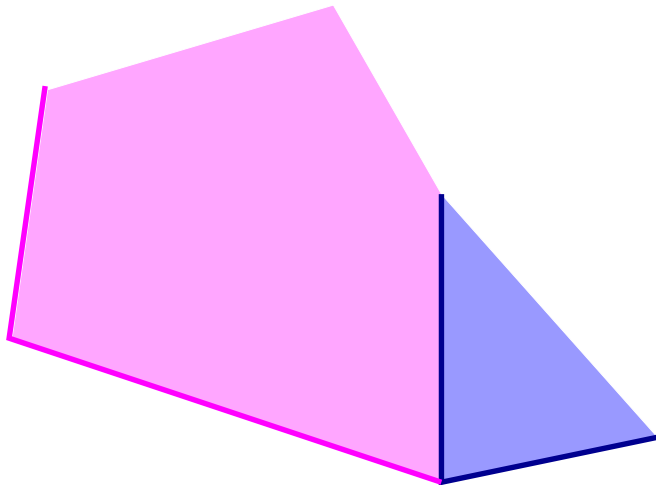
- ▶ Represent the pattern as an array of booleans/bits, say, 16 pixels long.
- ▶ Fill first half with 1 and rest with 0 for dashed lines.
- ▶ Perform WritePixel(x, y) only if pattern bit is a 1.

if (pattern[i]) WritePixel(x, y)

where **i** is an index variable starting with 0 giving the ordinal number (modulo 16) of the pixel from starting point.

Shared Points/Edges

- ▶ It is common to have points common between two lines and edges between two polygons.
- ▶ They will be scan converted **twice**. Not efficient. Sometimes harmful.
- ▶ Solution: Treat the intervals closed on the left and open on the right.
 $[x_m, x_M)$ & $[y_m, y_M)$
- ▶ Thus, edges of polygons on the **top** and **right** boundaries are not drawn.



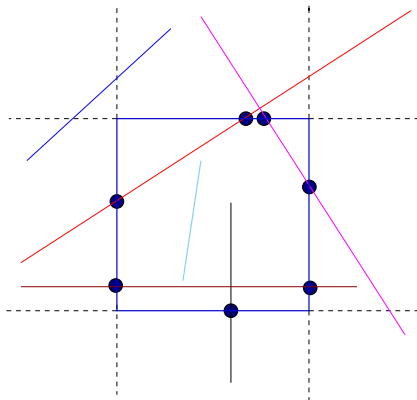
Clipping

- ▶ Often, many points map to outside the range in the normalized 2D space.
- ▶ Think of the FB as an infinite canvas, of which a small rectangular portion is sent to the screen.
- ▶ Let's get greedy: draw only the portion that is visible. That is, **clip** the primitives to a *clip-rectangle*.
- ▶ **Scissoring**: Doing scan-conversion and clipping together.

Clipping Points

- ▶ Clip rectangle: (x_m, y_m) to (x_M, y_M) .
- ▶ For (x, y) : $x_m \leq x \leq x_M, \quad y_m \leq y \leq y_M$
- ▶ Can use this to clip any primitives: Scan convert normally. Check above condition before writing the pixel.
- ▶ Simple, but perhaps we do more work than necessary.
- ▶ Analytically clip to the rectangle, then scan convert.

Clipping Lines

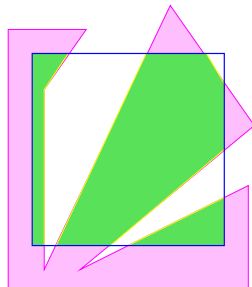
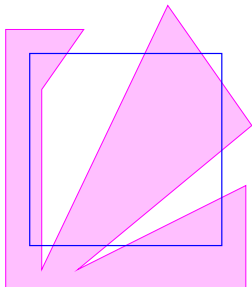


Popular: Cohen-Sutherland Algorithm

Clipping Polygons

- ▶ Restrict drawing/filling of a polygon to the inside of the clip rectangle.
- ▶ A convex polygon remains convex after clipping.
- ▶ A concave polygon can be clipped to multiple polygons.
- ▶ Can perform by intersecting to the four clip edges in turn.

An Example



Popular: Sutherland-Hodgman Algorithm

Filled Rectangles

- ▶ Write to all pixels within the rectangle.

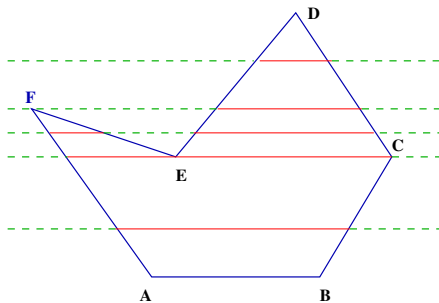
```
Function FilledRectangle ( $x_m, x_M, y_m, y_M$ , colour)
  for  $x_m \leq x \leq x_M$  do
    for  $y_m \leq y \leq y_M$  do
      WritePixel ( $x, y$ , colour)
    EndFunction
  EndFunction
```

- ▶ How about non-upright rectangles? General polygons?

Filled Polygons

- ▶ For each scan line, identify **spans** of the polygon interior. Strictly interior points only.
- ▶ For each scan line, the **parity** determines if we are inside or outside the polygon. Odd is inside, Even is outside.
- ▶ Trick: End-points count towards parity enumeration only if it is a **y_{\min}** point.
- ▶ Span extrema points and other information can be computed during scan conversion. This information is stored in a suitable data structure for the polygon.

Parity Checking



Edge Coherence

- ▶ If scan line y intersects with an edge E , it is likely that $y + 1$ also does. (Unless intersection is the y_{\max} vertex.)
- ▶ When moving from y to $y + 1$, the X -coordinate goes from x to $x + 1/m$.
 $1/m = (x_2 - x_1)/(y_2 - y_1) = \Delta x / \Delta y$
- ▶ Store the integer part of x , the numerator (Δx) and the denominator (Δy) of the fraction separately.
- ▶ For next scan line, add Δx to numerator. If sum goes $> \Delta y$, increment integer portion, subtract Δy from numerator.

Scan Converting Filled Polygons

- ▶ Find intersections of each scan line with polygon edges.
- ▶ Sort them in increasing X -coordinates.
- ▶ Use parity to find interior spans and fill them.
- ▶ Most information can be computed during scan conversion. A list of intersecting polygons stored for each scan line.
- ▶ Use edge coherence for the computation otherwise.

Special Concerns

- ▶ Fill only strictly interior pixels: Fractions rounded up when even parity, rounded down when odd.
- ▶ Intersections at integer pixels: Treat interval closed on left, open on right.
- ▶ Intersections at vertices: Count only y_m vertex for parity.
- ▶ Horizontal edges: Do not count as y_m !

Filled Polygon Scan Conversion

- ▶ Perform all of it together. Each scan line should not be intersected with each polygon edge!
- ▶ Edges are known when polygon vertices are mapped to screen coordinates.
- ▶ Build up an edge table while that is done.
- ▶ Scan conversion is performed in the order of scan lines. Edge coherence can be used; an active edge table can keep track of which edges matter for the current scan line.

Scan Conversion: Summary

- ▶ Filling the frame buffer given 2D primitives.
- ▶ Convert an analytical description of the basic primitives into pixels on an integer grid in the frame buffer.
- ▶ Lines, Polygons, Circles, etc. Filled and unfilled primitives.
- ▶ Efficient algorithms required since scan conversion is done repeatedly. Special hardware used these days
- ▶ 2D Scan Conversion is all, even for 3D graphics.

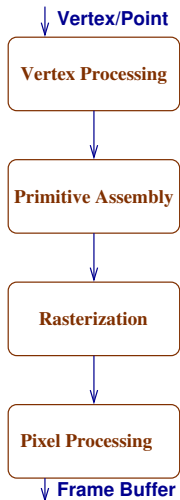
Scan Conversion: Summary

- ▶ High level primitives (point, line, polygon) map to window coordinates using transformations.
- ▶ Creating the display image on the Frame Buffer is important. Needs to be done efficiently.
- ▶ Clipping before filling FB to eliminate futile effort.
- ▶ After clipping, line remains line, polygons can become polygons of greater number of sides, etc.
- ▶ General polygon algorithm for clipping and scan conversion are necessary.

Now you know ...

- ▶ Objects represented/approximated using geometric (1D and 2D) primitives
- ▶ Primitives using (2D/3D) points in a natural coord frame
- ▶ Points transformed to screen coords in a few steps
- ▶ Primitives assembled and converted to pixels on screen
- ▶ Colour at each pixel: physics and interpolation
- ▶ Visibility evaluation to identify which is closer and farther
- ▶ Form image on framebuffer, which appears on the display

Primitive Pipeline



- ▶ **Vertex** stage: transform to screen coords, compute lighting in 3D
- ▶ Primitive assembly: form polygon/triangle/line
- ▶ Rasterization: Clip & Determine pixels inside each primitive
- ▶ **Pixel** stage: give **colour** to each pixel, perform Z-buffering